

Brad Artman

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Spring Review 2005

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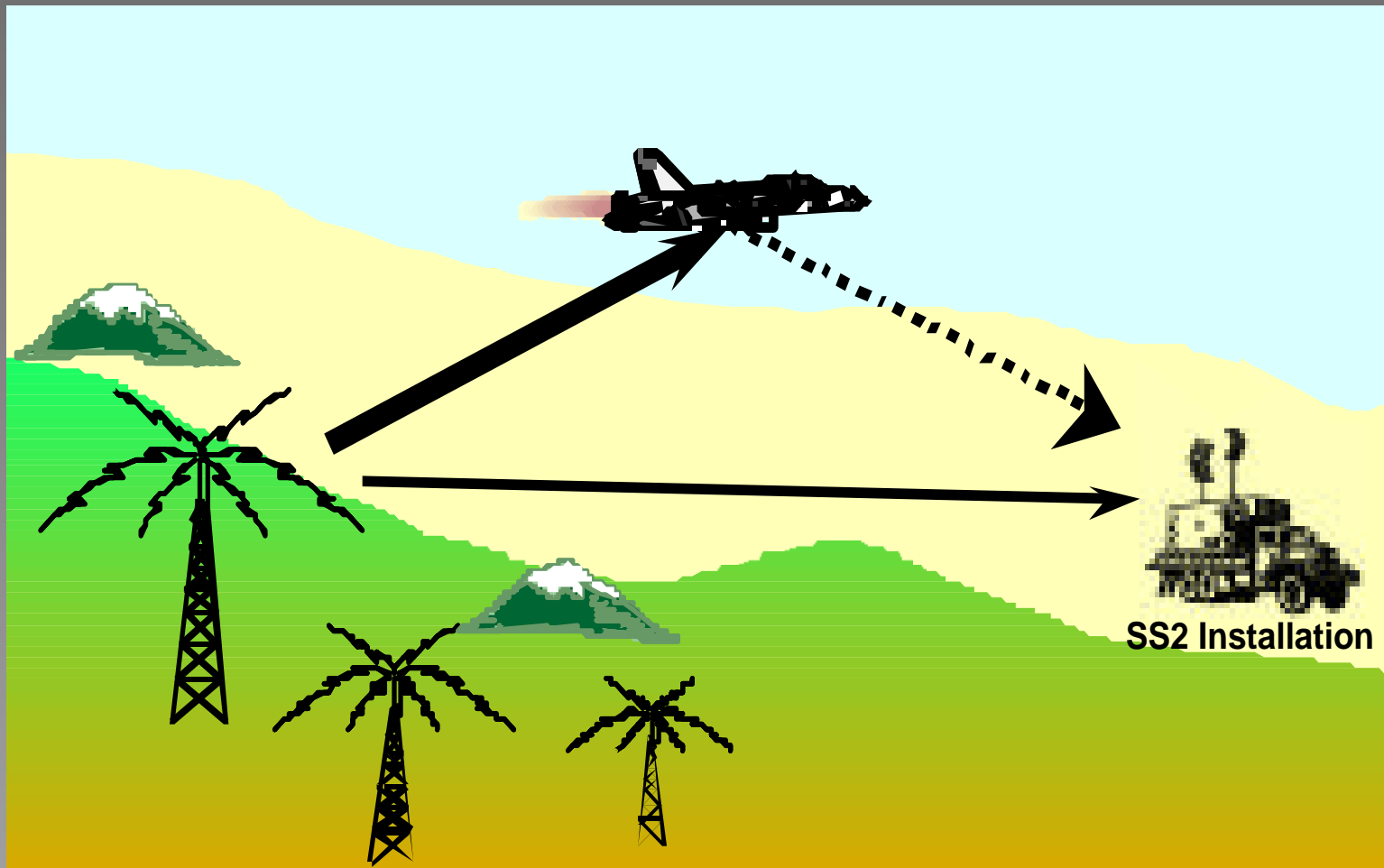
Passive Spy vs. Spy



Passive Spy vs. Spy



Passive Spy vs. Spy



2004

- *Fourier domain imaging condition & migration aliasing*
- Fourier domain time windowing
- Gather convolution
- Forward-scattered angle gathers
- Valhall data
- 100% accurate $\omega - k$ propagator
- Combined Linear/Hyperbolic radon transforms

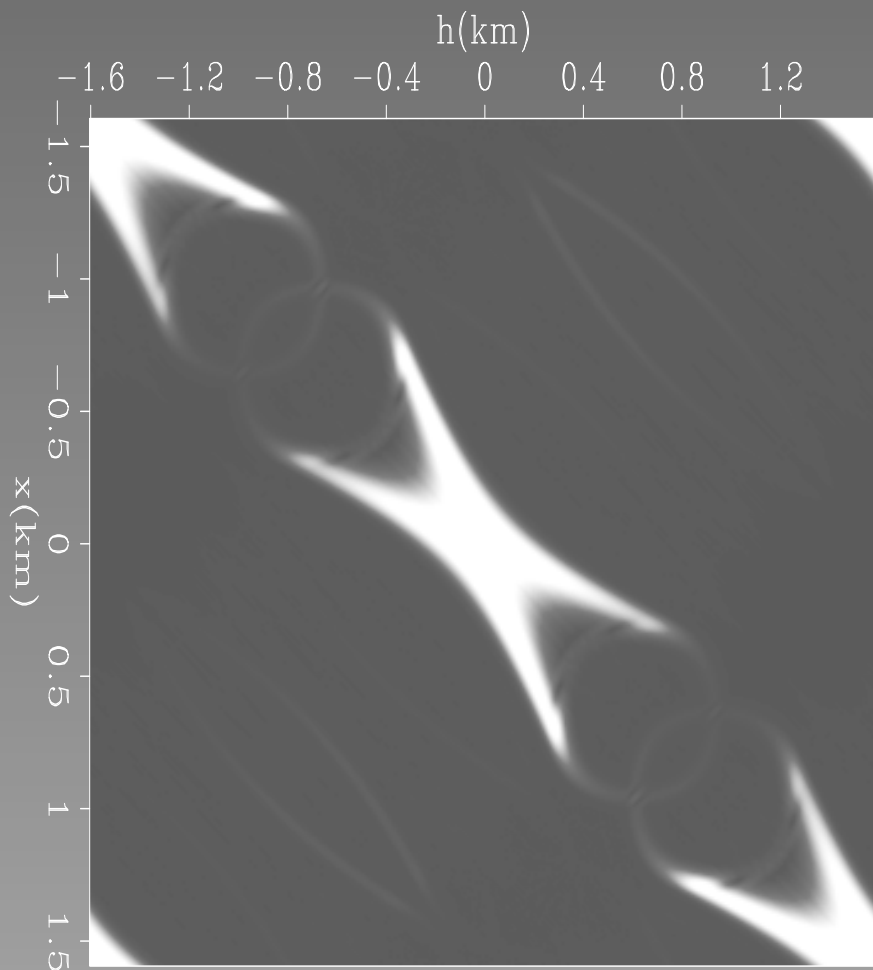
FDIC & aliasing

$$I(x, h)|_{\omega, z} = U(x + h) D^*(x - h)$$

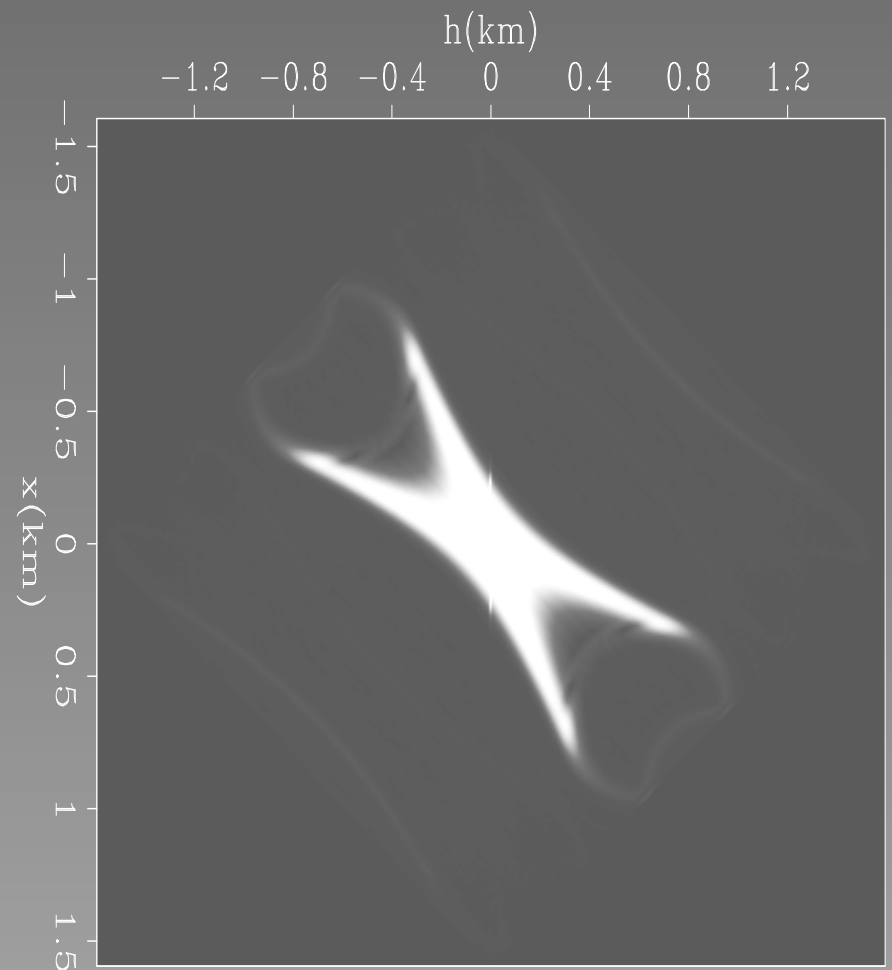
$$\hat{I}(k_x, k_h)|_{\omega, z} = \frac{1}{2} \hat{U} \left(\frac{k_x + k_h}{2} \right) \hat{D}^* \left(\frac{k_x - k_h}{2} \right)$$

derivation

FDIC & aliasing

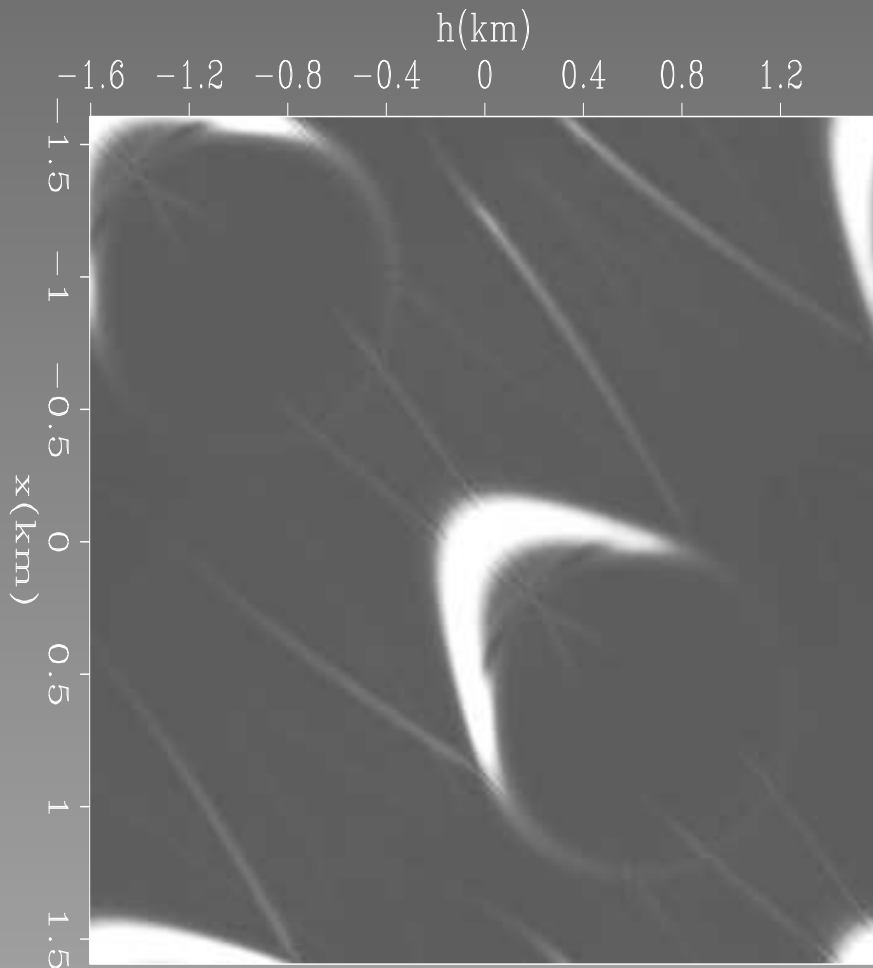


Fourier domain

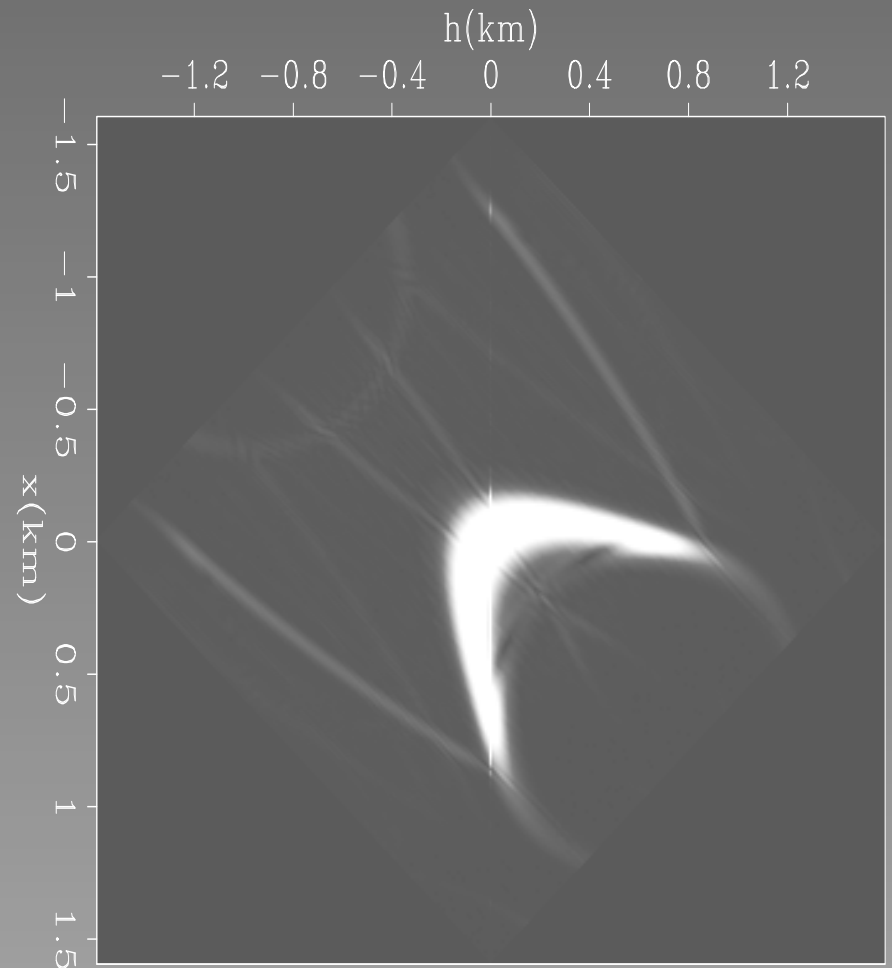


Space domain

FDIC & aliasing

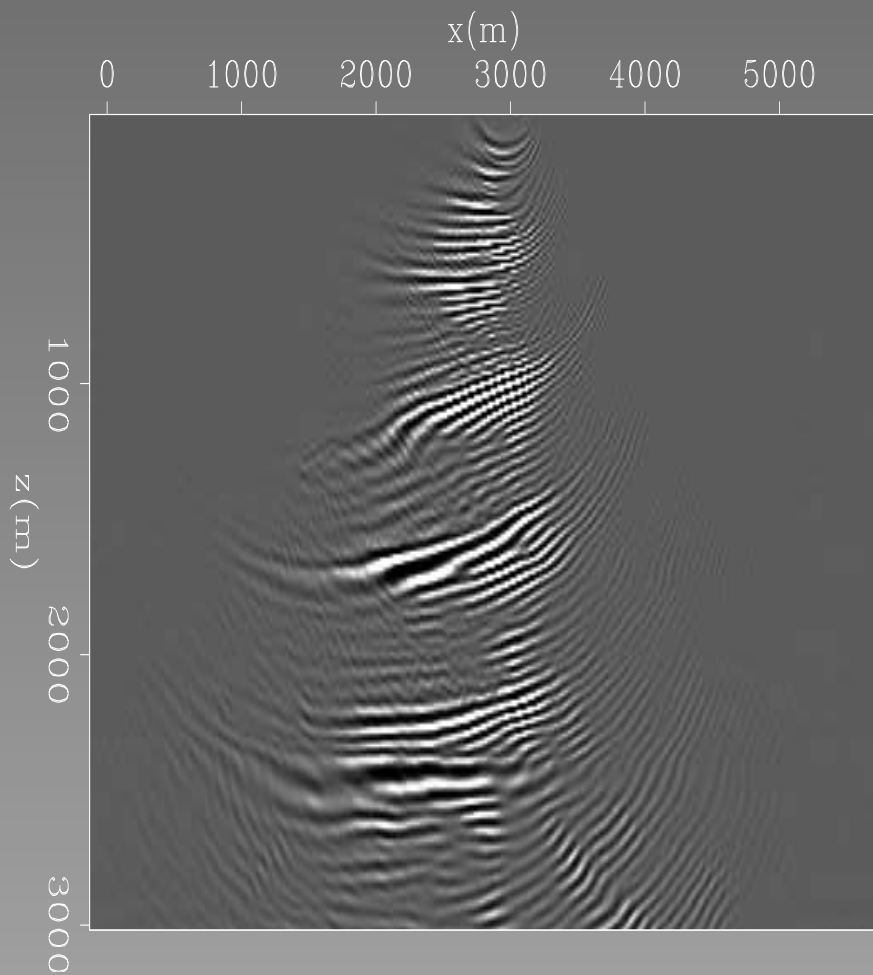


Fourier domain

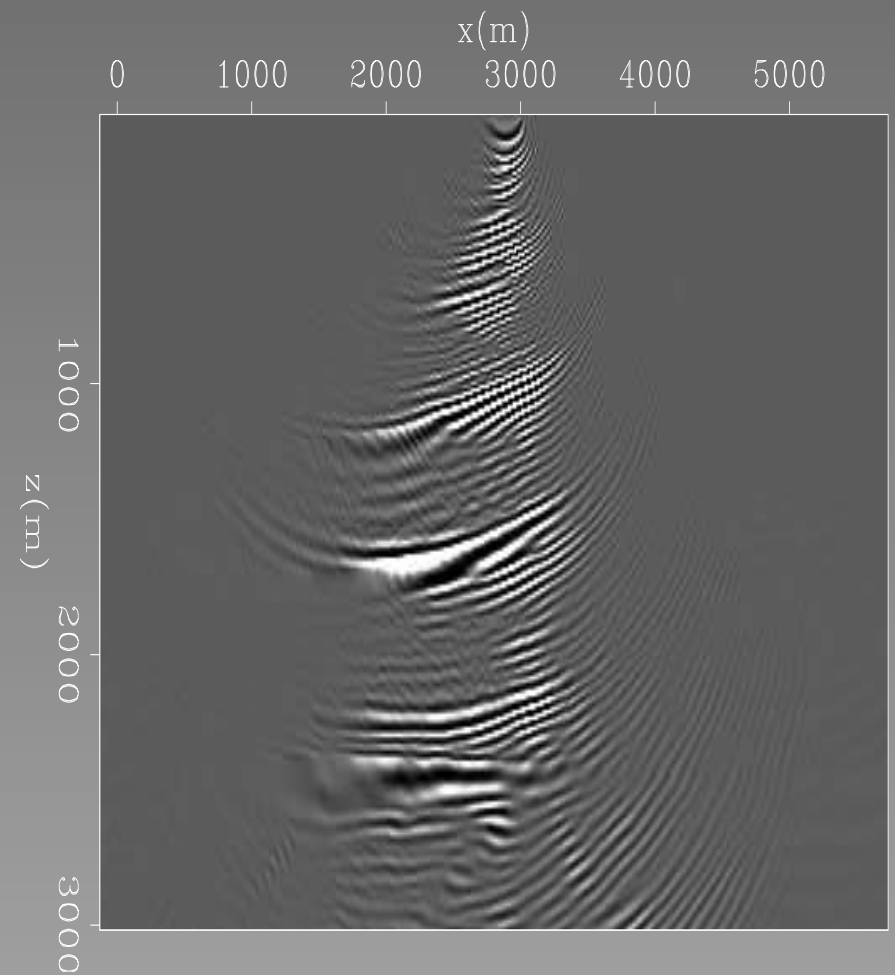


Space domain

FDIC & aliasing

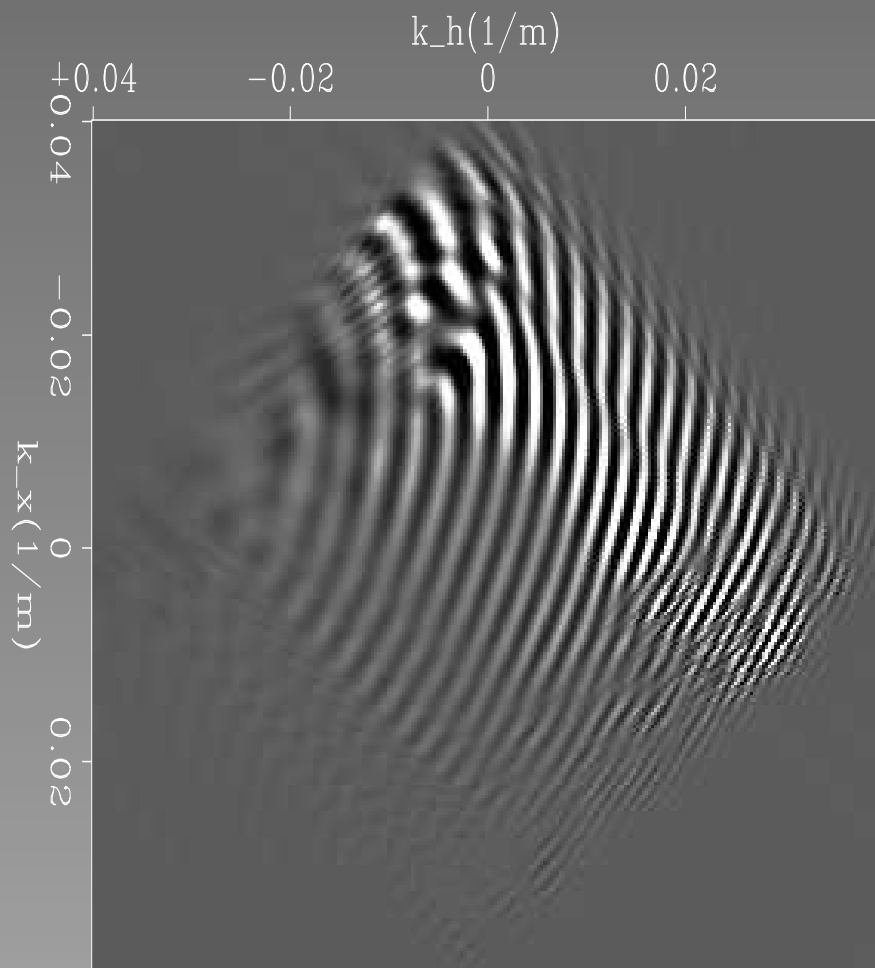


Fourier domain

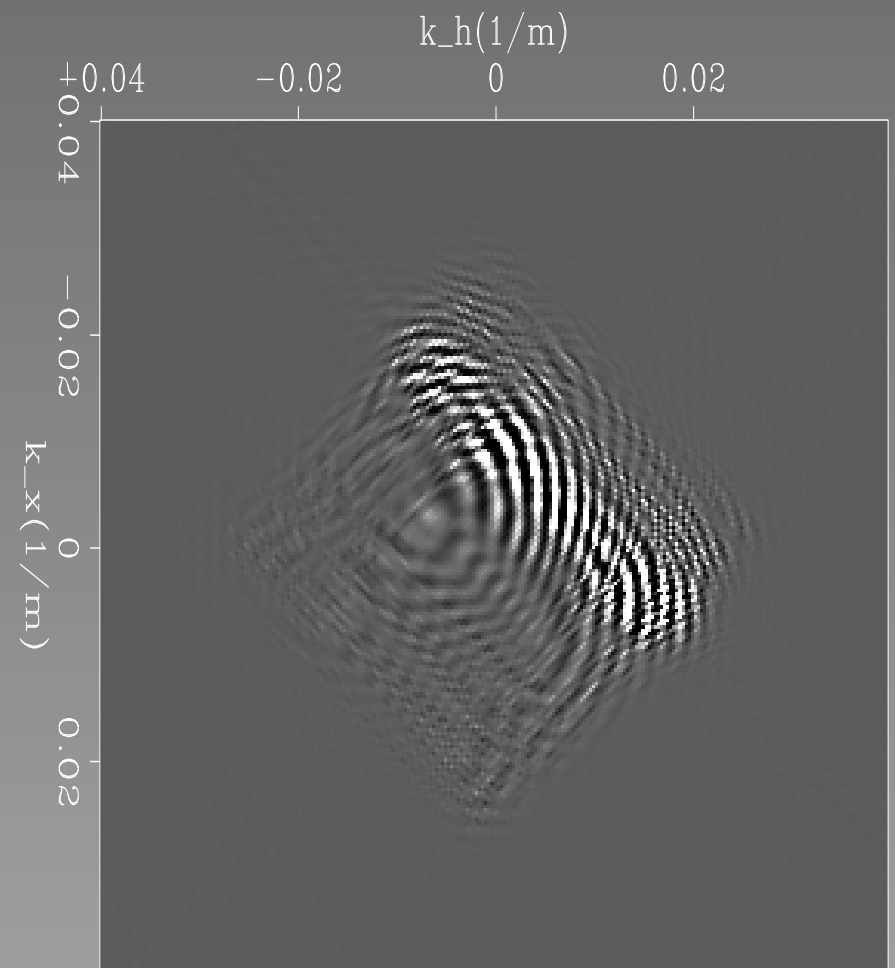


Space domain

FDIC & aliasing

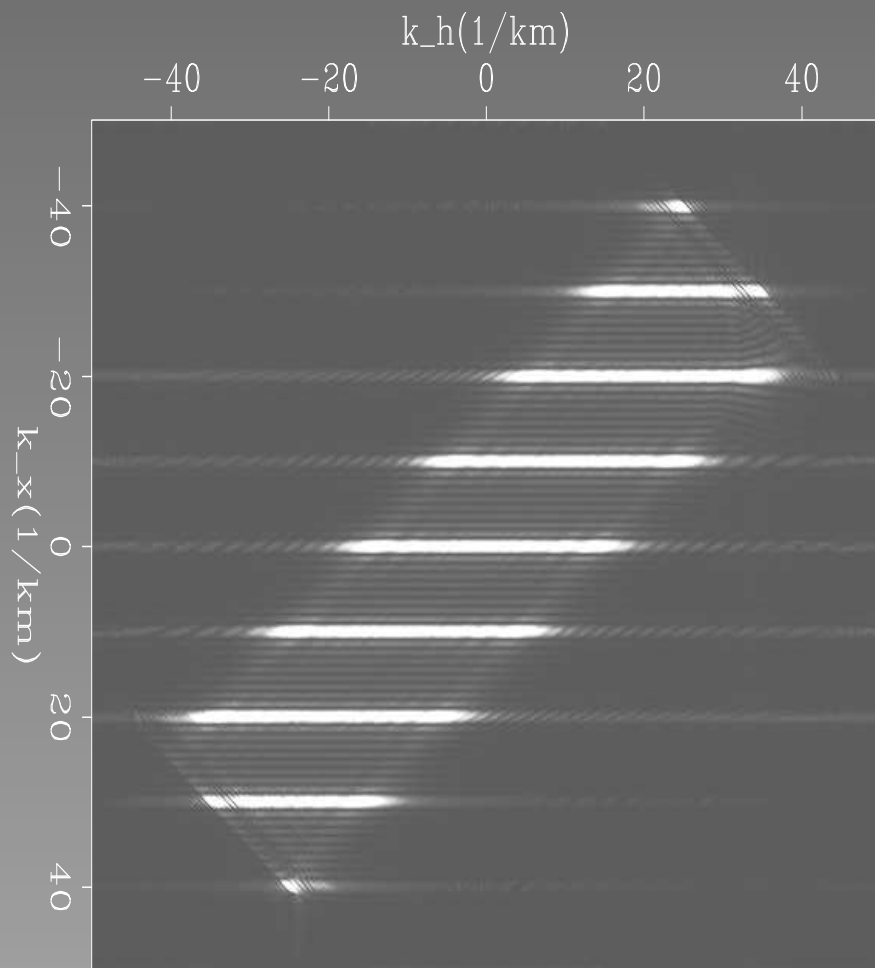


shallow

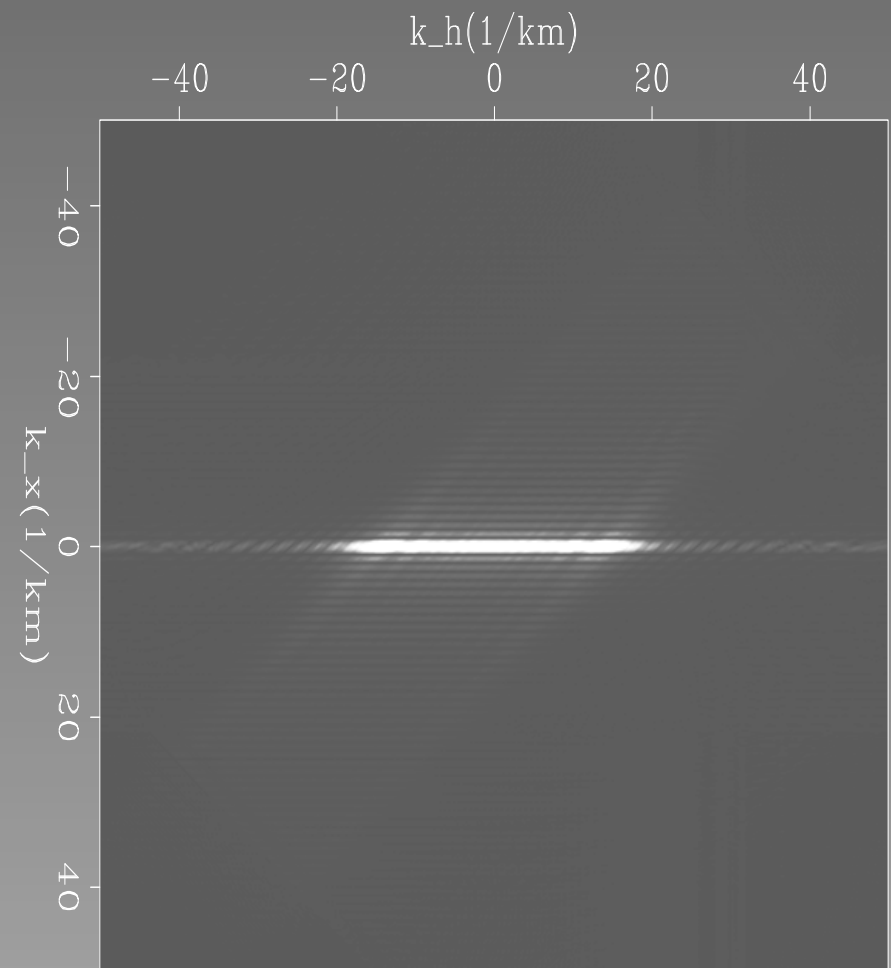


deep

FDIC & aliasing



every 10^{th} shot



all shots

FDIC & aliasing

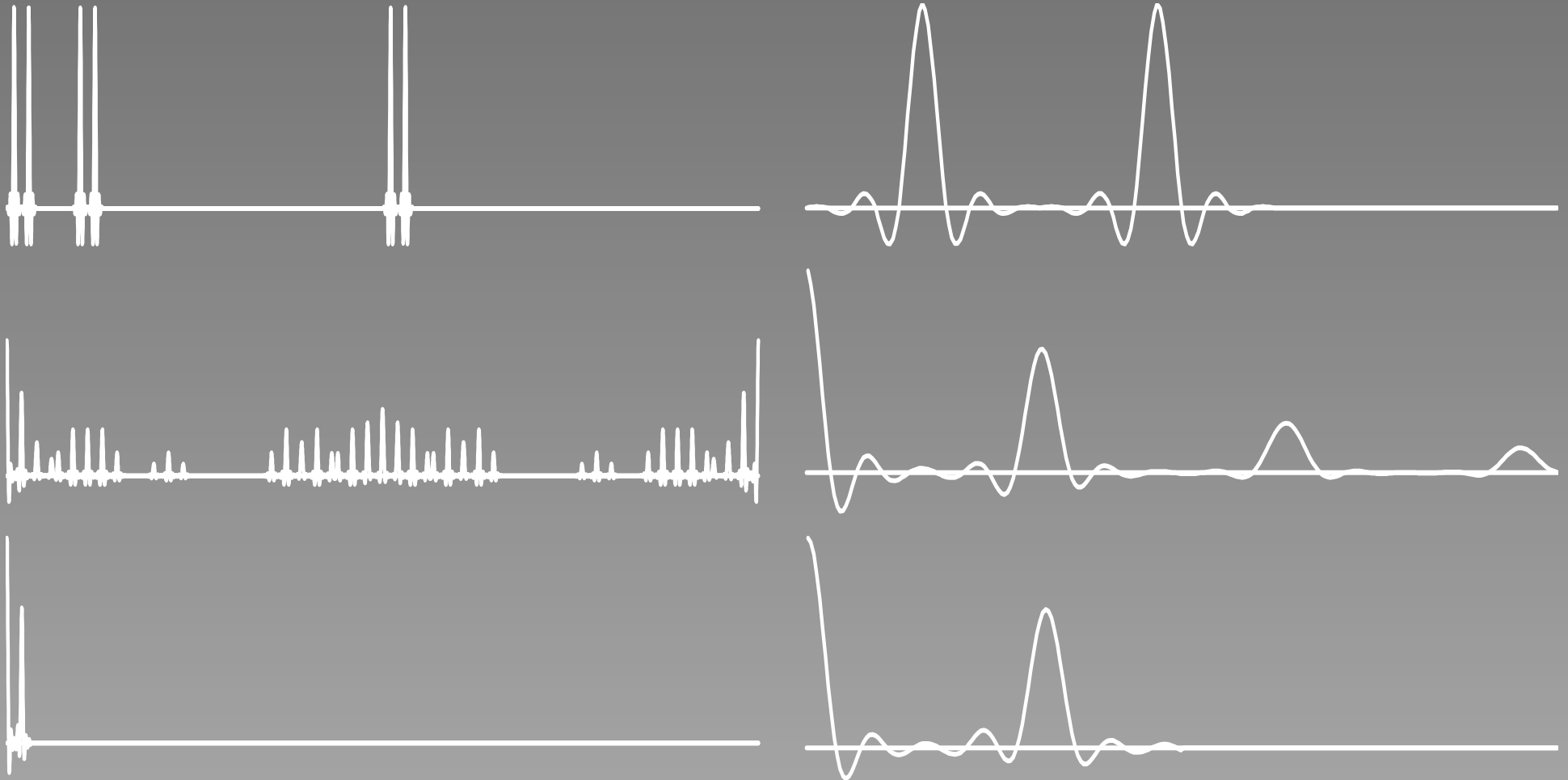
$$\hat{I}(k_x, k_h) = \frac{1}{2} \hat{U} \left(\frac{k_x + k_h}{2} \right) \hat{D}^* \left(\frac{k_x - k_h}{2} \right)$$

		k_h		
		-1	0	1
k_x	-1	$\hat{U}(\frac{-2}{2}) \hat{D}^*(0)$	$\hat{U}(\frac{-1}{2}) \hat{D}^*(\frac{-1}{2})$	$\hat{U}(0) \hat{D}^*(\frac{-2}{2})$
	0	$\hat{U}(\frac{-1}{2}) \hat{D}^*(\frac{1}{2})$	$\hat{U}(0) \hat{D}^*(0)$	$\hat{U}(\frac{1}{2}) \hat{D}^*(\frac{-1}{2})$
	1	$\hat{U}(0) \hat{D}^*(\frac{2}{2})$	$\hat{U}(\frac{1}{2}) \hat{D}^*(\frac{1}{2})$	$\hat{U}(\frac{2}{2}) \hat{D}^*(0)$
	2	$\hat{U}(\frac{1}{2}) \hat{D}^*(\frac{3}{2})$	$\hat{U}(\frac{2}{2}) \hat{D}^*(\frac{2}{2})$	$\hat{U}(\frac{3}{2}) \hat{D}^*(\frac{1}{2})$

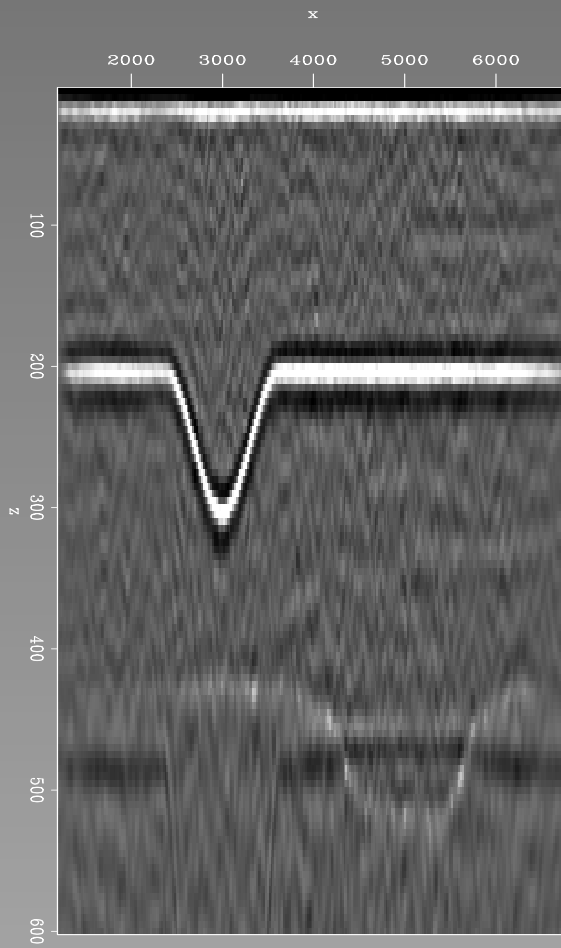
2004

- Fourier domain imaging condition & migration aliasing
- *Fourier domain time windowing*
- Gather convolution
- Forward-scattered angle gathers
- Valhall data

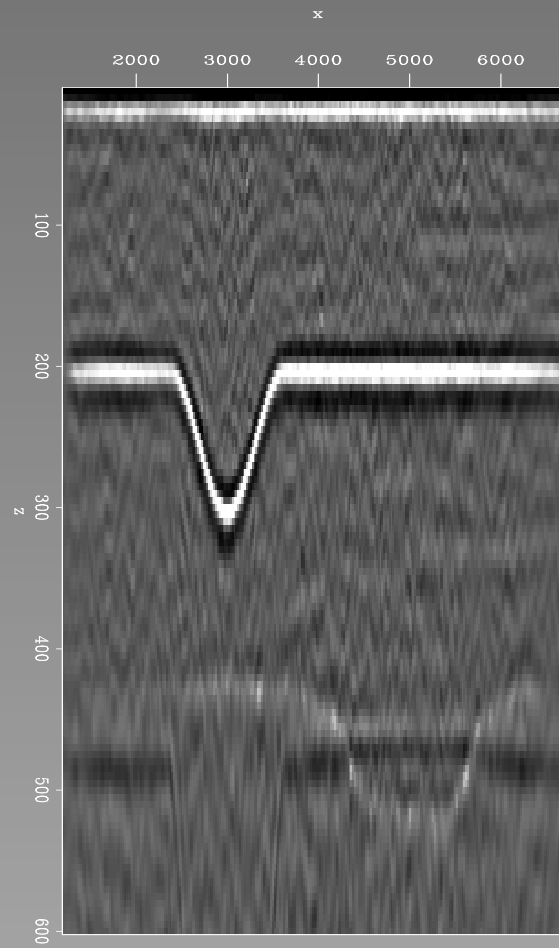
Fourier domain time windowing



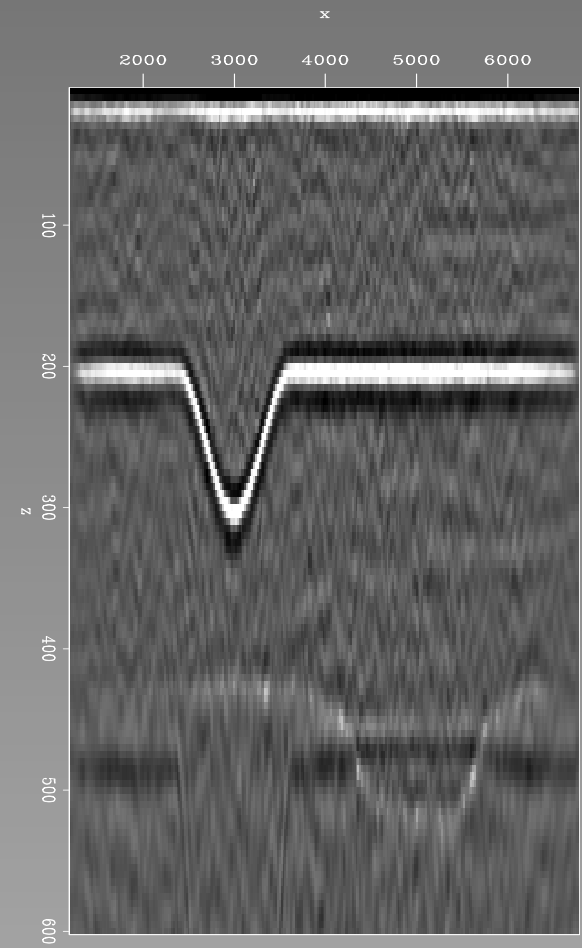
Fourier domain time windowing



(a)



(b)

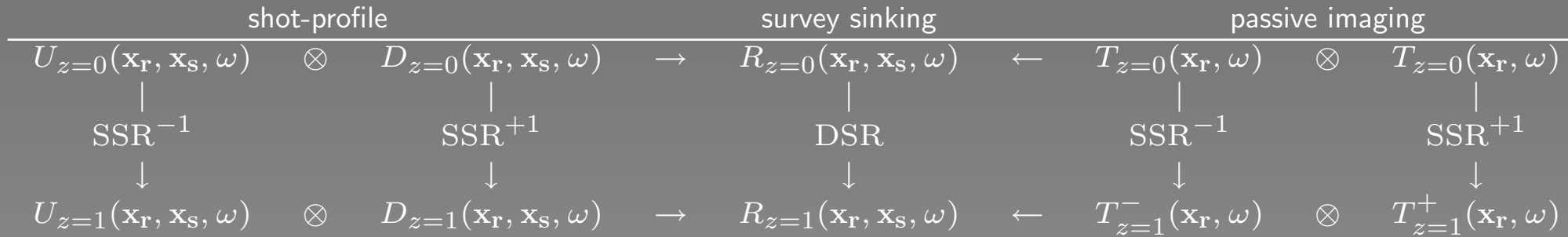


(c)

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Gather correlation



Gather correlation

Shot-profile=Source-receiver migration

$$\begin{aligned} R_{z+1} &= \text{DSR } R_z = \text{DSR } U_z D_z^* = & (1) \\ &= \text{SSR } U_z \text{SSR } D_z^* = \\ &= \text{SSR } U_z (\text{SSR}^{-1} D_z)^* = U_{z+1} D_{z+1}^* . \end{aligned}$$

Gather convolution

Image space SRME:

$$\begin{aligned} M_{z+1} &= \text{DSR } M_z = \text{DSR } U_z U_z^* = & (2) \\ &= \text{SSR } U_z \text{SSR } U_z^* = \\ &= \text{SSR } U_z (\text{SSR}^{-1} U_z)^* = U_{z+1} U_{z+1}^* . \end{aligned}$$

Migration

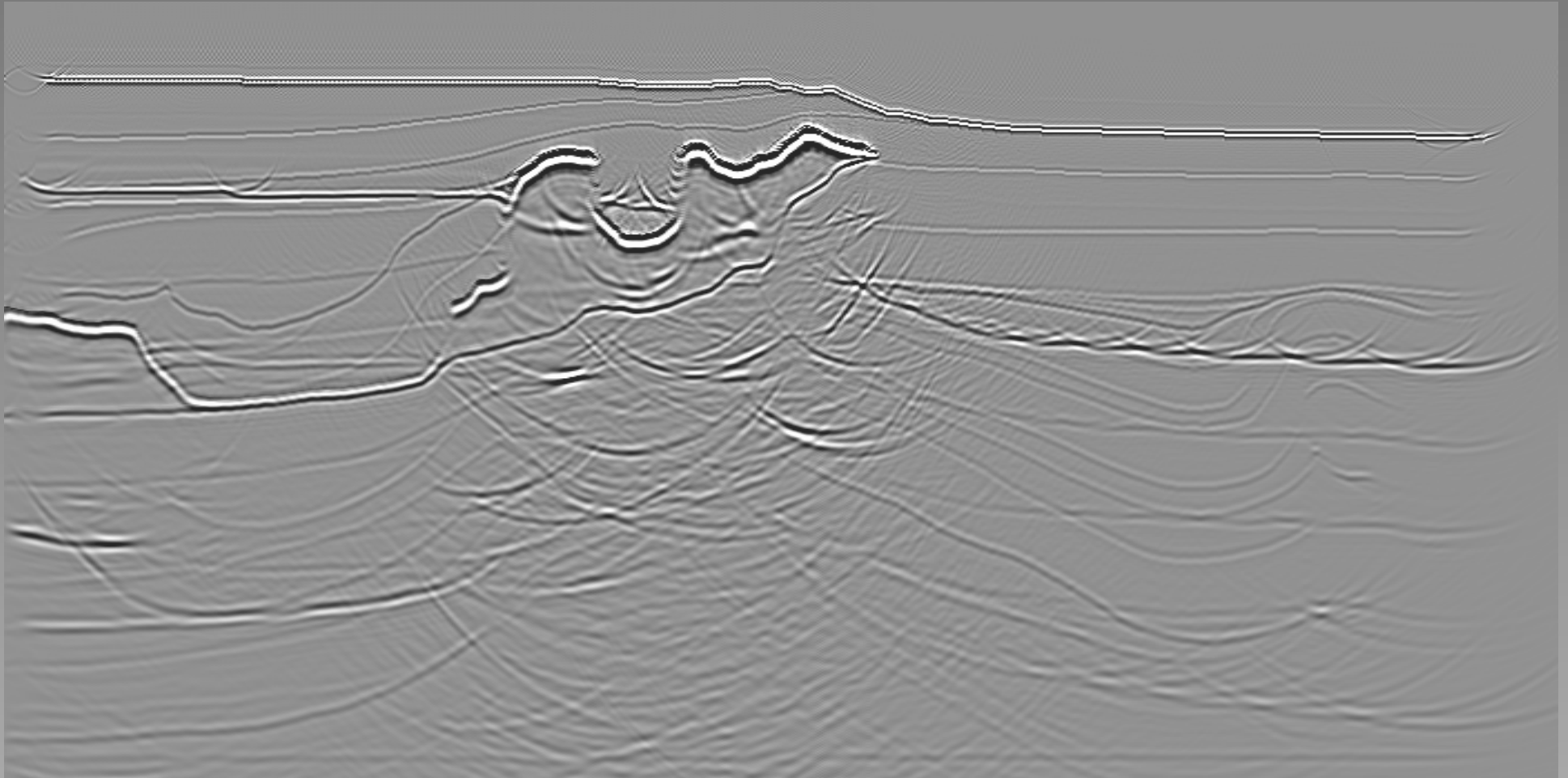
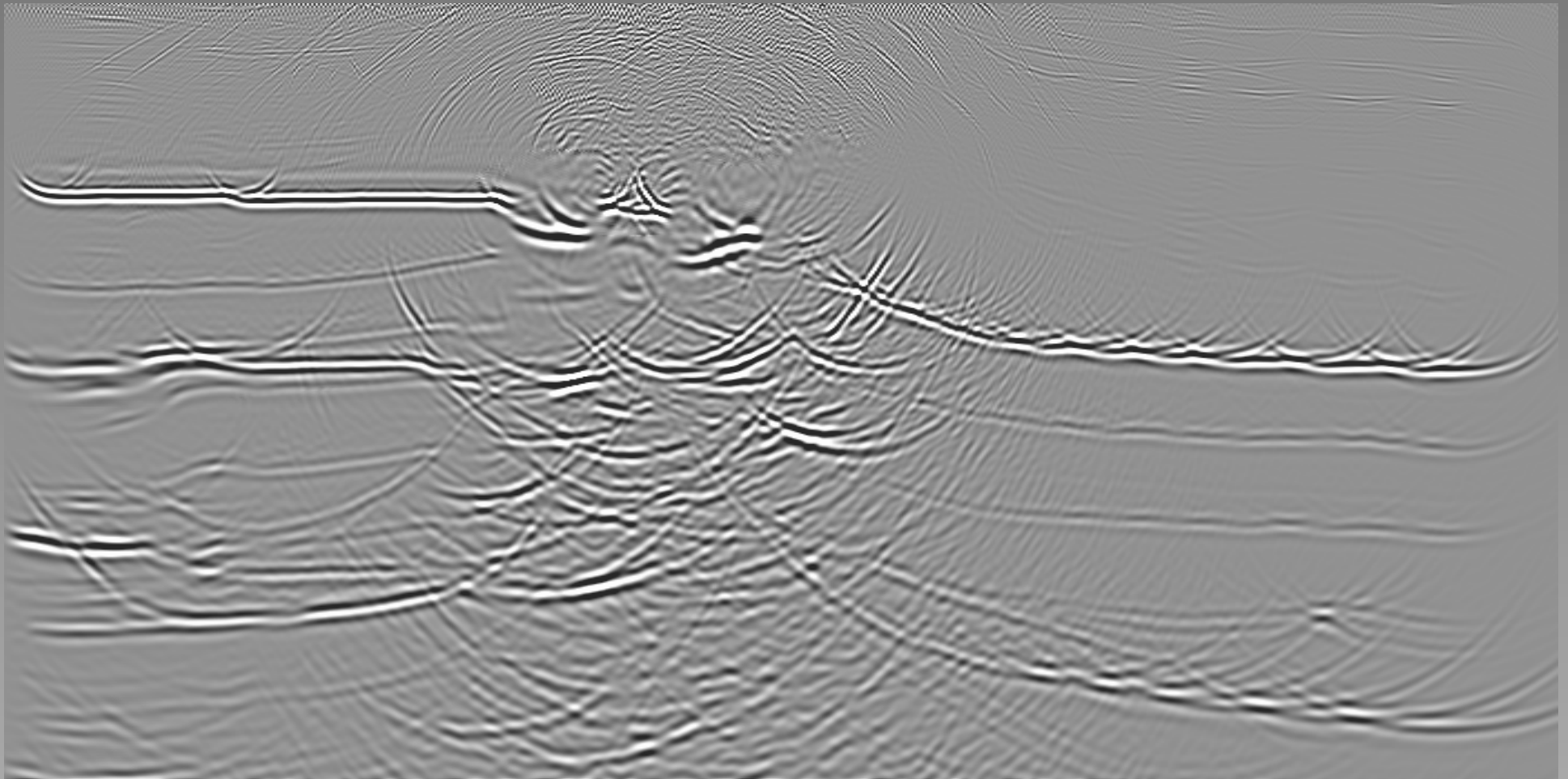
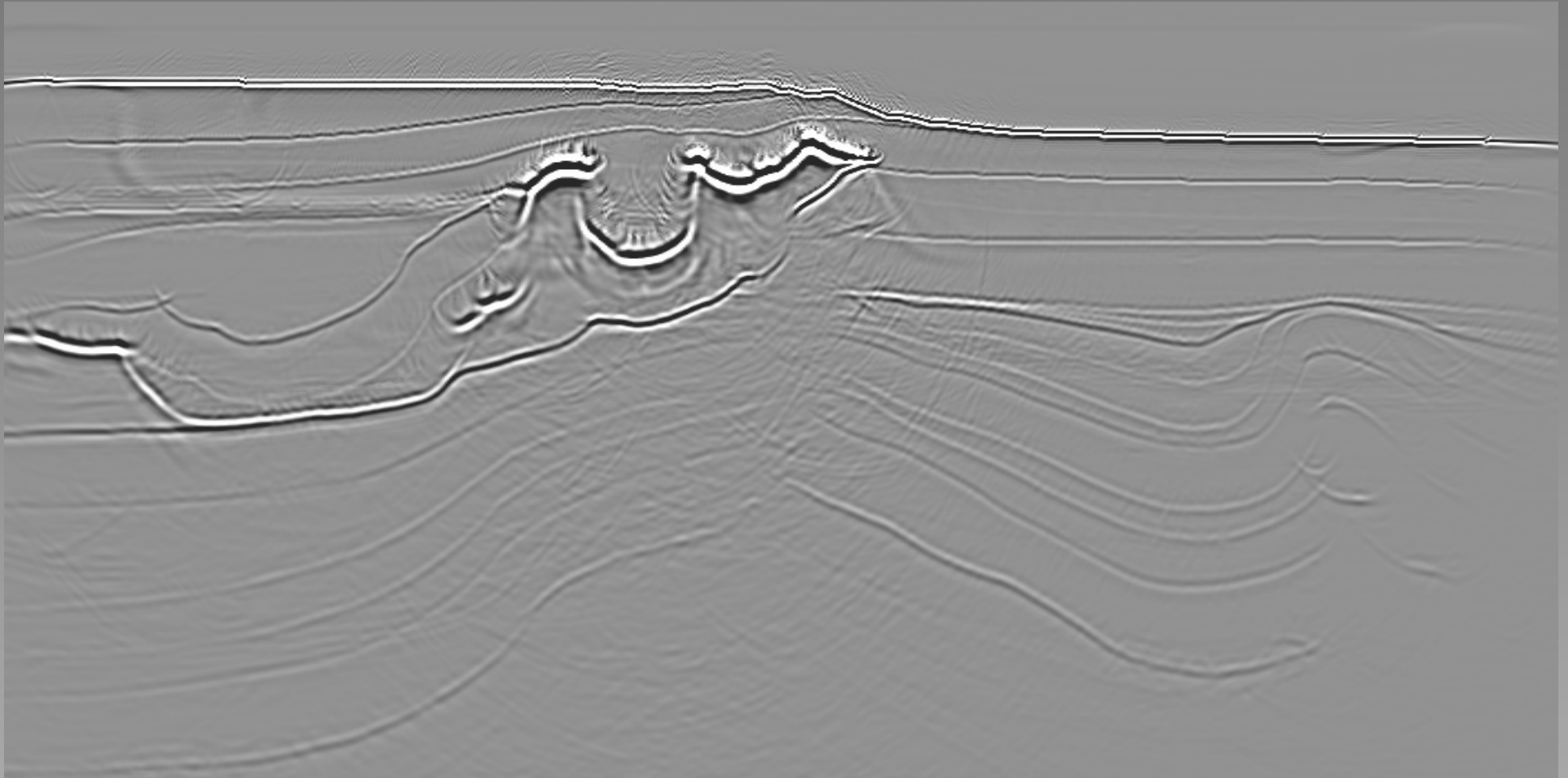


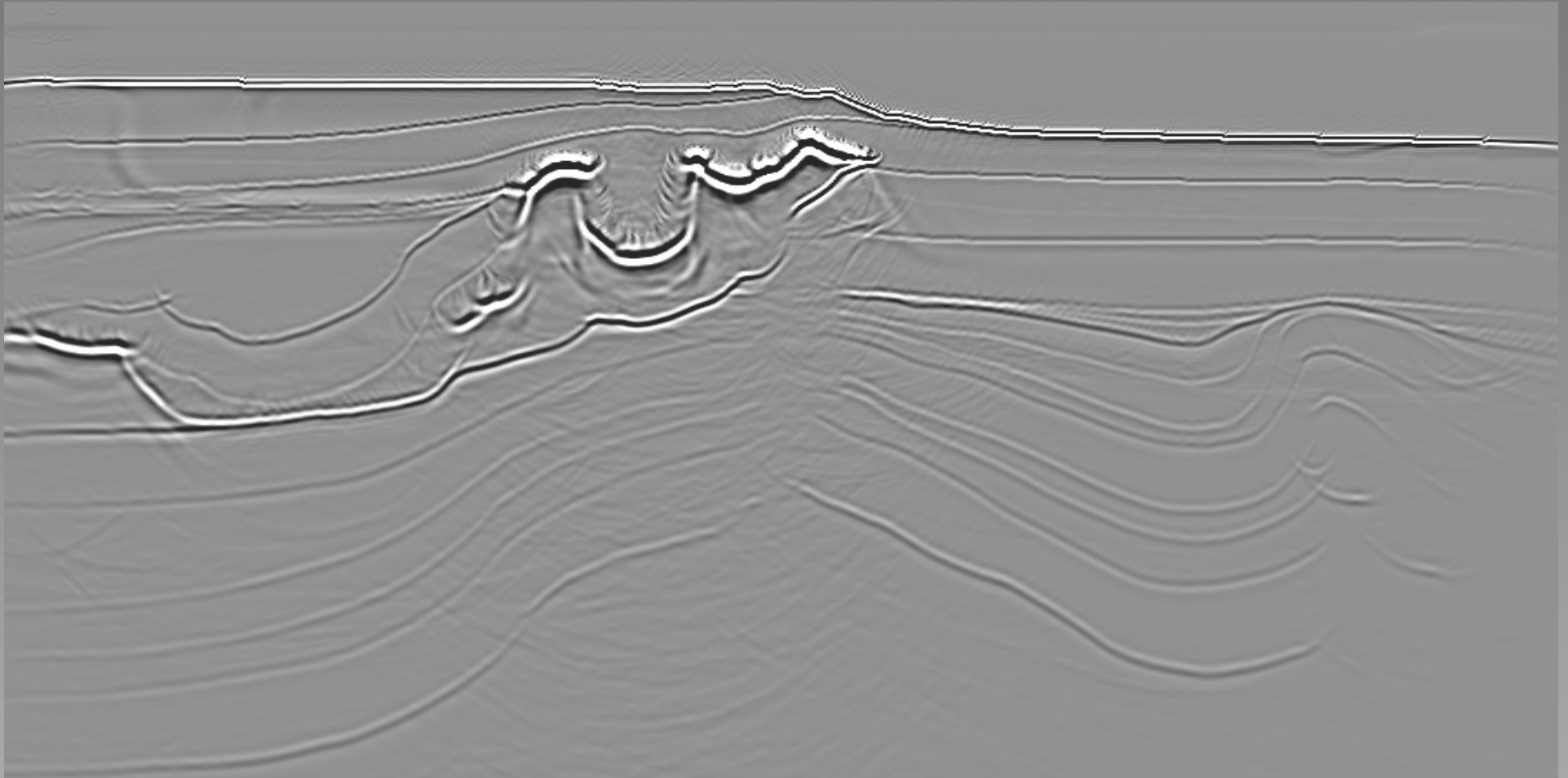
Image-space multiple model



Migration, subtraction



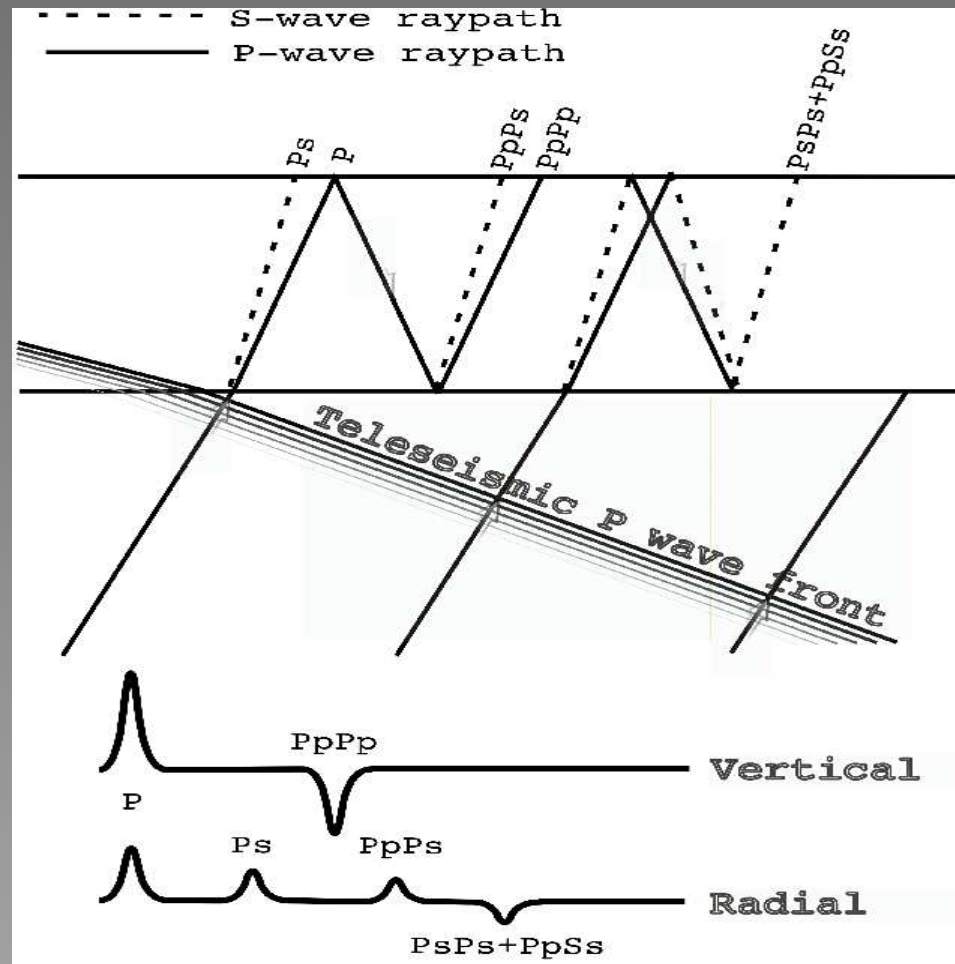
Subtraction, migration



2004

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Forward-scattered angle gathers



Forward-scattered angle gathers

$$x (p_r + p_s) + z (q_r + q_s) - h_x (p_r - p_s) - h_z (q_r - q_s) = 0,$$

$$\frac{\partial z}{\partial h_x} = -\tan \gamma \quad \text{and} \quad \frac{\partial z}{\partial x} = -\tan \alpha.$$

$$x (p_r - p_s) + z (q_r - q_s) - h_x (p_r + p_s) - h_z (q_r + q_s) = 0,$$

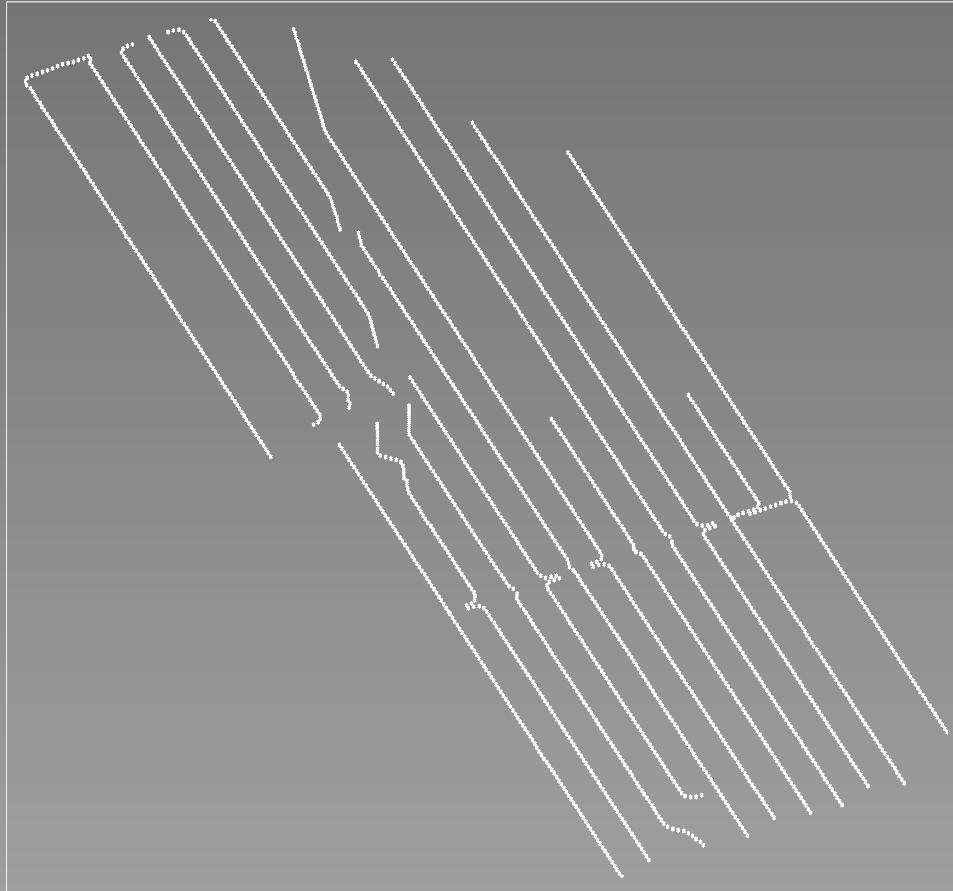
$$\frac{\partial z}{\partial h_x} = -\cot \gamma_a \quad \text{and} \quad \frac{\partial z}{\partial x} = -\cot \alpha_a.$$

2004

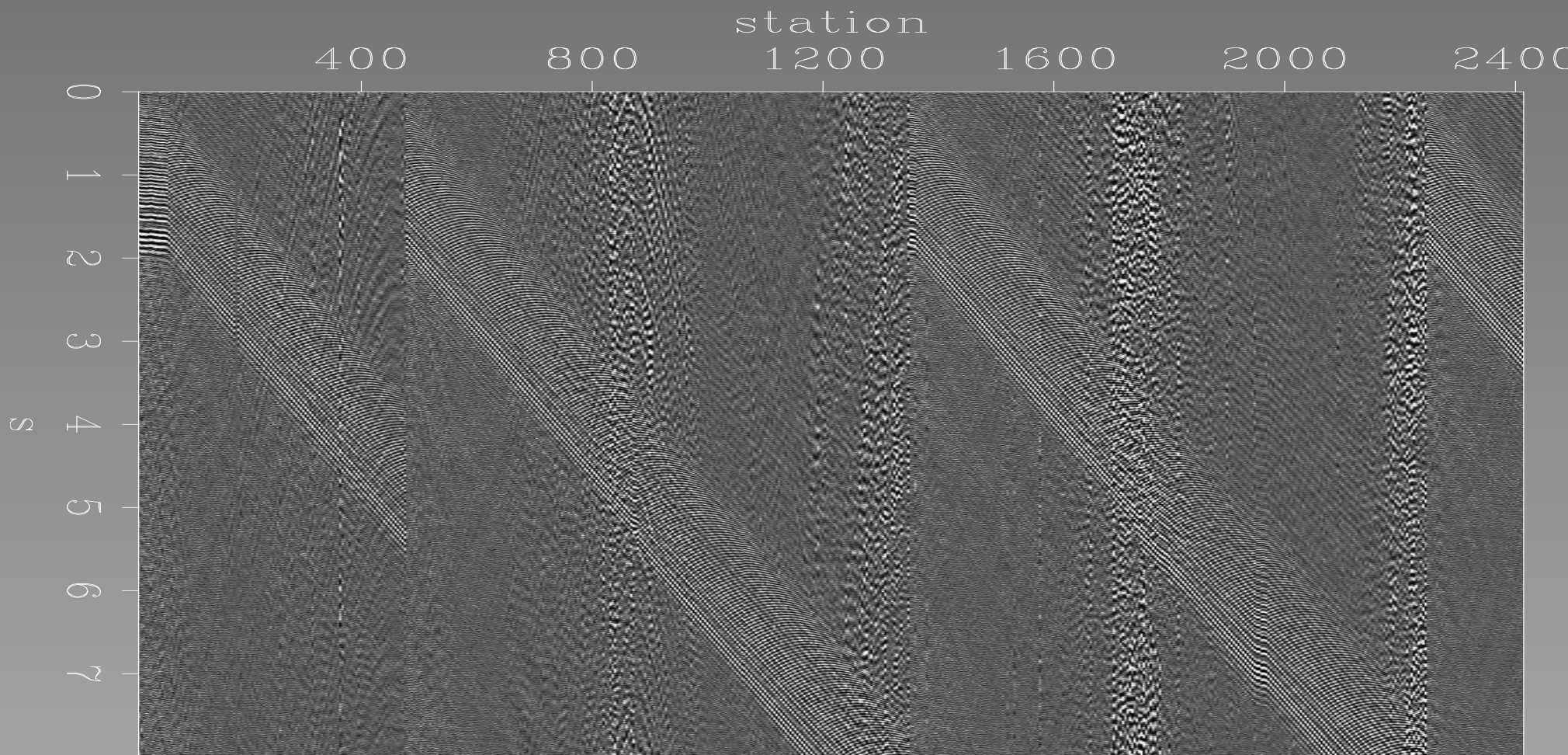
- Fourier domain imaging condition & migration aliasing
- Fourier domain time windowing
- Gather convolution
- Forward-scattered angle gathers
- *Valhall data*

Valhall

receivers



Valhall



2005a

- Valhall passive data
- Plan-wave decomposition & spectral analysis
- migrate P,Z, & S components
 - ★ Back-scattered
 - ★ Forward-scattered
- P-Z summation as $U D$ separation vs. correlation
- Compare to “best-case” image
- Search for earth tremor

2005b

- Finish aliasing paper
- Finish image-space multiple modeling paper
- Direct migration of Long Beach VSP data
- Submit multi-offset GPR migration paper

Thanks



contents

2004

- Fourier domain imaging condition & migration aliasing
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- Valhall data

Derivation 1

$$I(x, h)|_{\omega, z} = U(x_r - h)D(x_s + h) \quad (1)$$

Fourier transform D to \hat{D}

$$\hat{I}(x, h) = U(x - h) \int \hat{D}(k_s) e^{ik_s(x+h)} dk_s \quad (2)$$

FT all the x 's

$$\hat{I}(k_x, h) = \int U(x - h) \int \hat{D}(k_s) e^{ik_s(x+h)} dk_s e^{-ixk_x} dx \quad (3)$$

Derivation 2

Introduce (Sergey inspired) variable flip-flop/reorder

$$\begin{aligned}\hat{I}(k_x, h) &= \int \hat{D}(k_s) e^{ik_s h} \int U(x - h) e^{-ix(k_x - k_s)} dx dk_s \\ \hat{I}(k_x, h) &= \int \hat{D}(k_s) e^{ih(2k_s - k_x)} \\ &\quad \int U(x - h) e^{-i(x-h)(k_x - k_s)} d(x - h) dk_s \quad (4)\end{aligned}$$

Note salient details: Inner integral is FT of U,

$$\hat{I}(k_x, h) = \int \hat{U}(k_x - k_s) \hat{D}(k_s) e^{ih(2k_s - k_x)} dk_s \quad (5)$$

Derivation 3

knowing $k_h = 2k_s - k_x$,

$$\hat{I}(k_x, h) = \frac{1}{2} \int \hat{U}\left(\frac{k_x - k_h}{2}\right) \hat{D}\left(\frac{k_x + k_h}{2}\right) e^{-ihk_h} dk_h \quad (6)$$

This we see is FT over offset, so the complete FT of the IC is

$$\hat{I}(k_x, k_h) = \frac{1}{2} \hat{U}\left(\frac{k_x - k_h}{2}\right) \hat{D}\left(\frac{k_x + k_h}{2}\right). \quad (7)$$

return