

Fourier-domain imaging condition for shot-profile migration

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SEP120 pages 325-331

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Goals

- The Fourier-domain imaging condition
- It works ...
- ...but not well
- Why not
- What it teaches us
- Operator aliasing post-migration

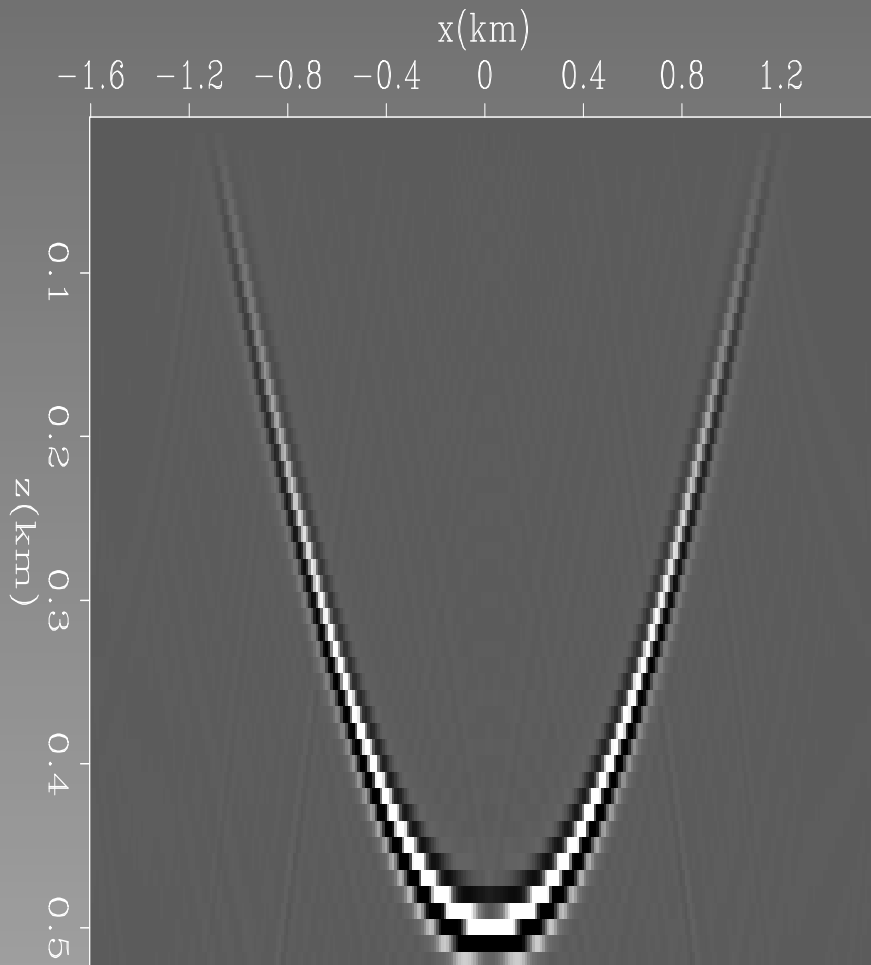
FDIC & aliasing

$$I(x, h)|_{\omega, z} = U(x + h) D^*(x - h)$$

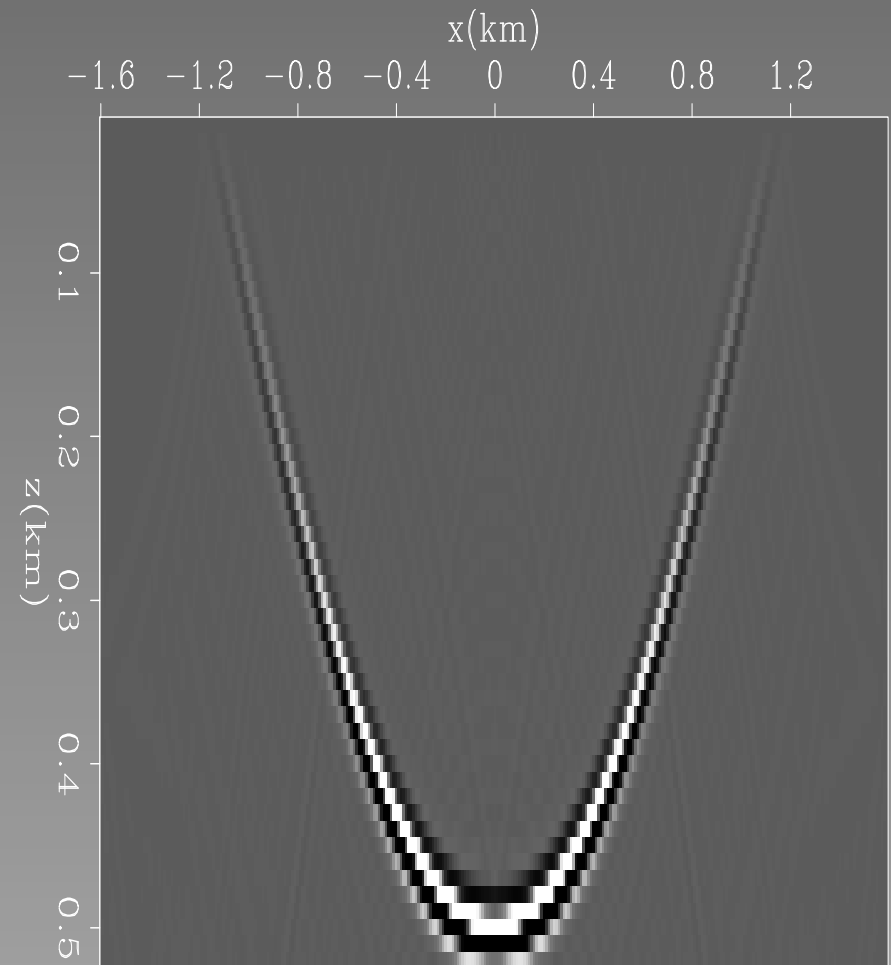
$$\hat{I}(k_x, k_h)|_{\omega, z} = \frac{1}{2} \hat{U} \left(\frac{k_x + k_h}{2} \right) \hat{D}^* \left(\frac{k_x - k_h}{2} \right)$$

derivation

$x - z$ impulse response

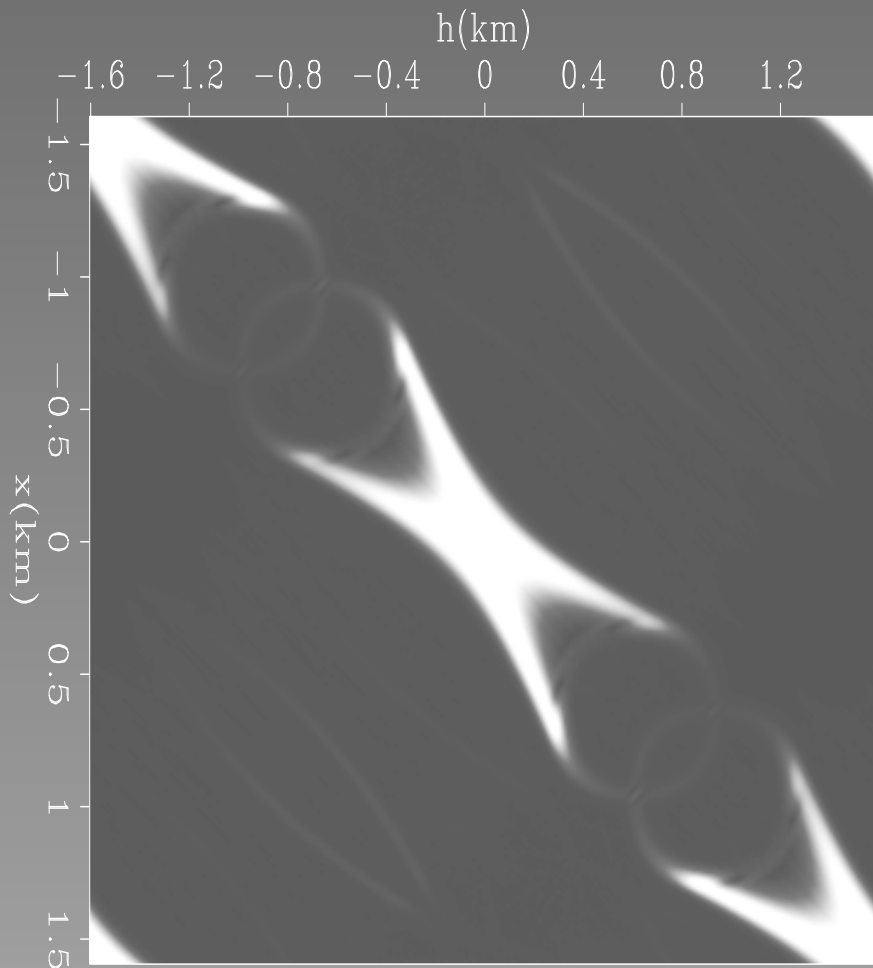


Fourier domain

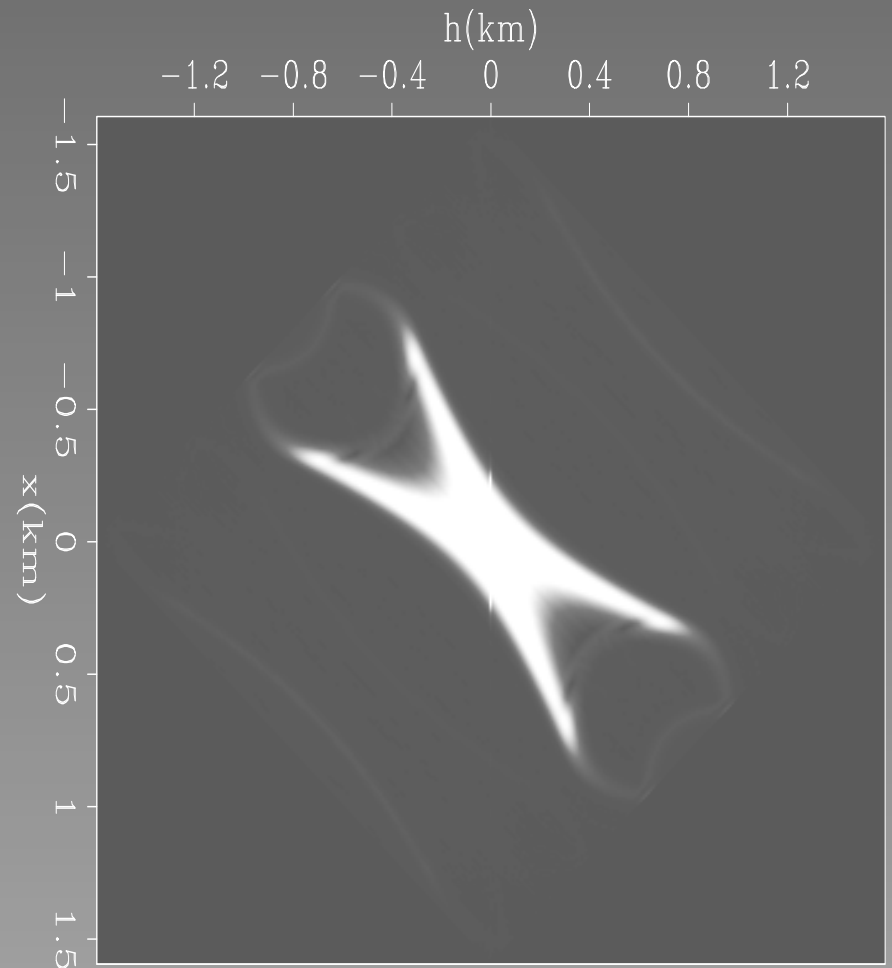


Space domain

$x - h$ impulse response

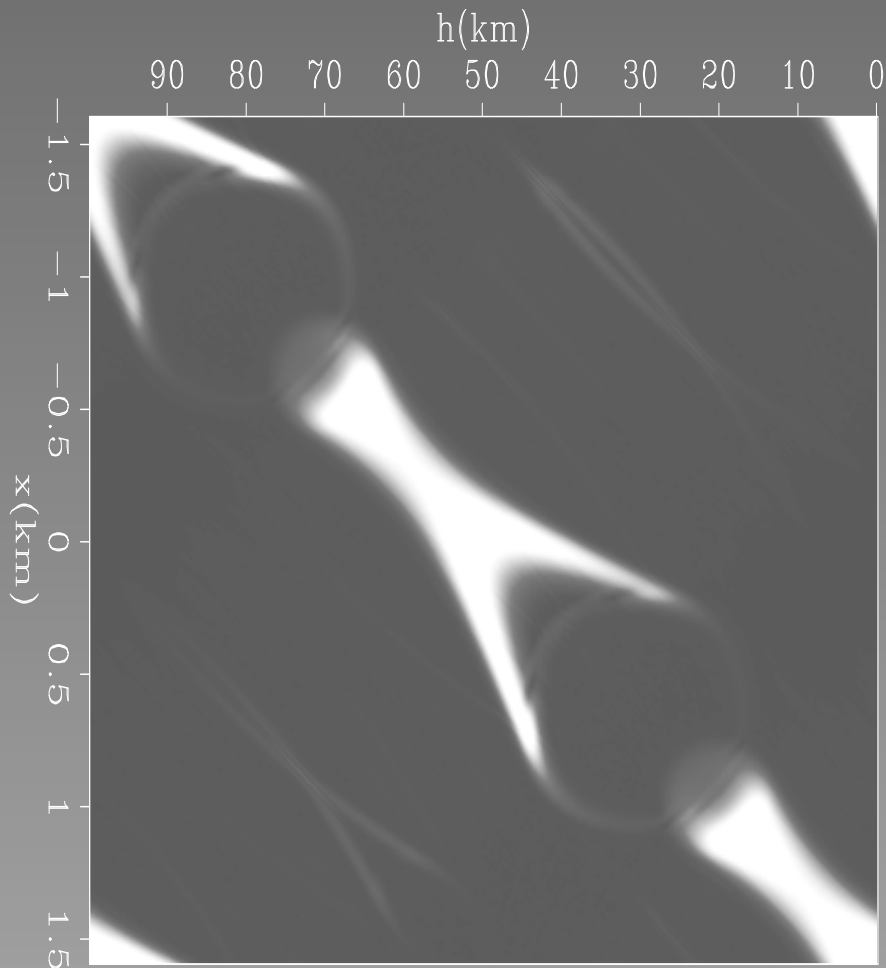


Fourier domain

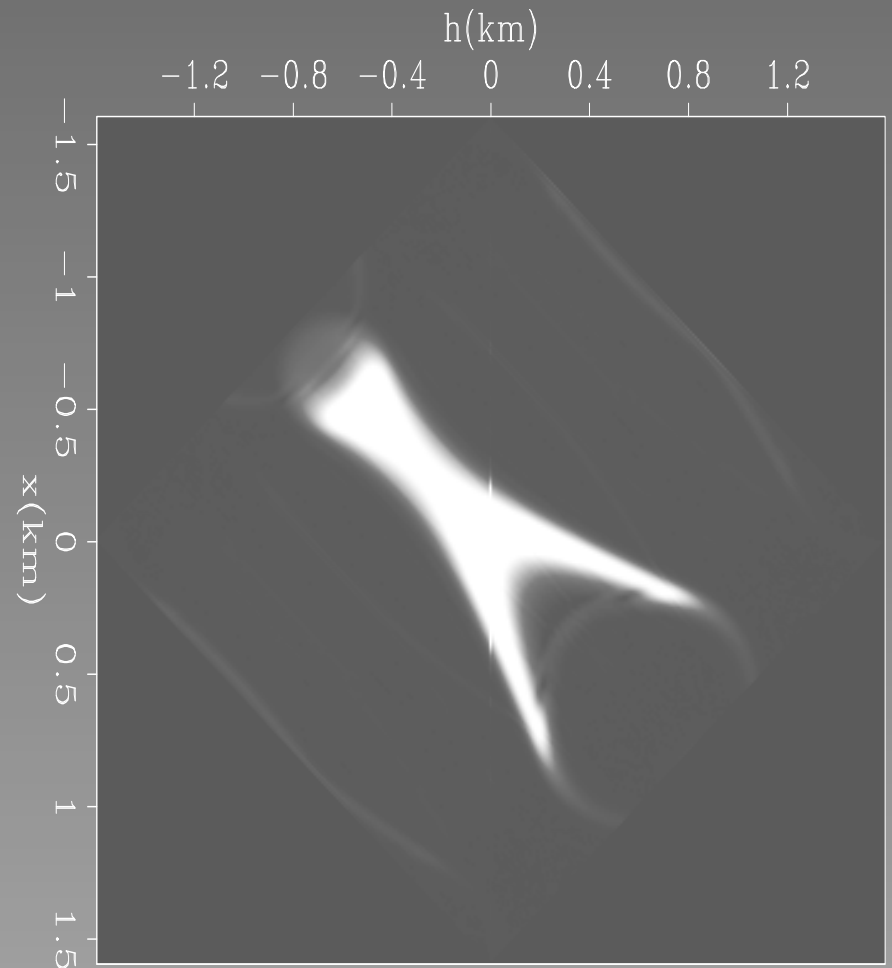


Space domain

$x - h$ impulse response

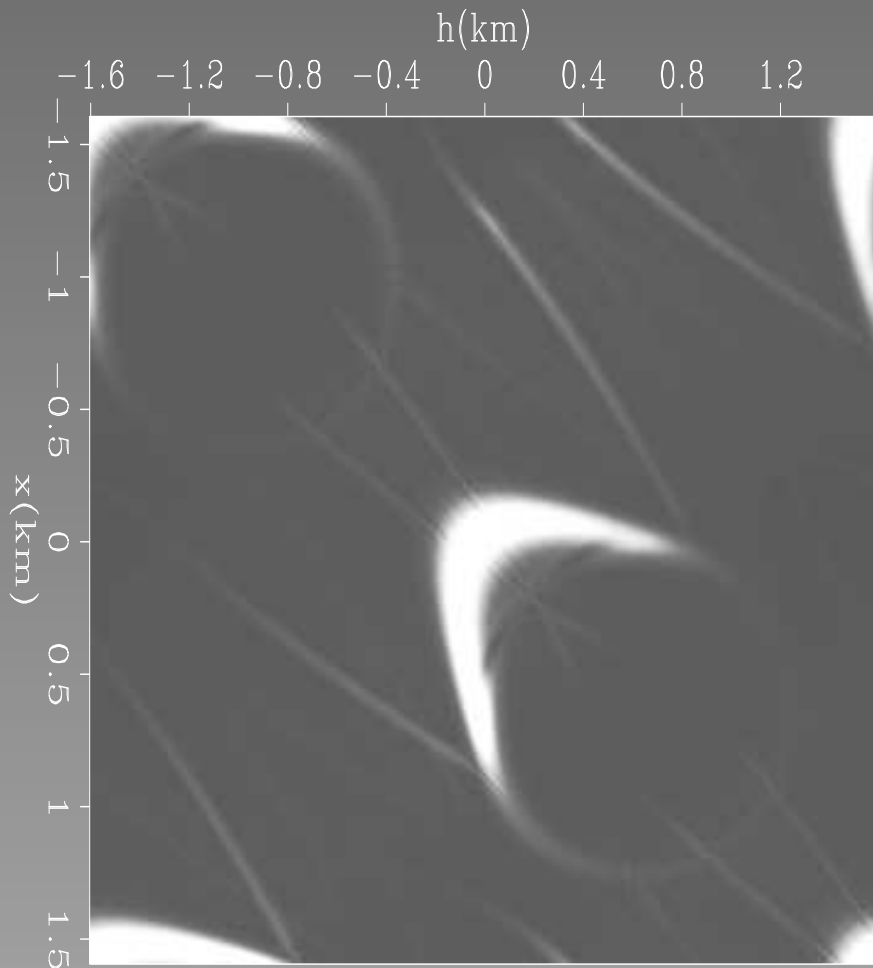


Fourier domain

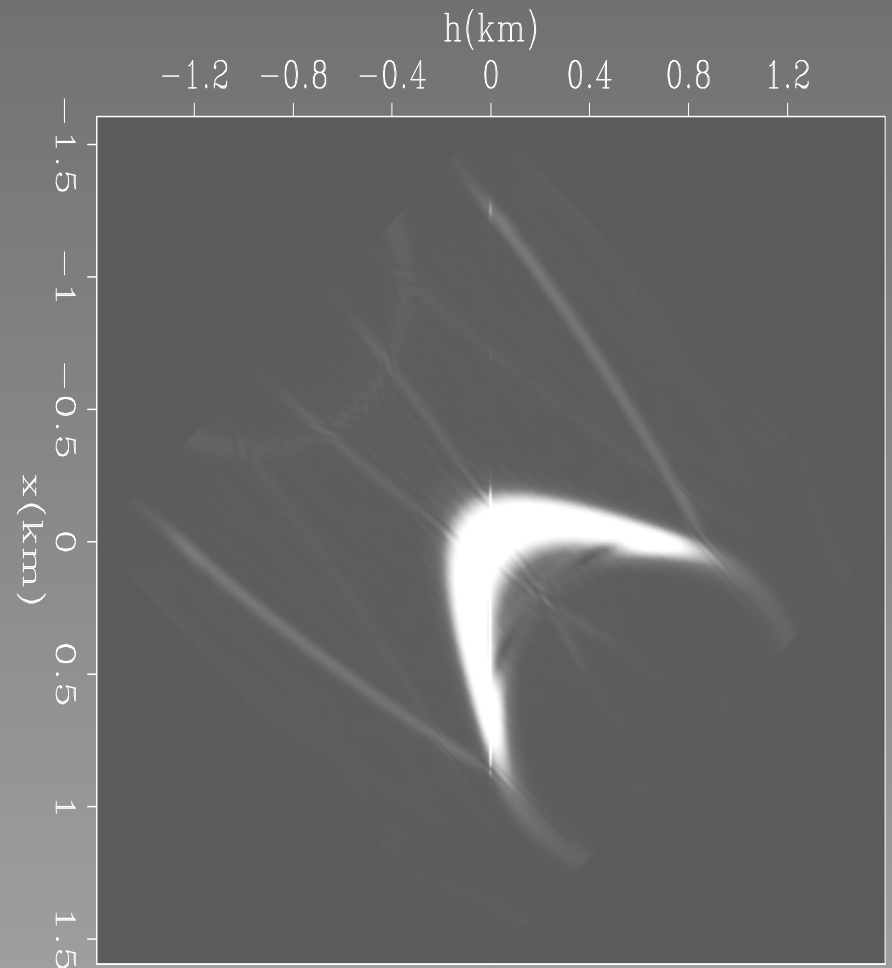


Space domain

$x - h$ impulse response

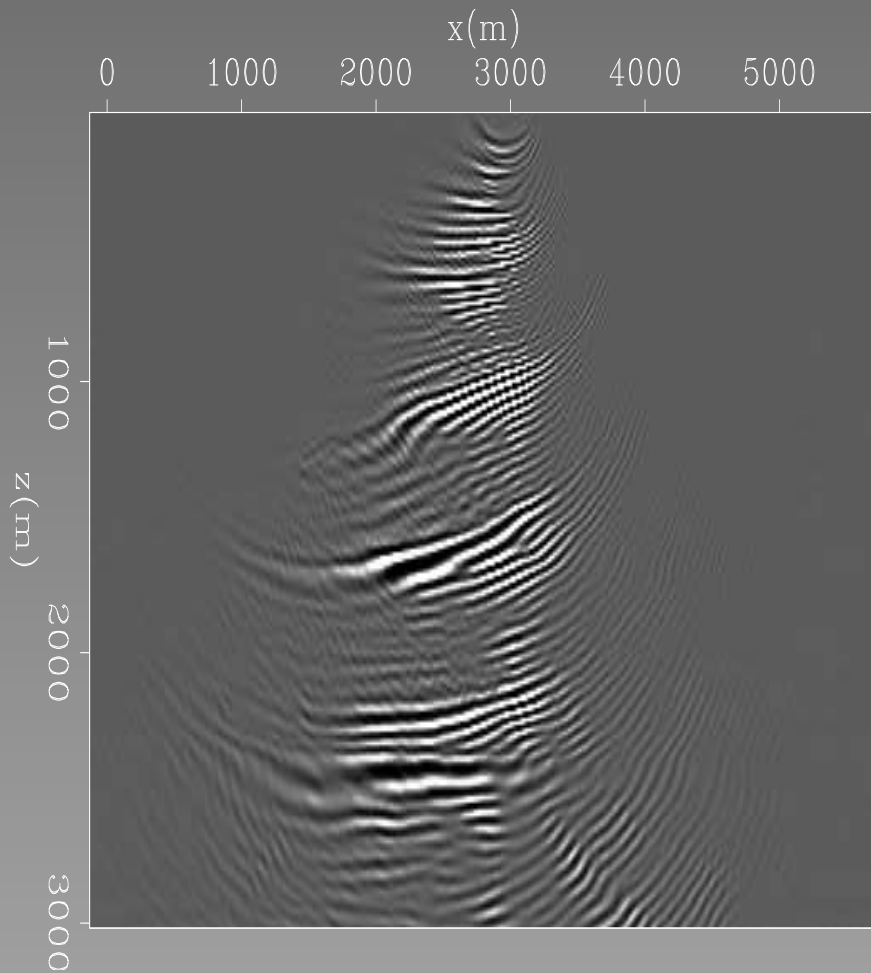


Fourier domain

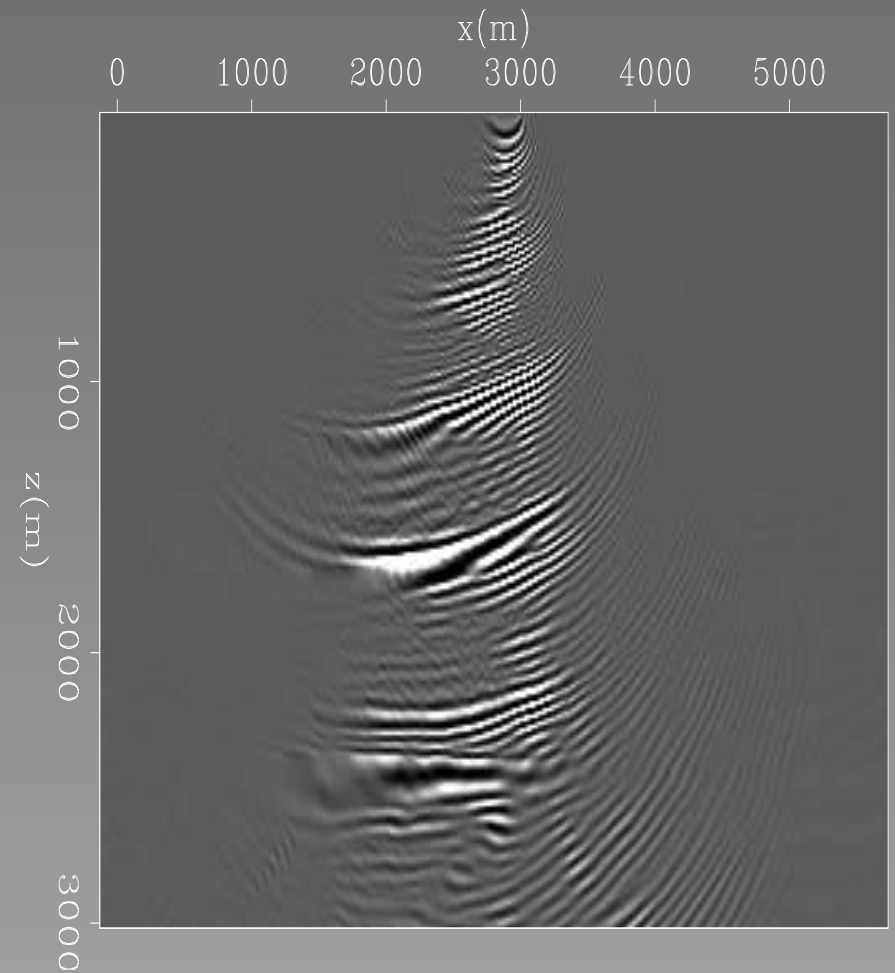


Space domain

Marmousi shot

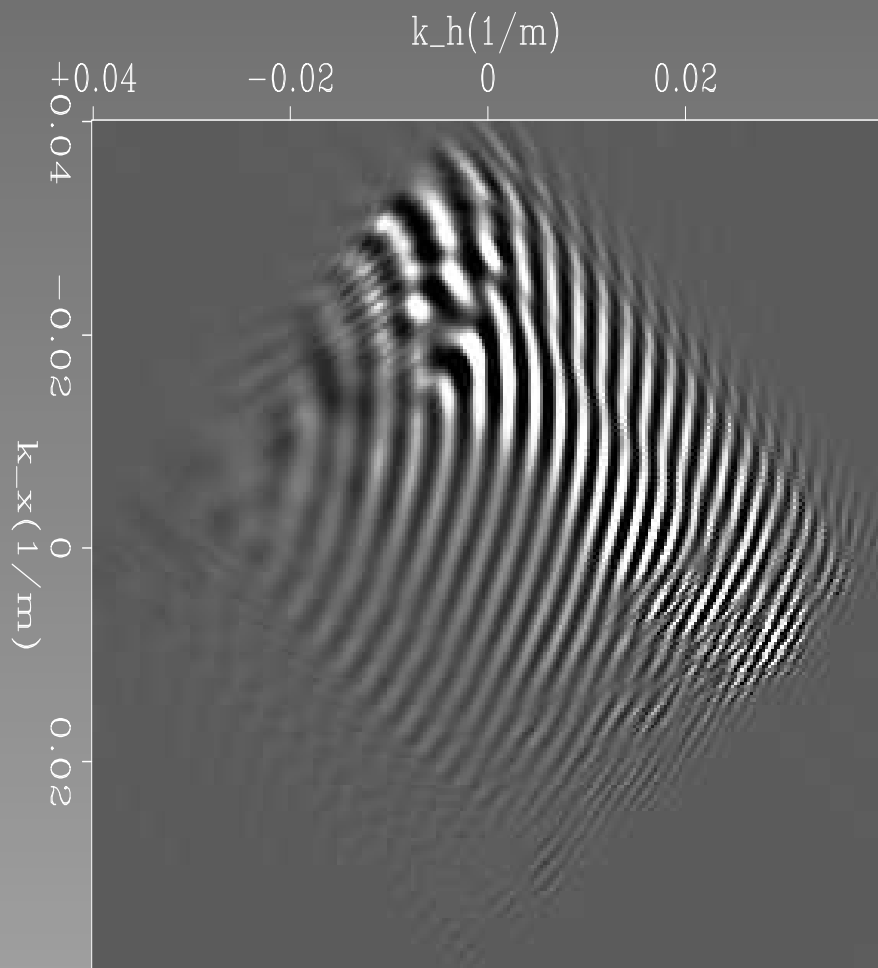


Fourier domain

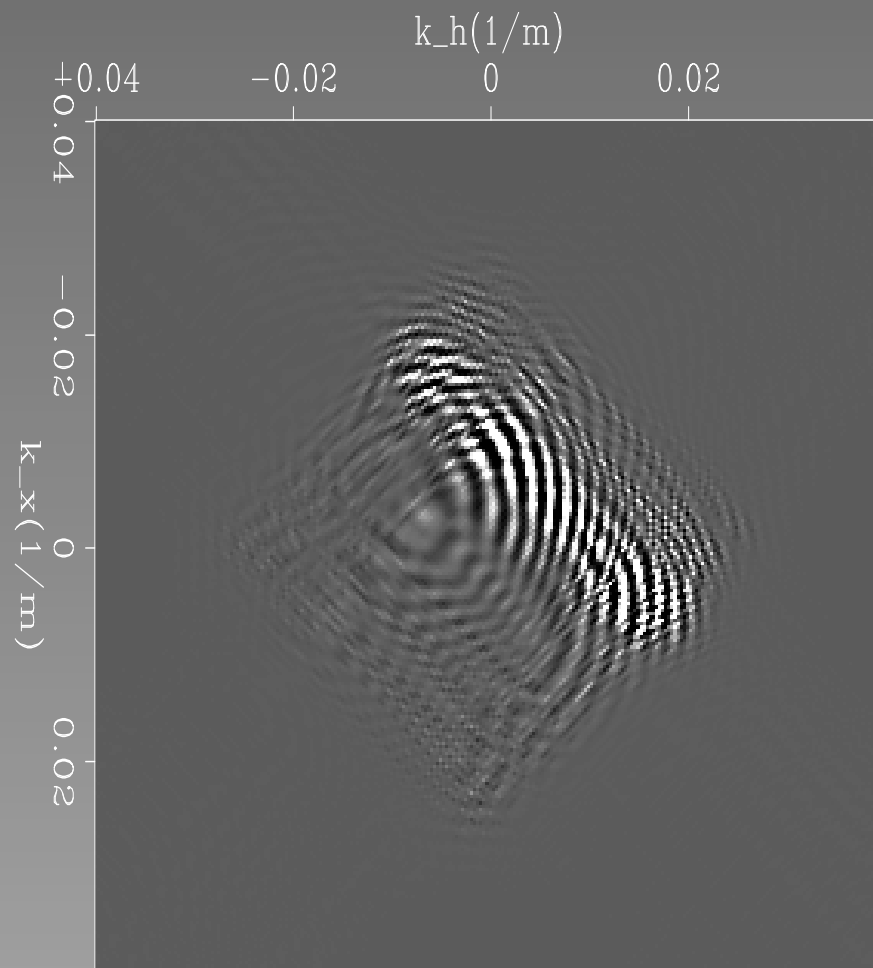


Space domain

Evanescence filter



shallow

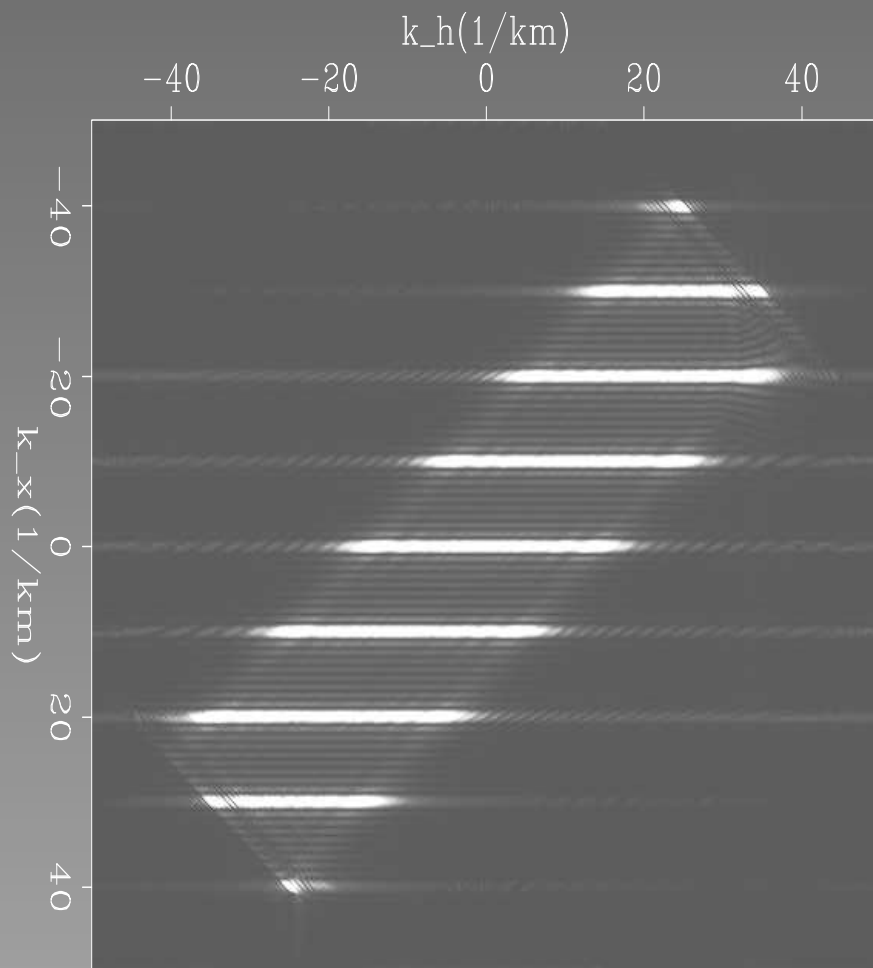


deep

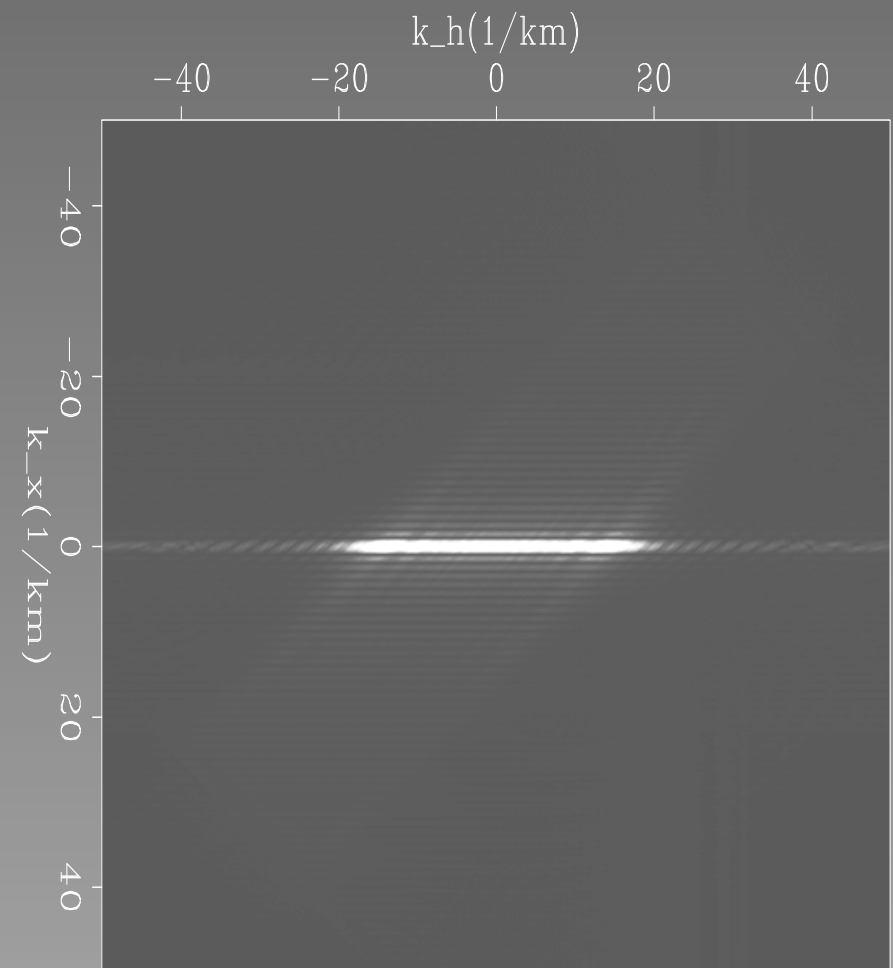
Operator aliasing

*“No hyperbolas have been harmed
during the filming of this motion picture.”*

Operator aliasing

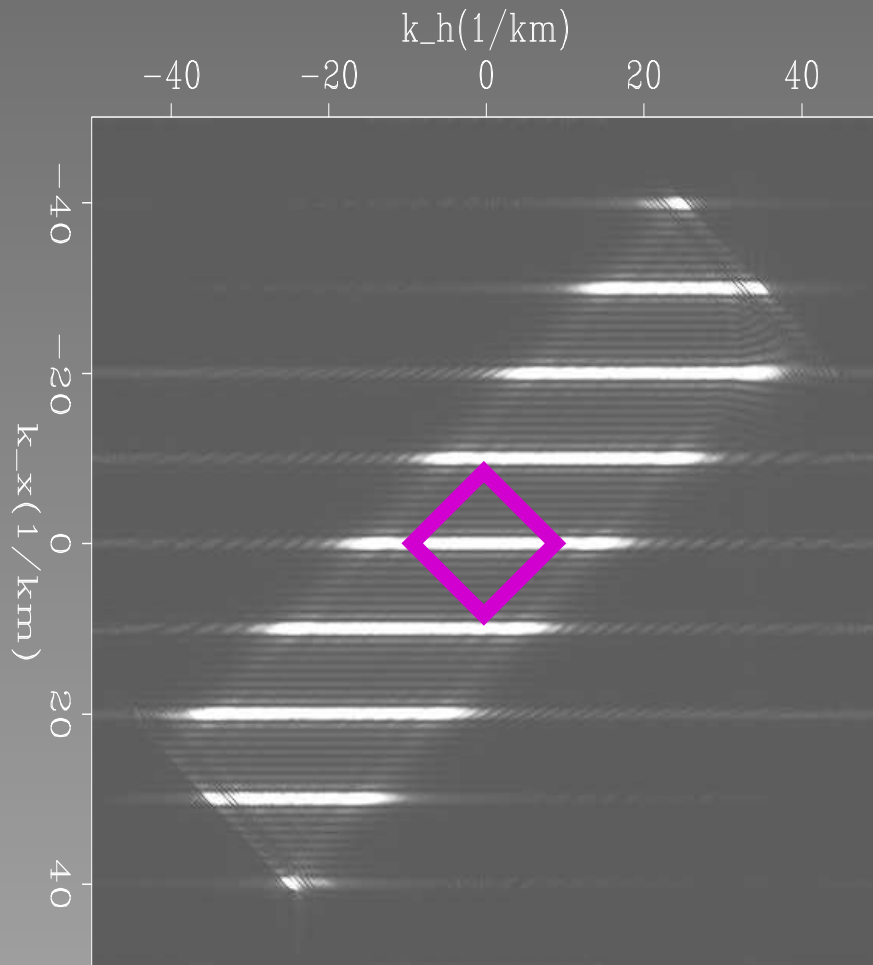


every 10^{th} shot

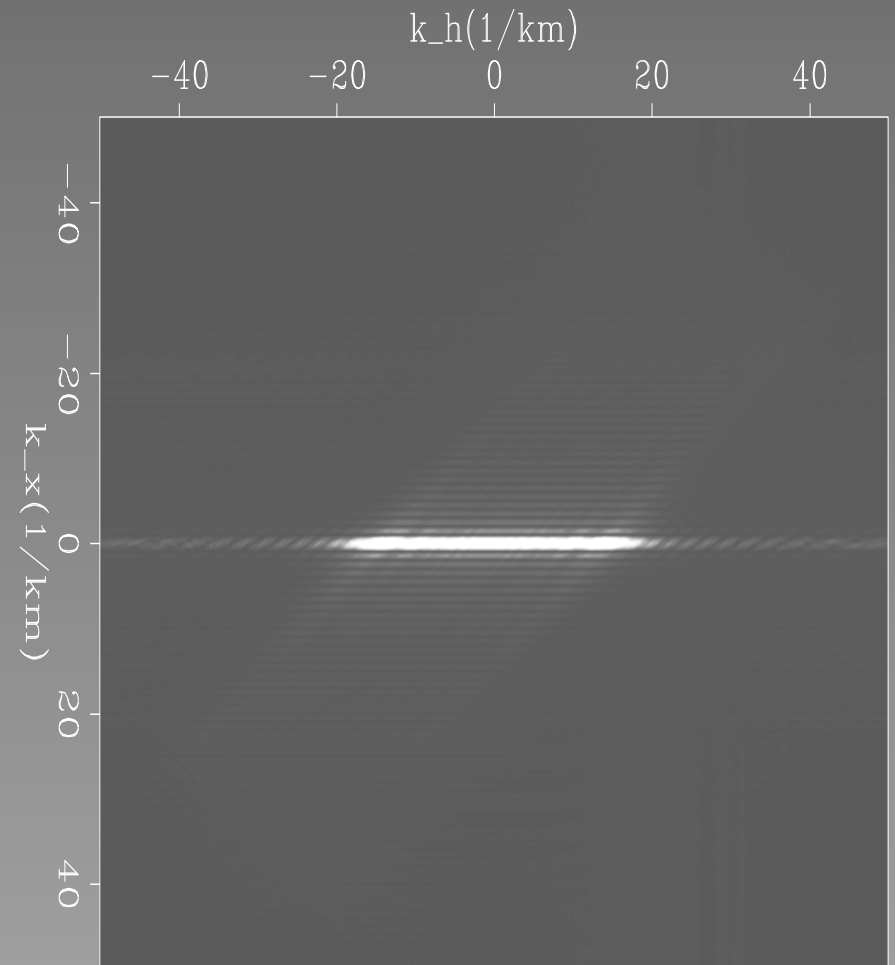


all shots

Operator aliasing



every 10^{th} shot



all shots

FDIC & aliasing

$$\hat{I}(k_x, k_h) = \frac{1}{2} \hat{U} \left(\frac{k_x + k_h}{2} \right) \hat{D}^* \left(\frac{k_x - k_h}{2} \right)$$

		k_h		
		-1	0	1
k_x	-2	$\hat{U}(-\frac{3}{2})\hat{D}^*(-\frac{1}{2})$	$\hat{U}(-\frac{2}{2})\hat{D}^*(-\frac{2}{2})$	$\hat{U}(-\frac{1}{2})\hat{D}^*(-\frac{3}{2})$
	-1	$\hat{U}(-\frac{2}{2})\hat{D}^*(0)$	$\hat{U}(-\frac{1}{2})\hat{D}^*(-\frac{1}{2})$	$\hat{U}(0)\hat{D}^*(-\frac{2}{2})$
	0	$\hat{U}(-\frac{1}{2})\hat{D}^*(\frac{1}{2})$	$\hat{U}(0)\hat{D}^*(0)$	$\hat{U}(\frac{1}{2})\hat{D}^*(-\frac{1}{2})$
	1	$\hat{U}(0)\hat{D}^*(\frac{2}{2})$	$\hat{U}(\frac{1}{2})\hat{D}^*(\frac{1}{2})$	$\hat{U}(\frac{2}{2})\hat{D}^*(0)$
	2	$\hat{U}(\frac{1}{2})\hat{D}^*(\frac{3}{2})$	$\hat{U}(\frac{2}{2})\hat{D}^*(\frac{2}{2})$	$\hat{U}(\frac{3}{2})\hat{D}^*(\frac{1}{2})$

Conclusion

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 - ★ Post-migration!

Thanks

Sergey Fomel & Biondo

Derivation 1

$$I(x, h)|_{\omega, z} = U(x_r - h)D(x_s + h) \quad (1)$$

Fourier transform D to \hat{D}

$$\hat{I}(x, h) = U(x - h) \int \hat{D}(k_s) e^{ik_s(x+h)} dk_s \quad (2)$$

FT all the x 's

$$\hat{I}(k_x, h) = \int U(x - h) \int \hat{D}(k_s) e^{ik_s(x+h)} dk_s e^{-ixk_x} dx \quad (3)$$

Derivation 2

Introduce (Sergey inspired) variable flip-flop/reorder

$$\begin{aligned}\hat{I}(k_x, h) &= \int \hat{D}(k_s) e^{ik_s h} \int U(x - h) e^{-ix(k_x - k_s)} dx dk_s \\ \hat{I}(k_x, h) &= \int \hat{D}(k_s) e^{ih(2k_s - k_x)} \\ &\quad \int U(x - h) e^{-i(x-h)(k_x - k_s)} d(x - h) dk_s \quad (4)\end{aligned}$$

Note salient details: Inner integral is FT of U,

$$\hat{I}(k_x, h) = \int \hat{U}(k_x - k_s) \hat{D}(k_s) e^{ih(2k_s - k_x)} dk_s \quad (5)$$

Derivation 3

knowing $k_h = 2k_s - k_x$,

$$\hat{I}(k_x, h) = \frac{1}{2} \int \hat{U}\left(\frac{k_x - k_h}{2}\right) \hat{D}\left(\frac{k_x + k_h}{2}\right) e^{-ihk_h} dk_h \quad (6)$$

This we see is FT over offset, so the complete FT of the IC is

$$\hat{I}(k_x, k_h) = \frac{1}{2} \hat{U}\left(\frac{k_x - k_h}{2}\right) \hat{D}\left(\frac{k_x + k_h}{2}\right). \quad (7)$$

return