

## Homework 10: Numerical Solution of ODE: One-Step Methods (due on April 23)

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1. (a) Which of the following functions satisfy the Lipschitz condition on  $y$ ? For those that do, find the Lipschitz constant.
- i.  $f(x, y) = \sqrt{x^2 + y^2}$  for  $x \in [-1, 1]$
  - ii.  $f(x, y) = |y|$
  - iii.  $f(x, y) = \sqrt{|y|}$
  - iv.  $f(x, y) = |y|/x$  for  $x \in [-1, 1]$
- (b) Prove that the function  $f(x, y) = -\sqrt{|1 - y^2|}$  does not satisfy the Lipschitz condition and find two different solutions of the initial-value problem

$$\begin{cases} y'(x) = -\sqrt{|1 - y^2(x)|} \\ y(0) = 1 \end{cases} \quad (1)$$

on the interval  $x \in [0, \pi]$ .

2. Consider the initial-value problem

$$\begin{cases} y''(x) = y(x) \\ y(0) = y_0 \\ y'(0) = y_1 \end{cases} \quad (2)$$

Write it as a system of two first-order differential equations with the appropriate initial conditions. Prove that Euler's method applied to this system can be unstable for a large step size.

Hint: Take the special case  $y_1 = -y_0$ .

3. Consider the initial-value problem

$$\begin{cases} y'(x) = \lambda y(x) \\ y(0) = y_0 \end{cases} \quad (3)$$

- (a) Prove that the Taylor series method for this problem takes the form

$$y(x_{k+1}) \approx y_{k+1} = \left[ 1 + \lambda h + \frac{(\lambda h)^2}{2} + \cdots + \frac{(\lambda h)^n}{n!} \right] y_k, \quad (4)$$

where  $h = x_{k+1} - x_k$ , and  $n$  is the order of the method.

- (b) Prove that every second-order Runge-Kutta method for this problem is equivalent to the second-order Taylor method.
- (c) Prove that the second-order Taylor method can be unstable for large negative  $\lambda$  and find the stability region for the step size  $h$ .

4. (Programming) The exact solution of the initial-value problem

$$\begin{cases} y'(x) = f(x, y) = y^2(x)e^{-x} \\ y(0) = 1 \end{cases} \quad (5)$$

is

$$y(x) = e^x. \quad (6)$$

Solve the problem numerically on the interval  $x \in [0, 1]$  using

(a) Euler's method

$$y_{k+1} = y_k + h f(x_k, y_k) \quad (7)$$

(b) Second-order Taylor method

$$y_{k+1} = y_k + h f(x_k, y_k) + \frac{h^2}{2} \left[ \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} f(x_k, y_k) \right] \quad (8)$$

(c) Midpoint method

$$y_{k+1} = y_k + h f \left[ x_k + \frac{h}{2}, y_k + \frac{h}{2} f(x_k, y_k) \right] \quad (9)$$

Take the step size  $h = 0.1$  and output the error at all steps of the computation.

5. (Programming) In 1926, Volterra developed a mathematical model for predator-prey systems. If  $R$  is the population density of prey (rabbits), and  $F$  is the population density of predators (foxes), then Volterra's model for the population growth is the system of ordinary differential equations

$$R'(t) = a R(t) - b R(t) F(t); \quad (10)$$

$$F'(t) = d R(t) F(t) - c F(t), \quad (11)$$

where  $t$  is time,  $a$  is the natural growth rate of rabbits,  $c$  is the natural death rate of foxes,  $b$  is the death rate of rabbits per one unit of the fox population, and  $d$  is the growth rate of foxes per one unit of the rabbit population.

Adopt the midpoint method for the solution of this system. Take  $a = 0.03$ ,  $b = 0.01$ ,  $c=0.01$ , and  $d = 0.01$ , the interval  $t \in [0, 500]$ , the step size  $h = 1$  and the initial values

(a)

$$R(0) = 1.0;$$

$$F(0) = 2.0$$

(b)

$$R(0) = 1.0;$$

$$F(0) = 4.0$$

Plot the solution: functions  $R(t)$  and  $F(t)$ .