

Imaging of complex structures by 3-D reflection seismic data



Biondo Biondi

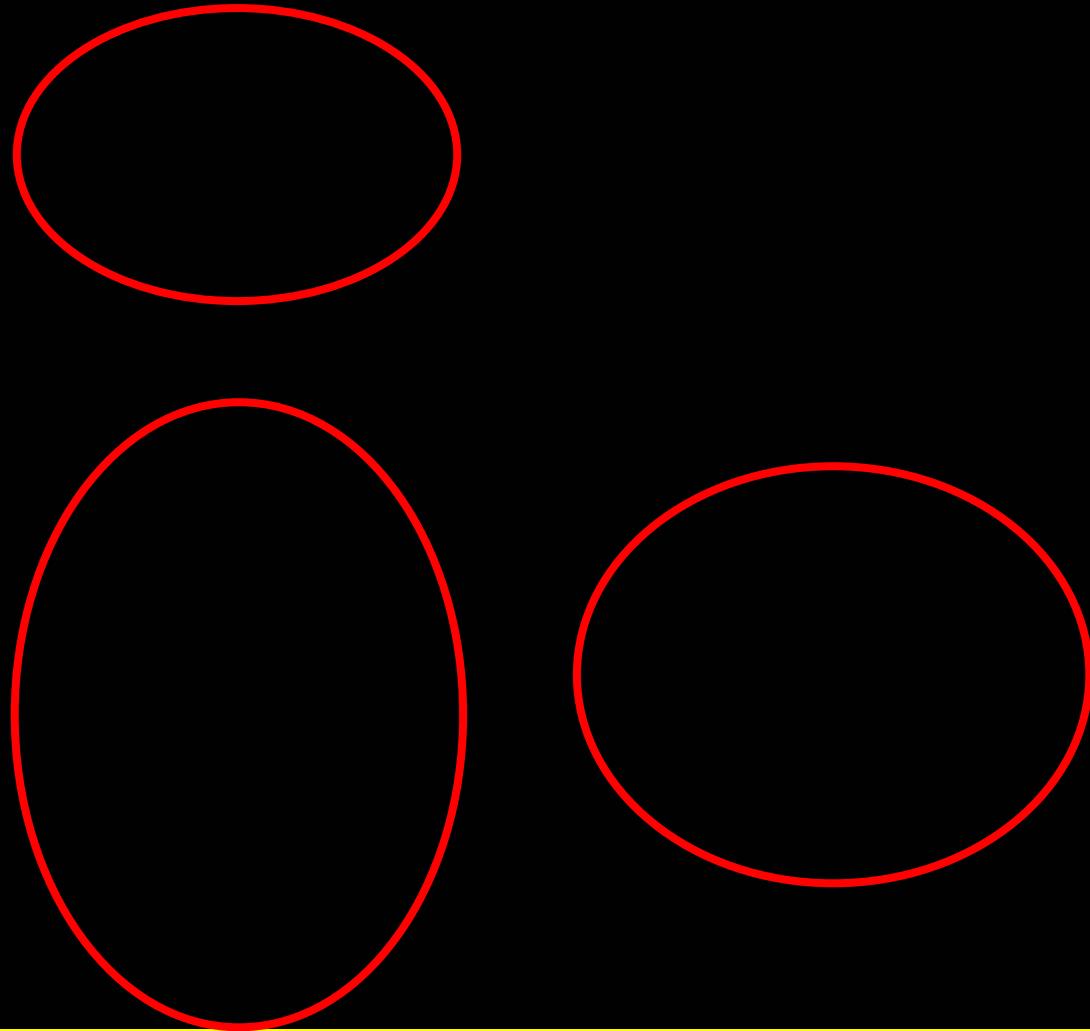
Stanford Exploration Project
Stanford University

IPRPI Workshop on Geophysical Imaging

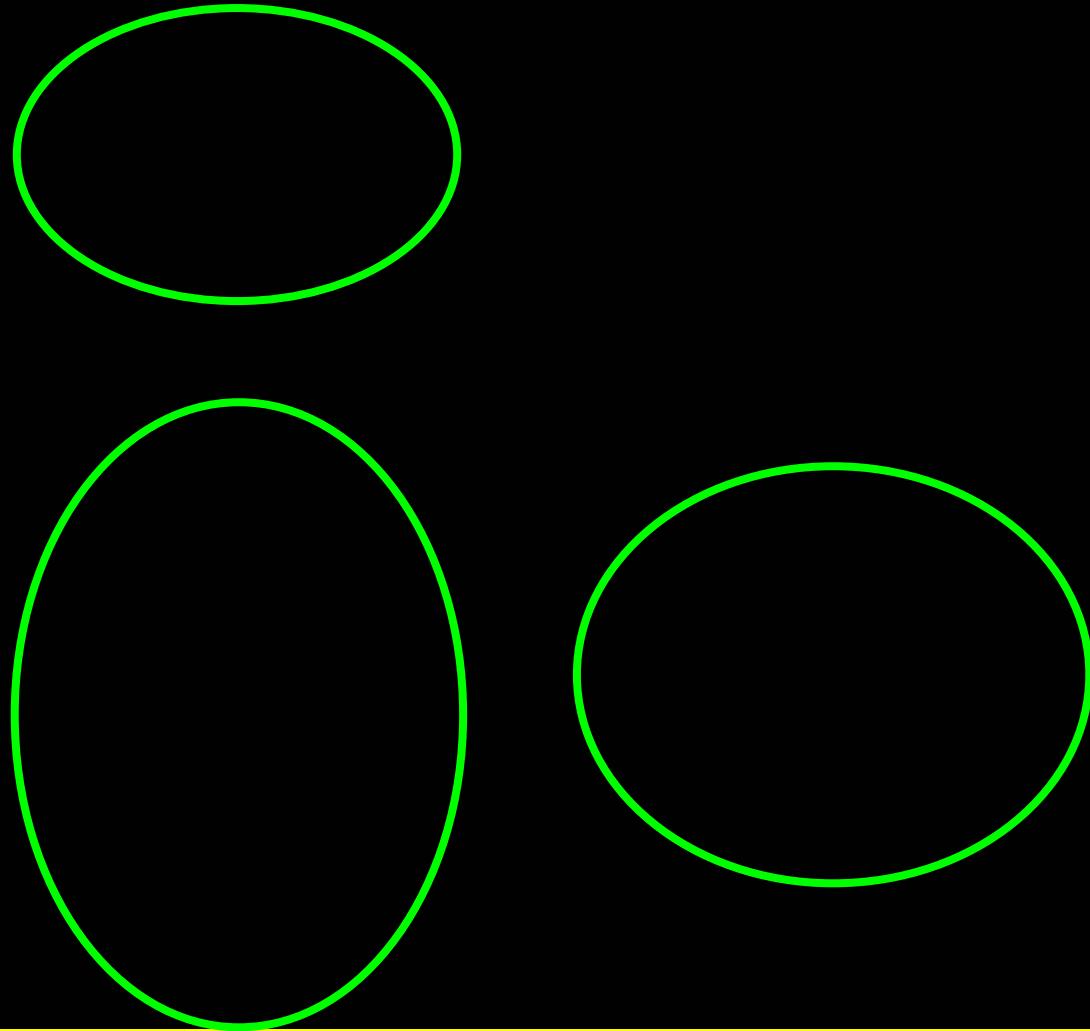
An example of imaging complex structures...



Deep Water GOM - Kirchhoff Mig.



Deep Water GOM – Wavefield-continuation Mig.



Outline

- **Migration and complex wave propagation**
 - Wavefield continuation migration
 - Gaussian Beams and Coherent States migration
- **Migration => Iterative Regularized Inversion**
 - Normalized Migration
 - Iterative Wavefield Inversion with geophysical and geological constraints
- **Migration Velocity Analysis (MVA)**
 - Angle Domain Common Image Gathers (ADCIGs)
 - Ray tomography using ADCIGs
 - Wave-equation Migration Velocity Analysis

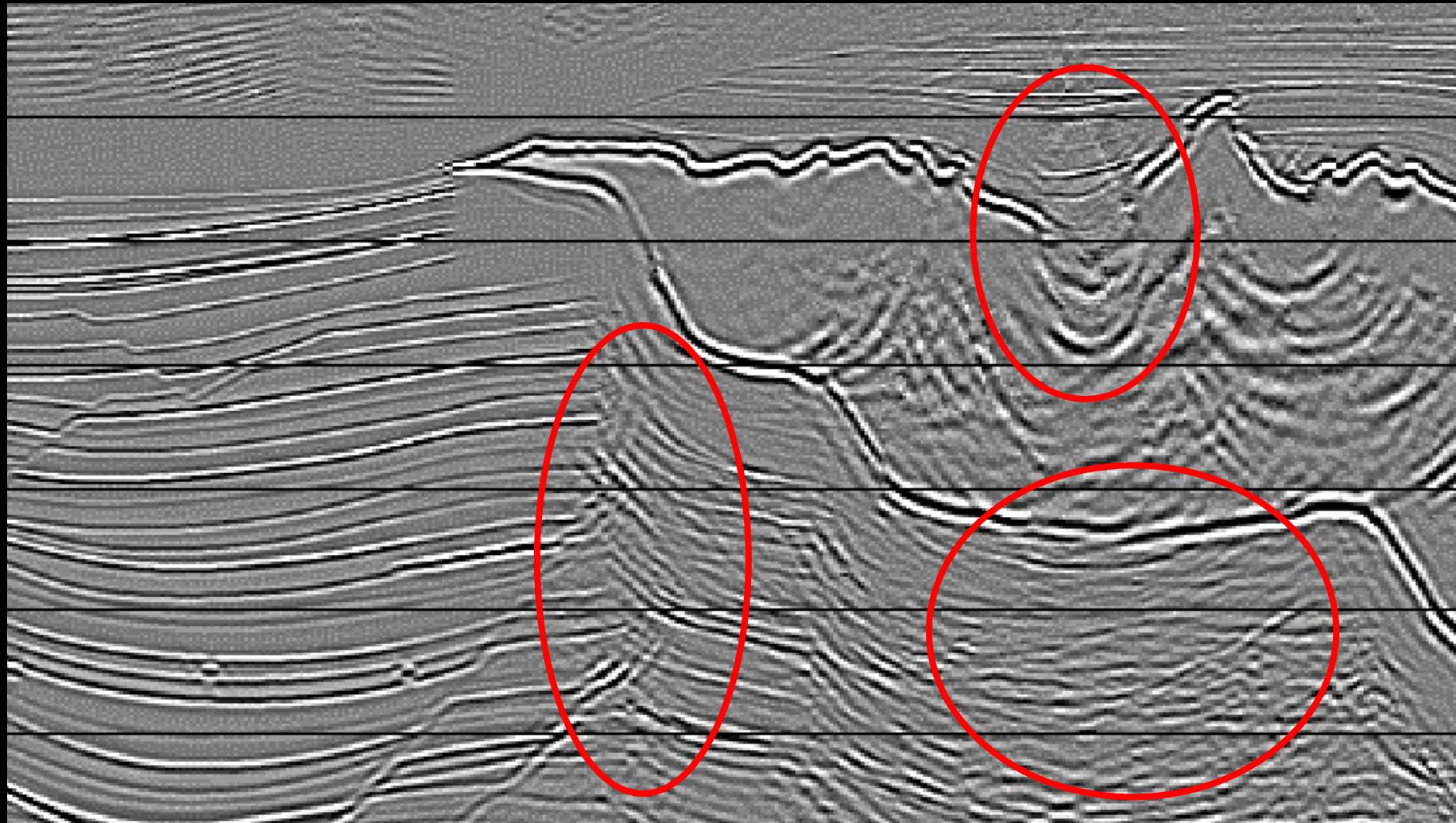
- Routine
- Advanced
- Future?

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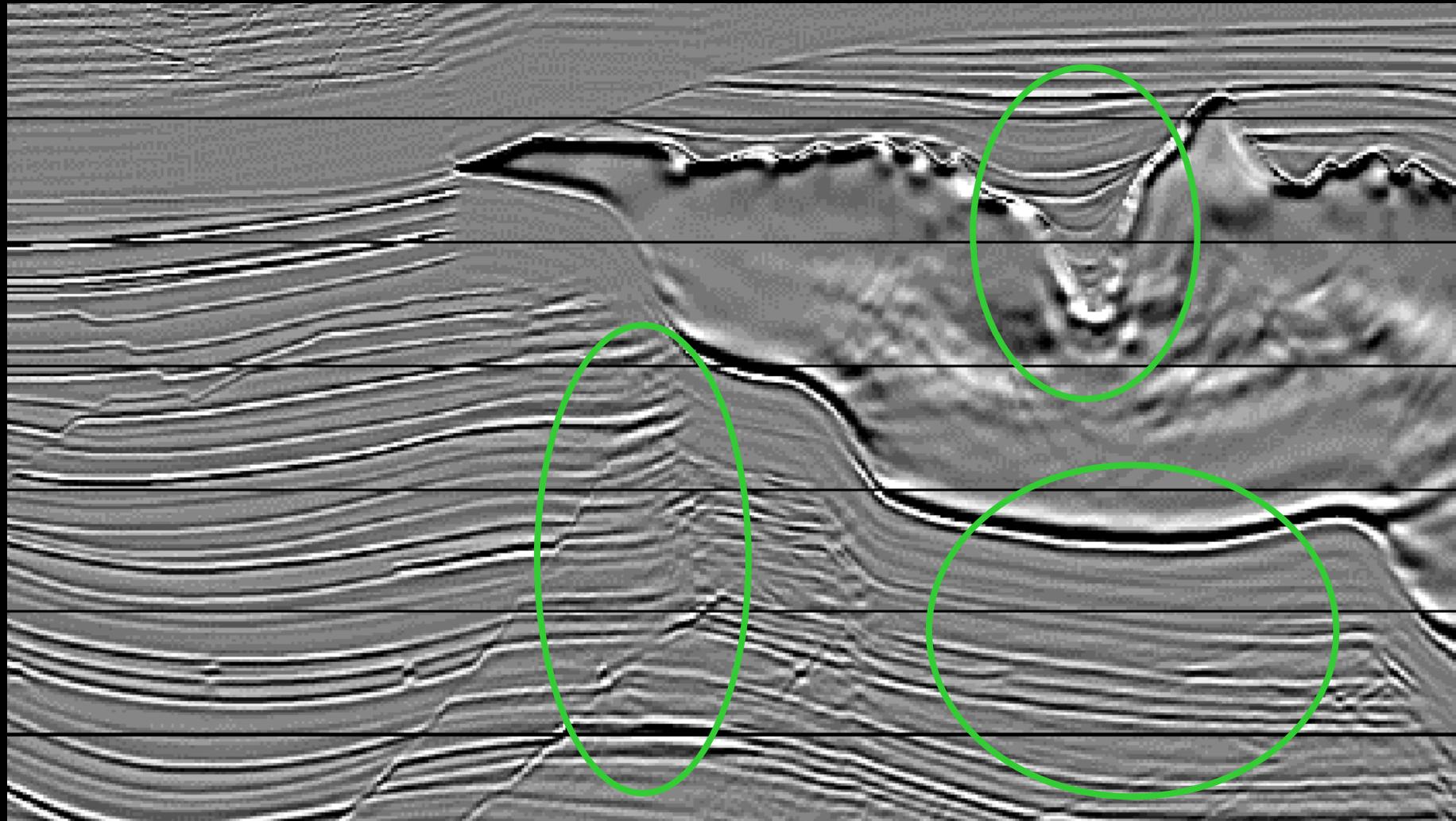
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Sigsbee data - Kirchhoff



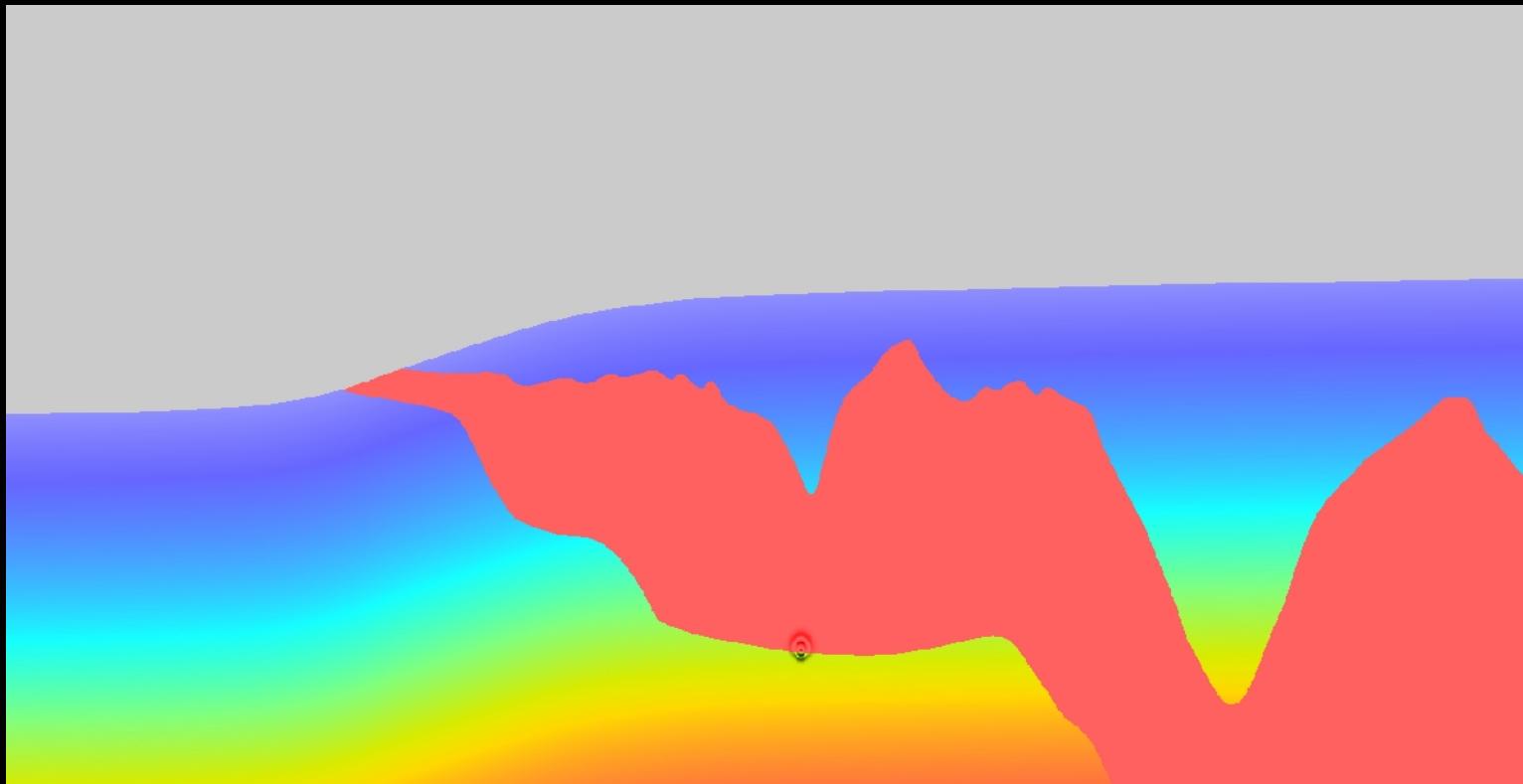
J. Paffenholz - SEG 2001

Sigsbee data - Wavefield continuation

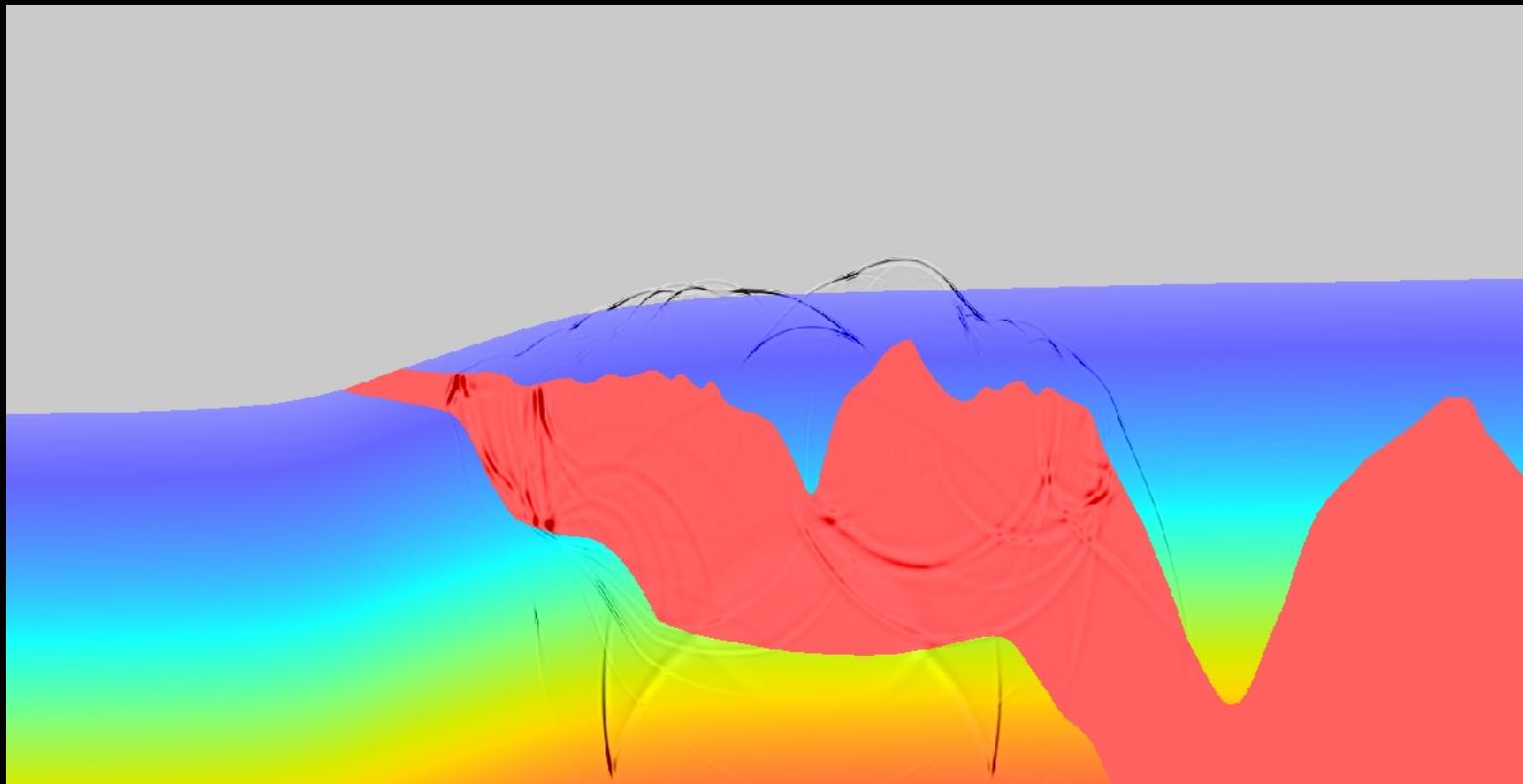


J. Paffenholz - SEG 2001

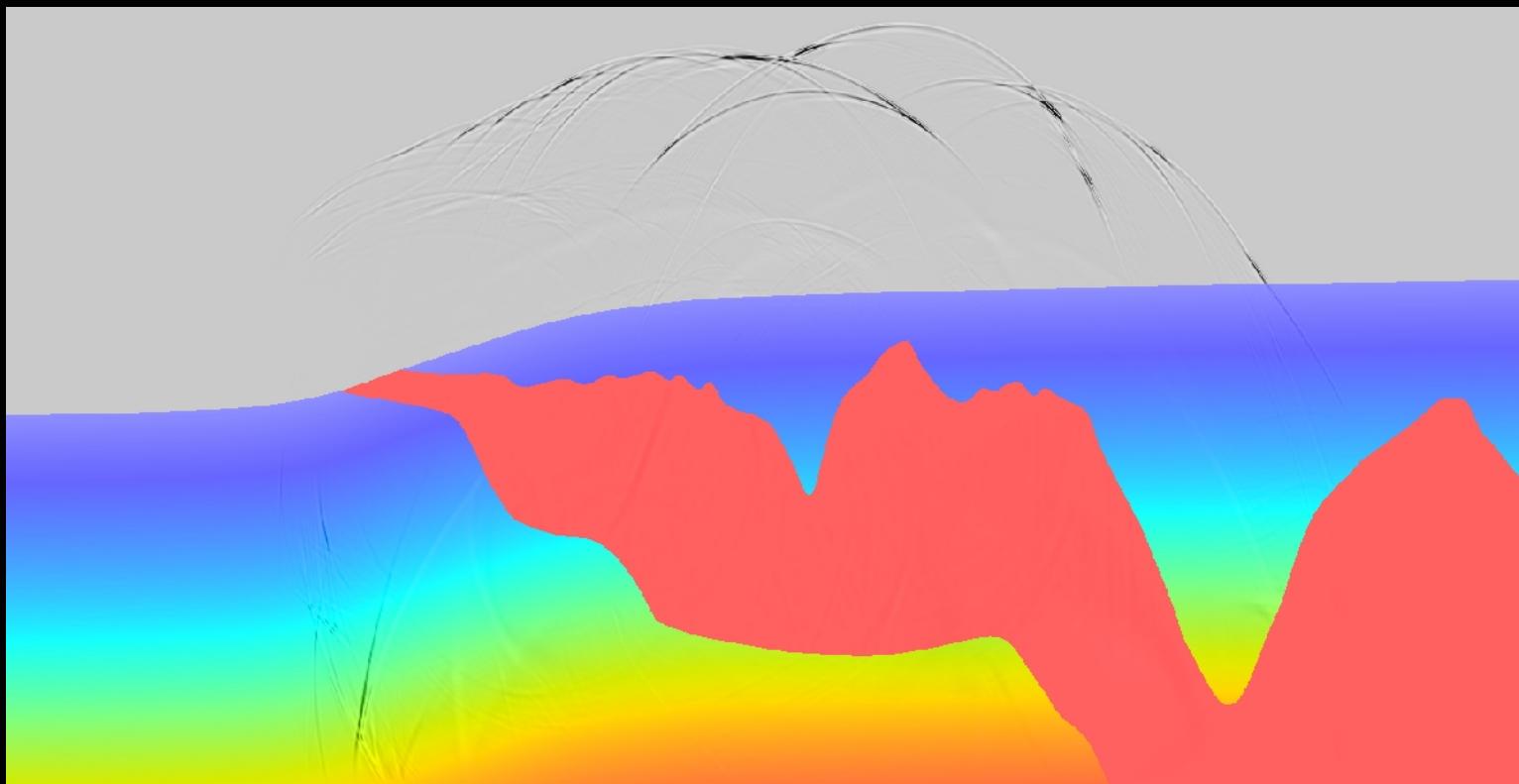
Sigsbee data - Wave modeling



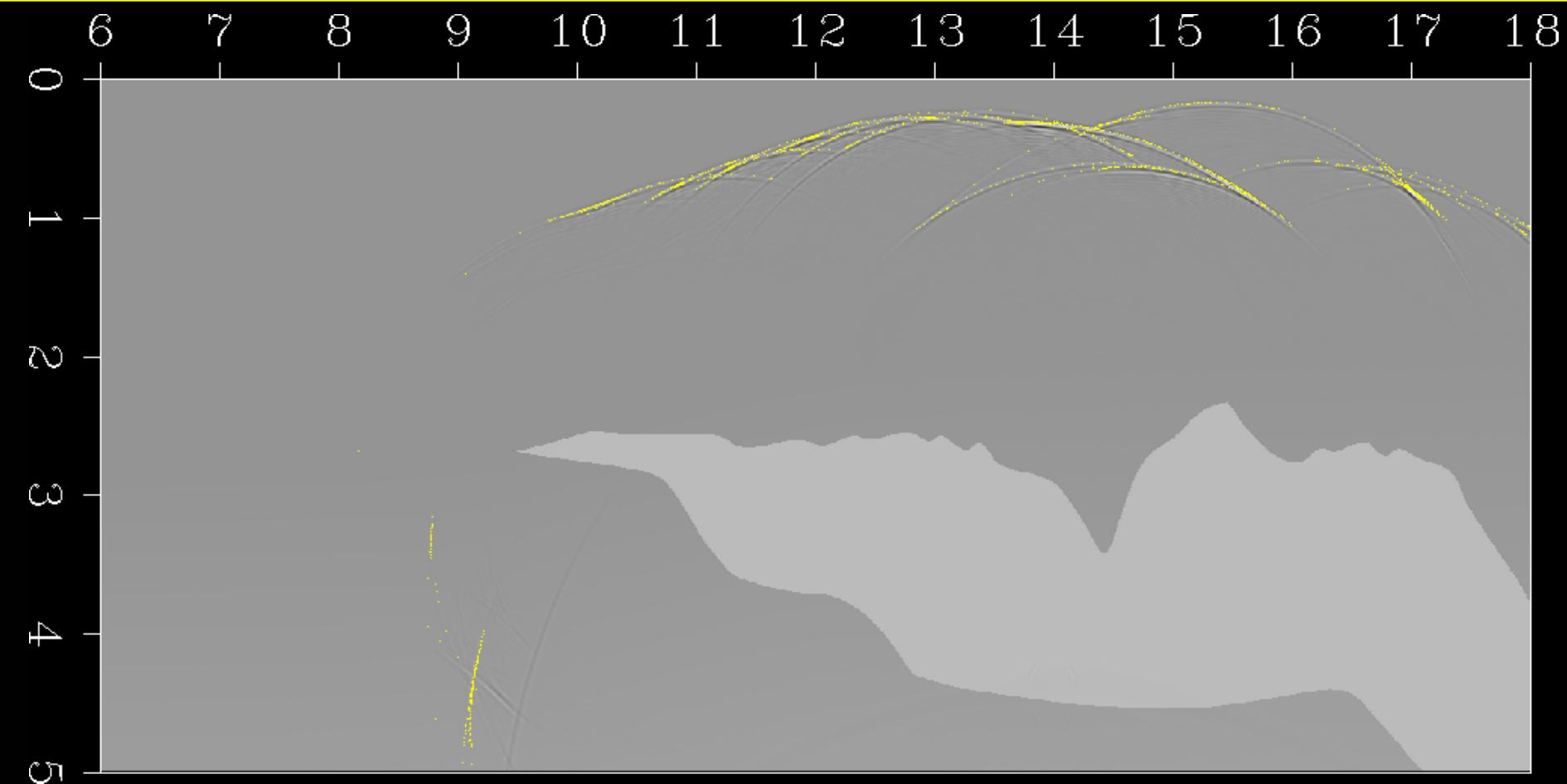
Sigsbee data - Wave modeling



Sigsbee data - Wave modeling



Sigsbee data - Wave modeling



Sigsbee data - Wave modeling

11

12

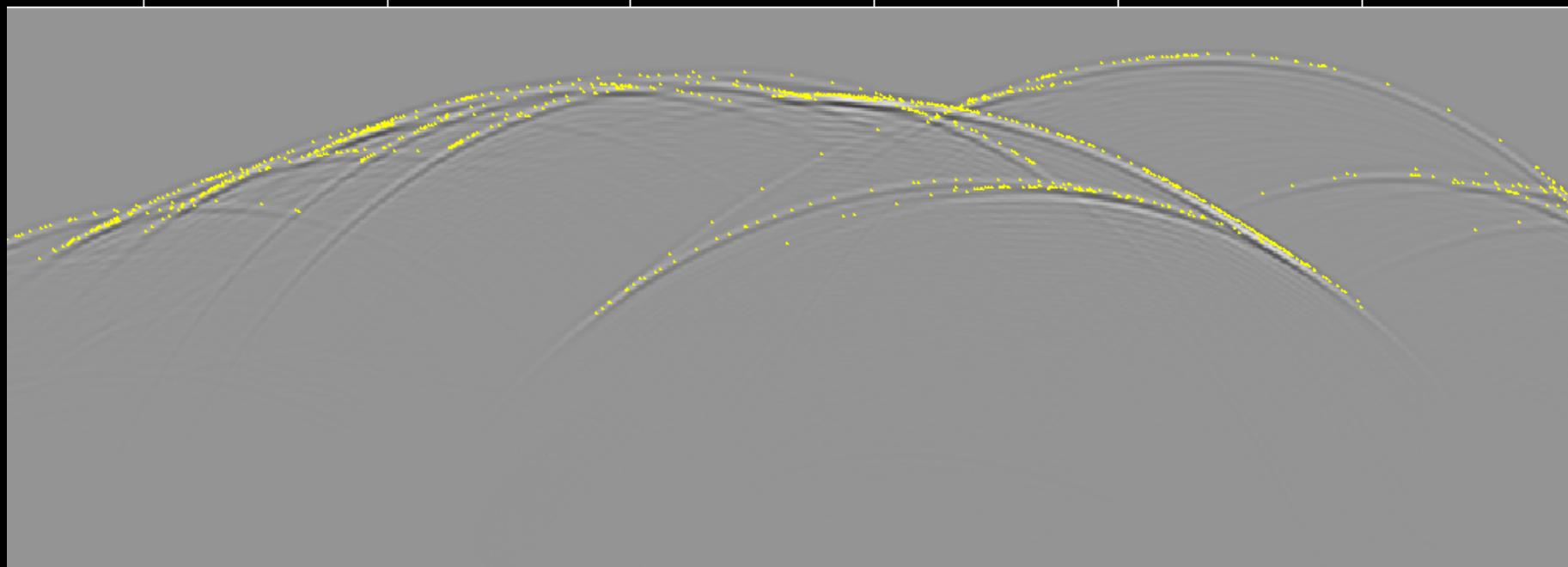
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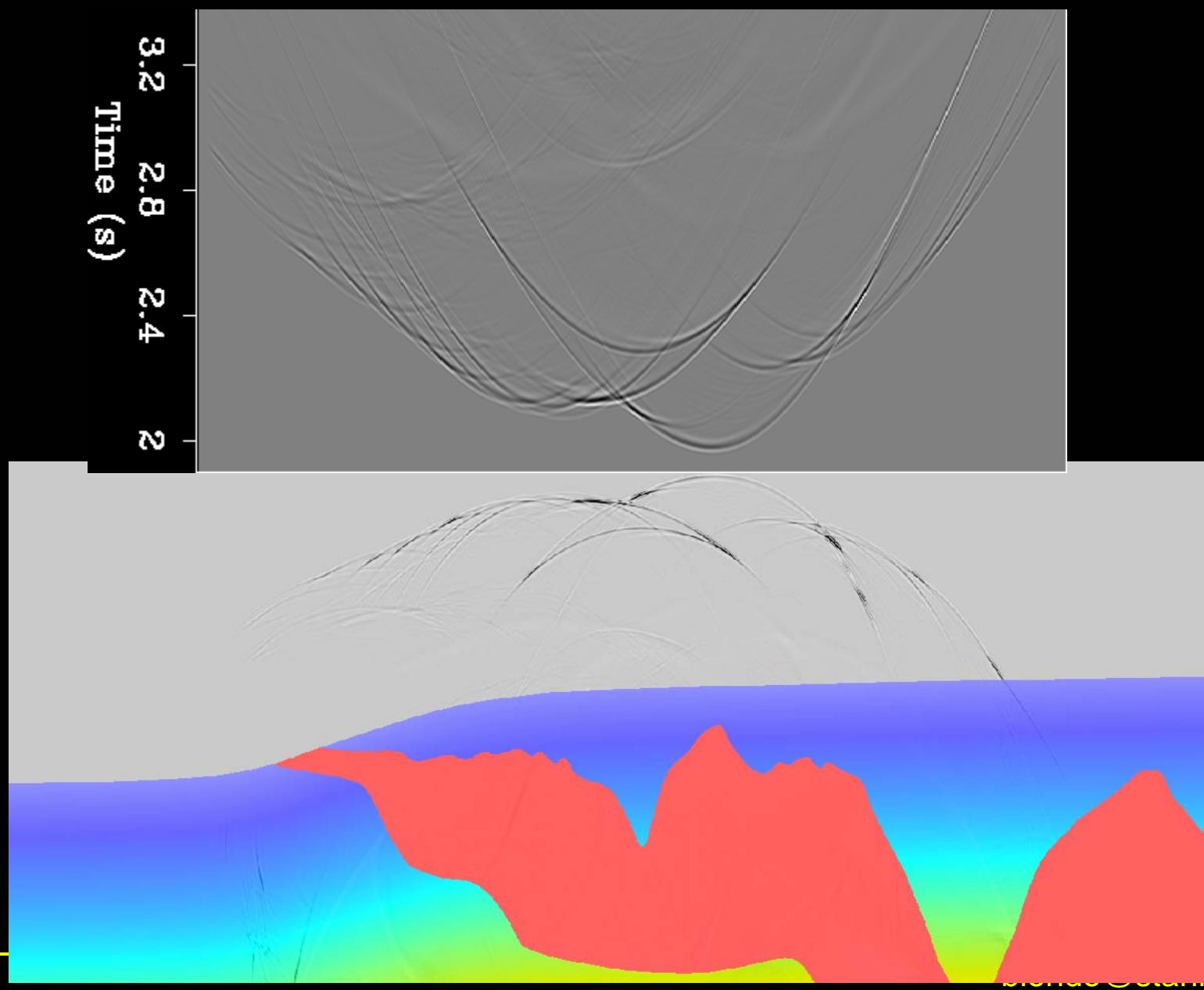
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1



Sigsbee data - Wave modeling

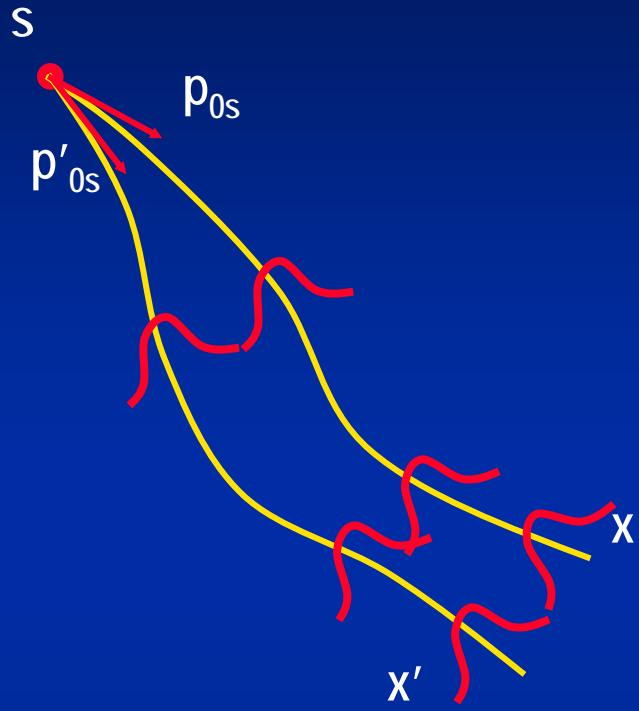


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Superposition of Beams

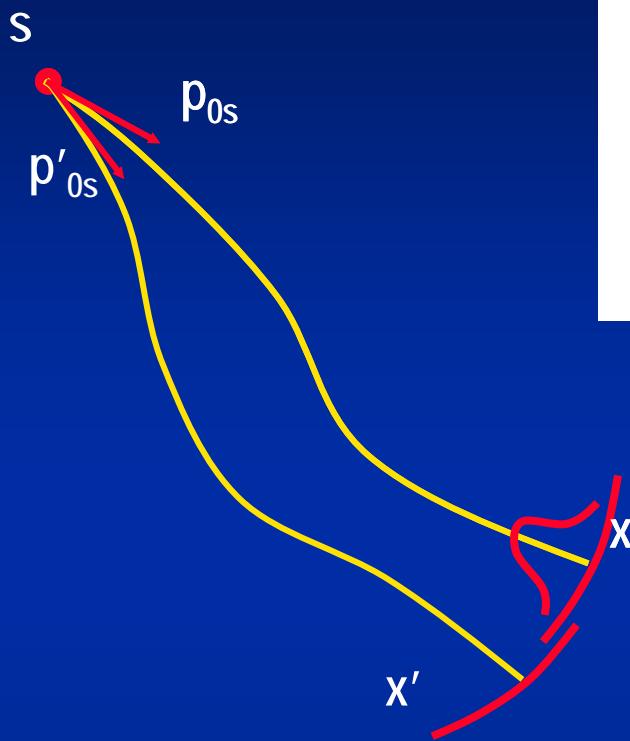


Solve wave equation by localizing initial wavefield in space and ray parameter (wavenumber)

Extrapolate and superimpose these solutions to form wavefield

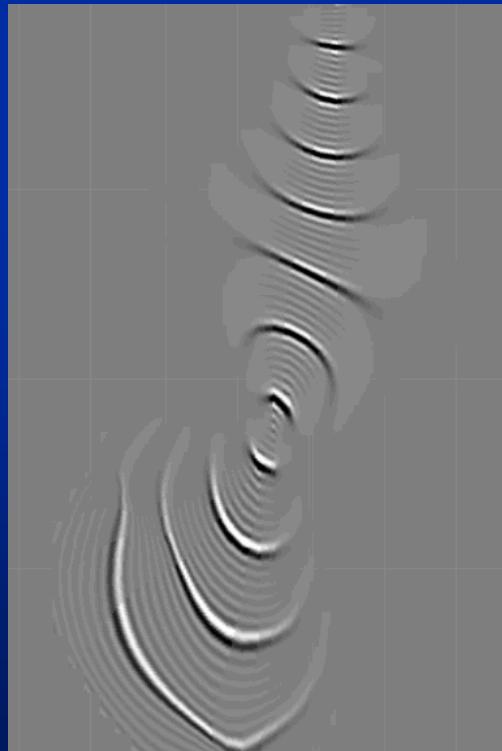
If local solution is accurate and superposition is correct, accurate wavefield should result, including all arrivals, amplitudes, and phases

Gaussian Beam (Ray based)



$$G(s, \mathbf{x}) \sim \int dp_{0s} u(s, p_{0s}, \sigma_s, n_s)$$

$$u = \left(\frac{v(\sigma_s)}{q(\sigma_s)} \right)^{1/2} \exp \left[i\omega \left(\tau(s, \sigma_s) + \frac{1}{2} \frac{p(\sigma_s)}{q(\sigma_s)} n_s^2 \right) \right].$$



Cerveny, Popov, Psencik 1982

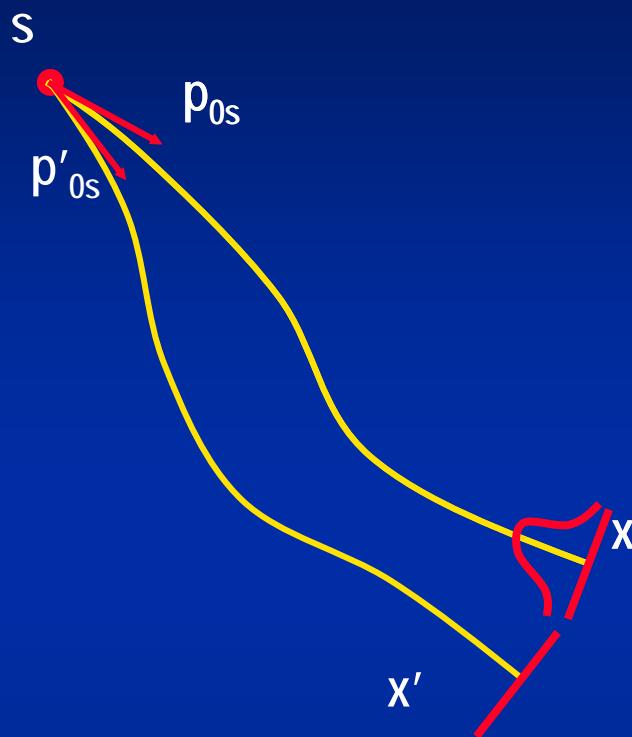
Hill, 1990, 2001

Kinneging et al 1989

White et al 1987

Hale 1992

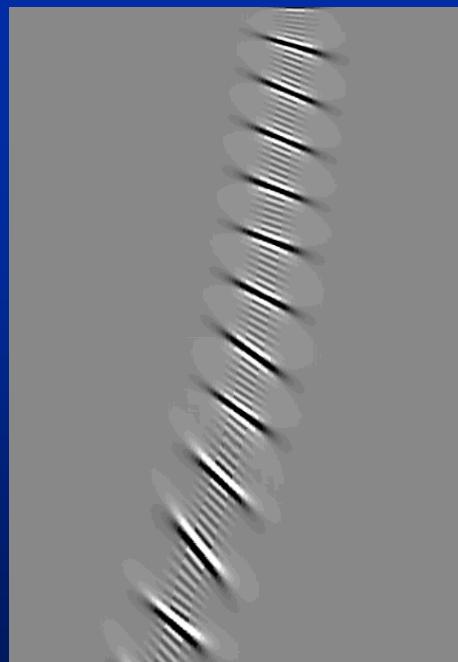
Asymptotic Coherent State (Ray based)



$$G(s, \mathbf{x}) \sim \int dp_{0s} u(s, p_{0s})$$

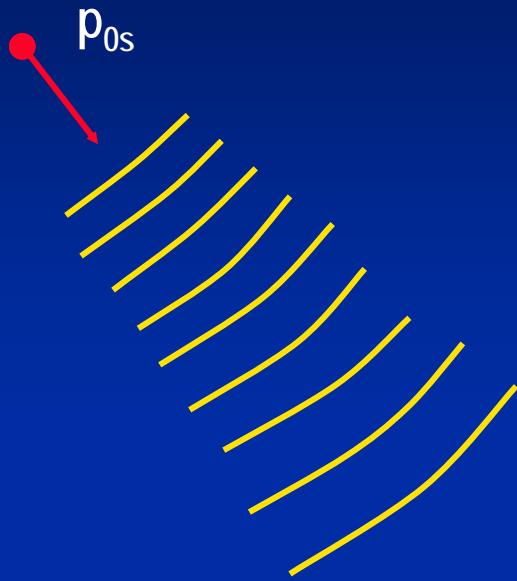
$$u(s, p_{0s}) \sim \left[\left| \frac{d\mathbf{p}}{dp_{0s}} \right|^2 \mu^2 + \Omega^2 \left| \frac{d\mathbf{x}}{dp_{0s}} \right|^2 \right]^{1/4}$$

$$\exp \left[i\omega [\tau(s, \mathbf{x}(p_{0s})) - \mathbf{p}(p_{0s}) \cdot (\mathbf{x}(p_{0s}) - \mathbf{x})] - \frac{1}{2}\omega\Omega(\mathbf{x}(p_{0s}) - \mathbf{x})^2 \right]$$

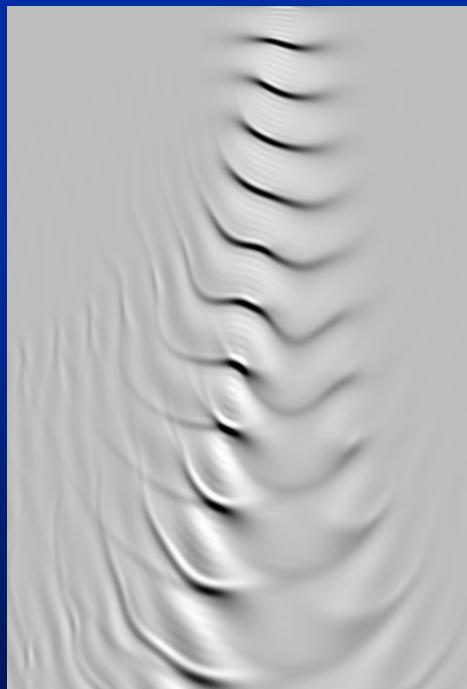


Foster and Huang, 1991
Thompson, 2000
Albertin et al 2001

Wavefield-Extrapolated Coherent State



$$G(s, \mathbf{x}) \sim \int dp_{0s} u(s, p_{0s}, \mathbf{x})$$
$$u(s, p_{0s}, \mathbf{x}) \sim W \left[e^{-\frac{1}{2}\omega\Omega(x-x_0)^2} e^{-i\omega p_{0s}(x-x_0)} \right]$$



Foster and Huang 1991
Wu et al 2000
Albertin 2001

Wavefield Extrapolated Zero-offset Impulse

Schlumberger Private

Asymptotic Coherent State Reconstruction

Schlumberger Private

3 raytraced coherent states

Asymptotic Coherent State Reconstruction

Schlumberger Private

12 raytraced coherent states

Asymptotic Coherent State Superposition

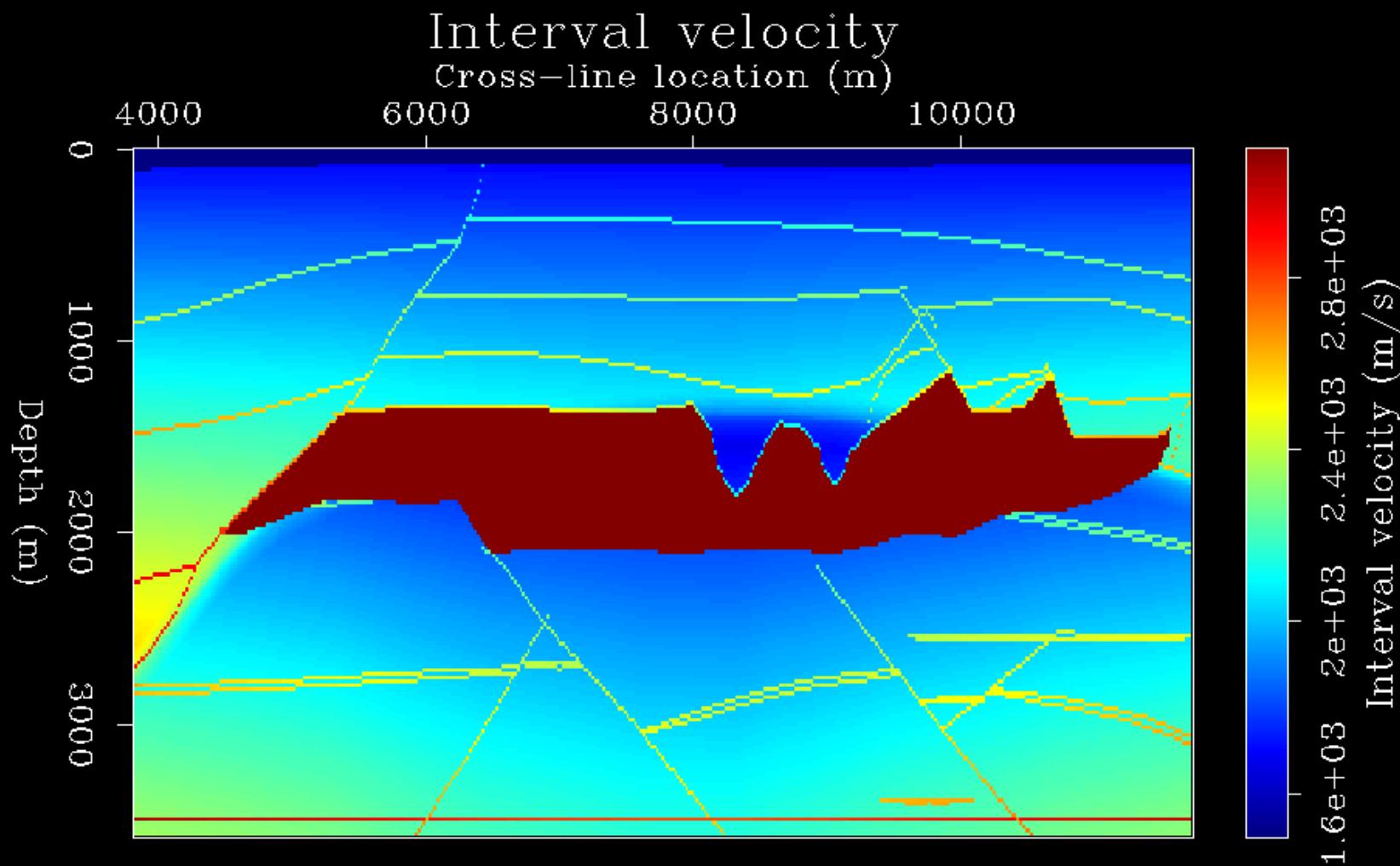
Schlumberger Private

572 raytraced coherent states

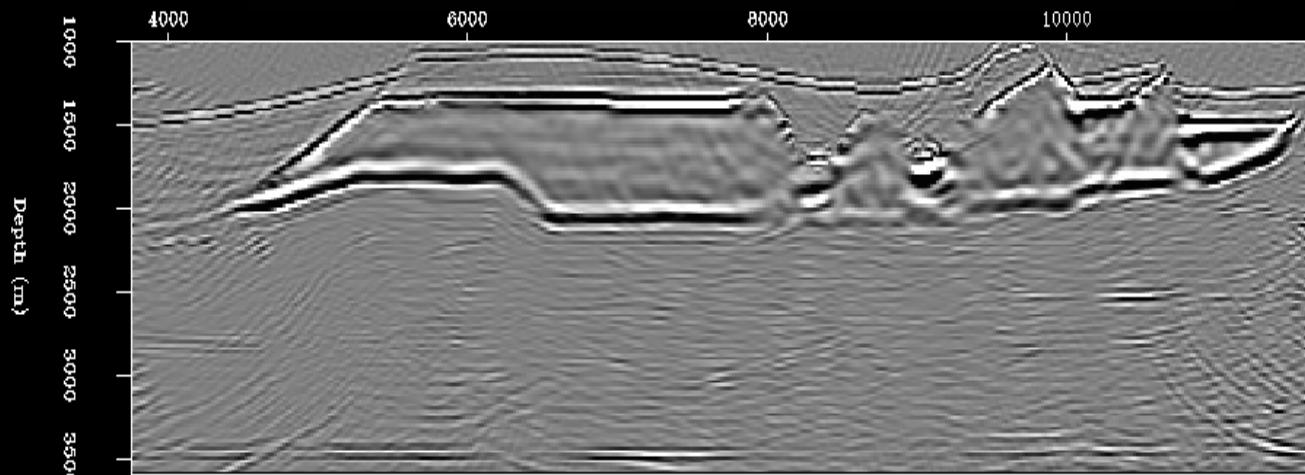
Wavefield Extrapolated Zero-offset Impulse

Schlumberger Private

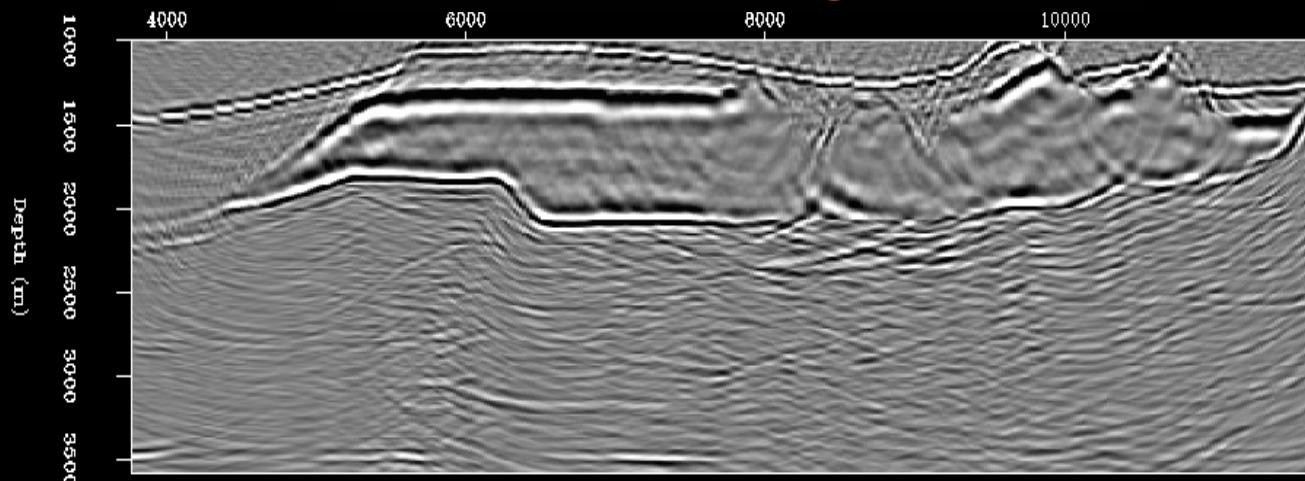
SEG/EAGE salt data set - Crossline



Wavefield-continuation migration



Kirchhoff migration



Beam Migration $y=375$

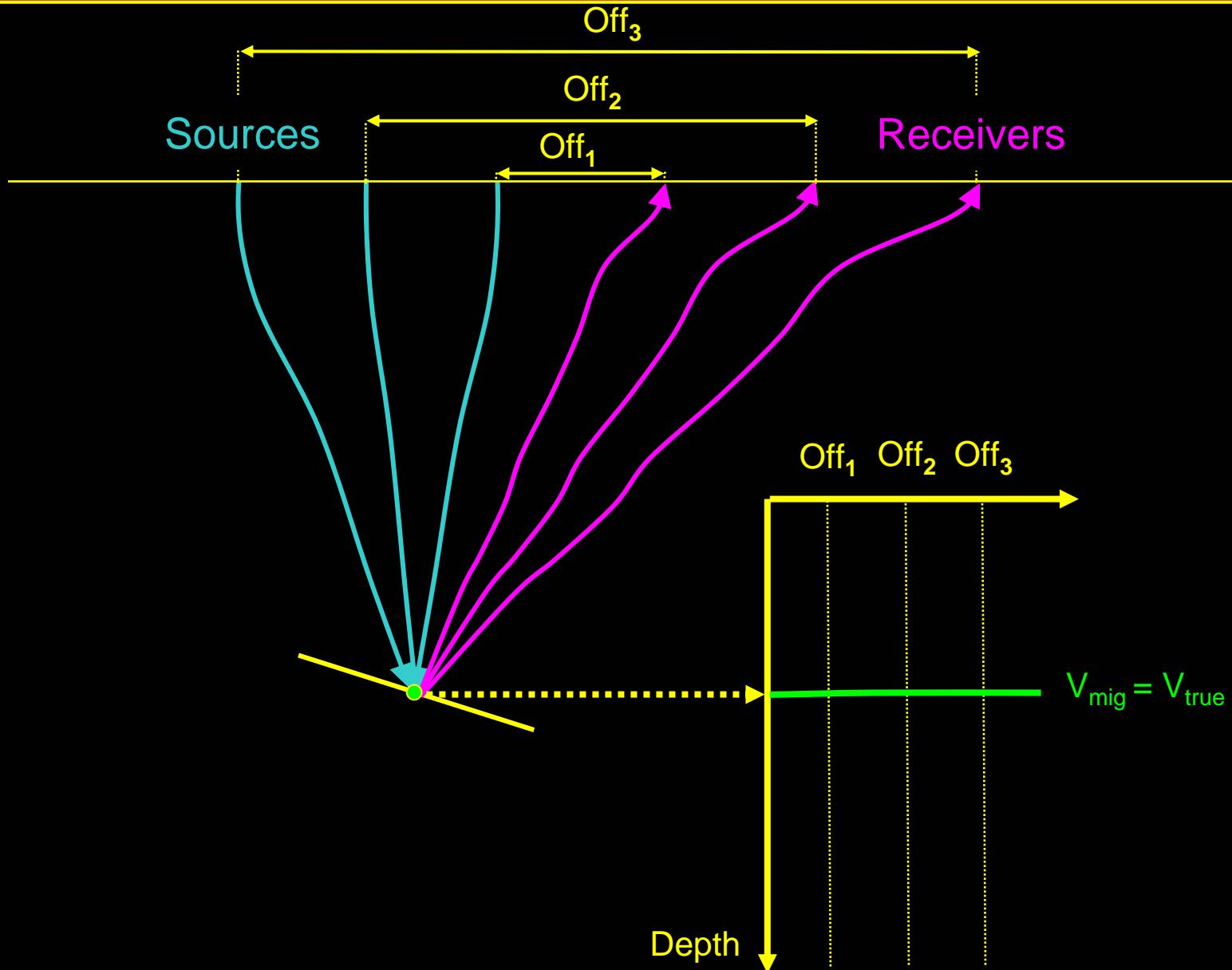
Schlumberger Private

Outline

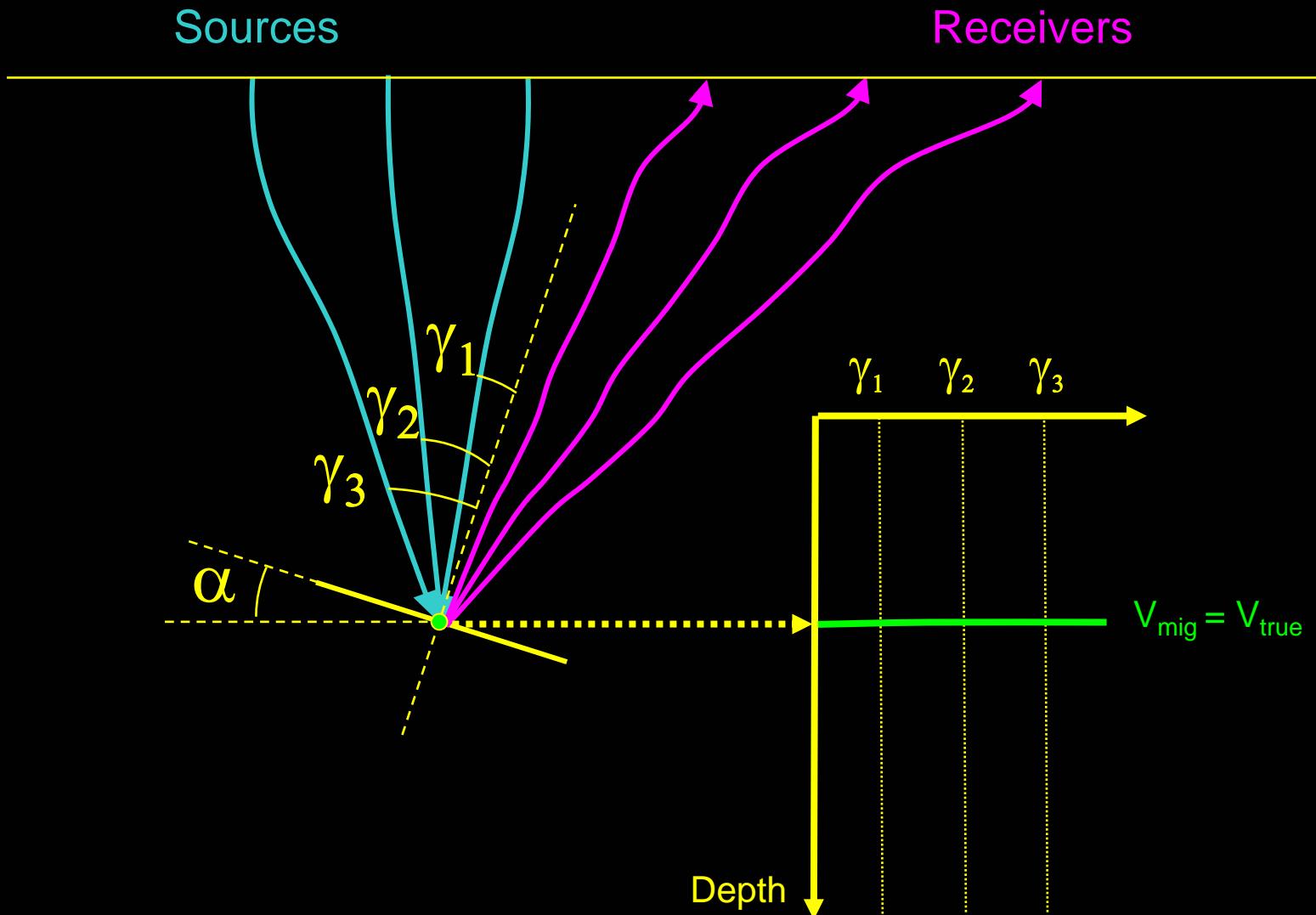
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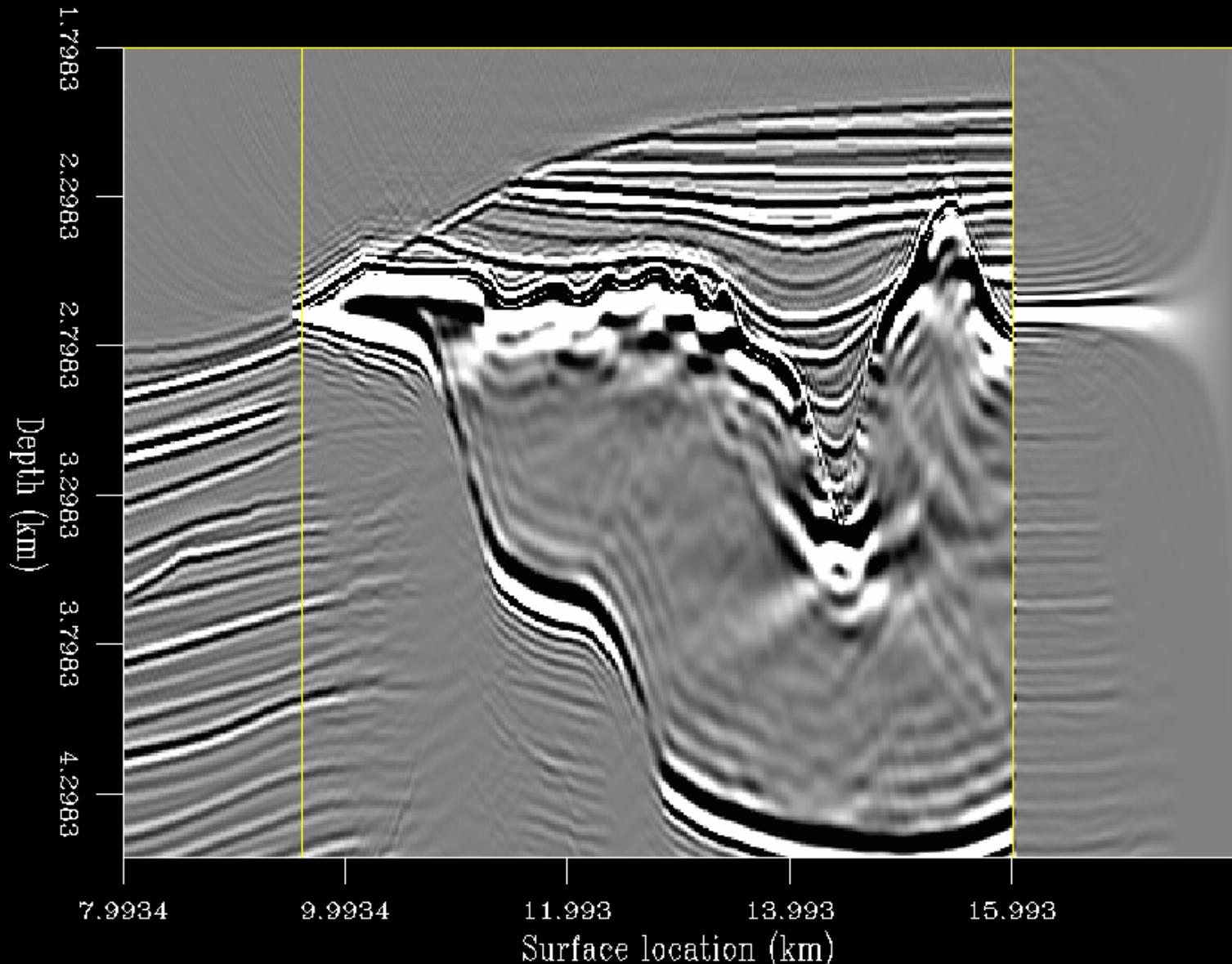
Offset Domain CIG (Kirchhoff)



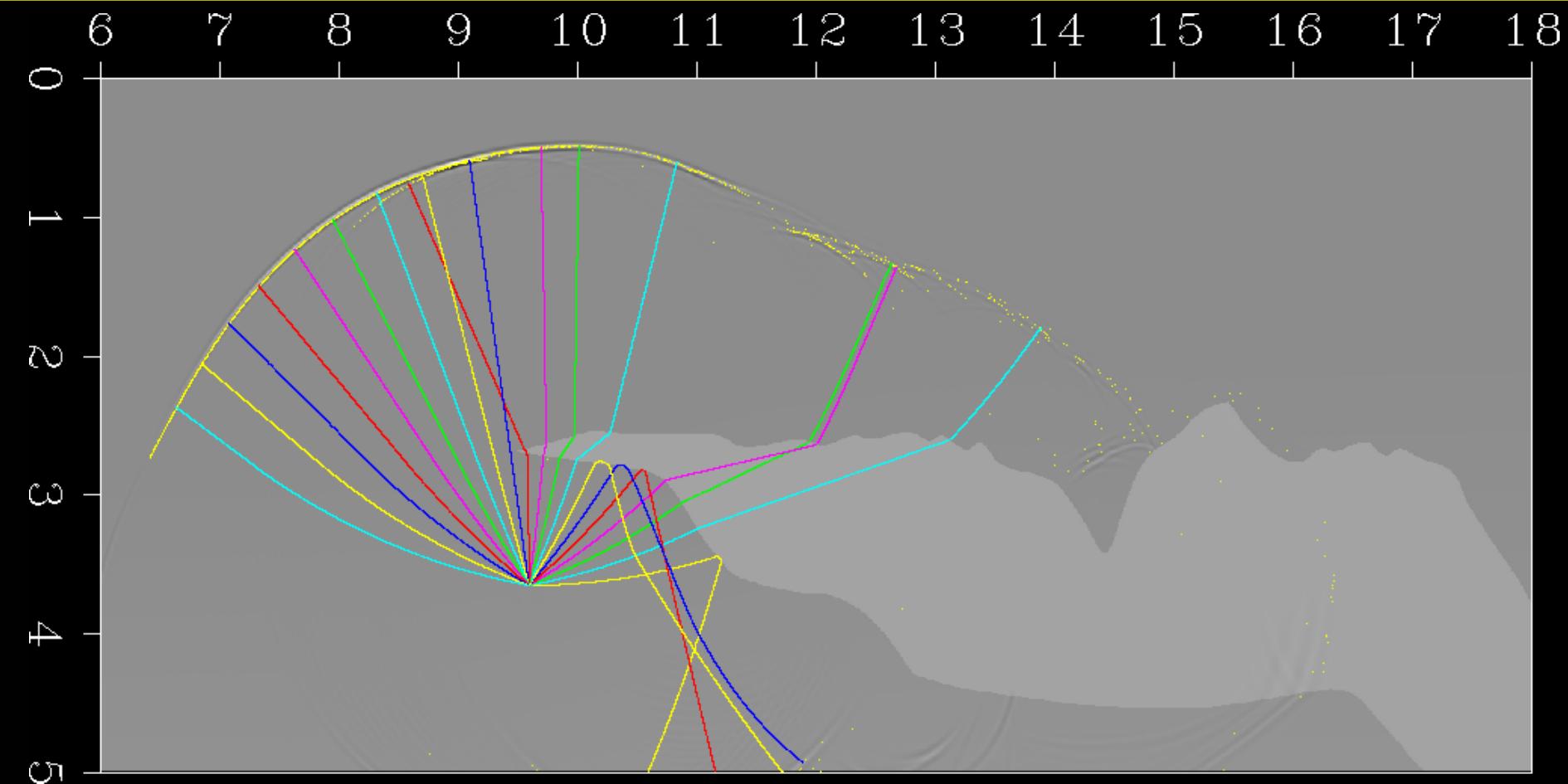
Angle Domain CIG (wavefield continuation)



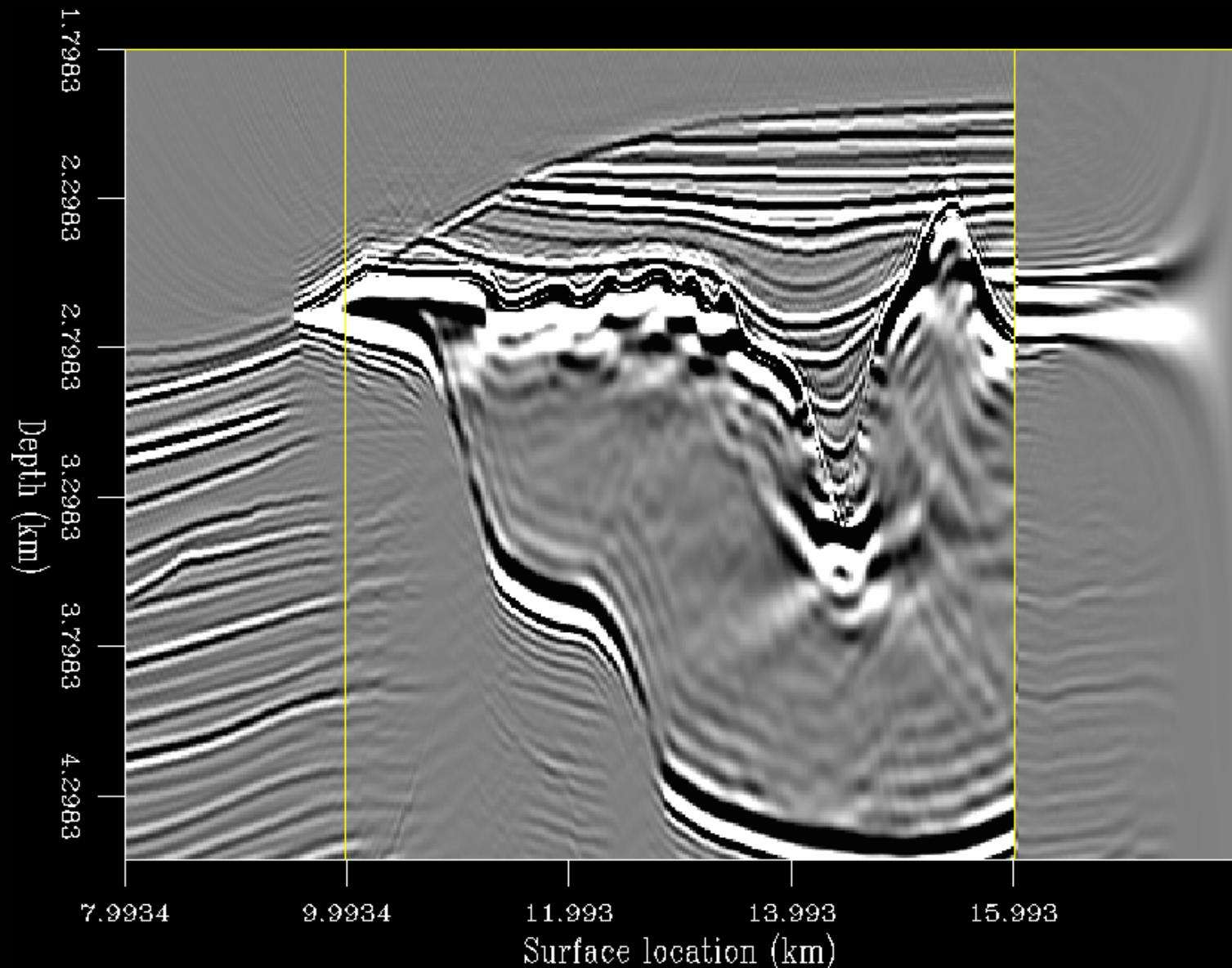
Sigsbee data - Well illuminated CIG



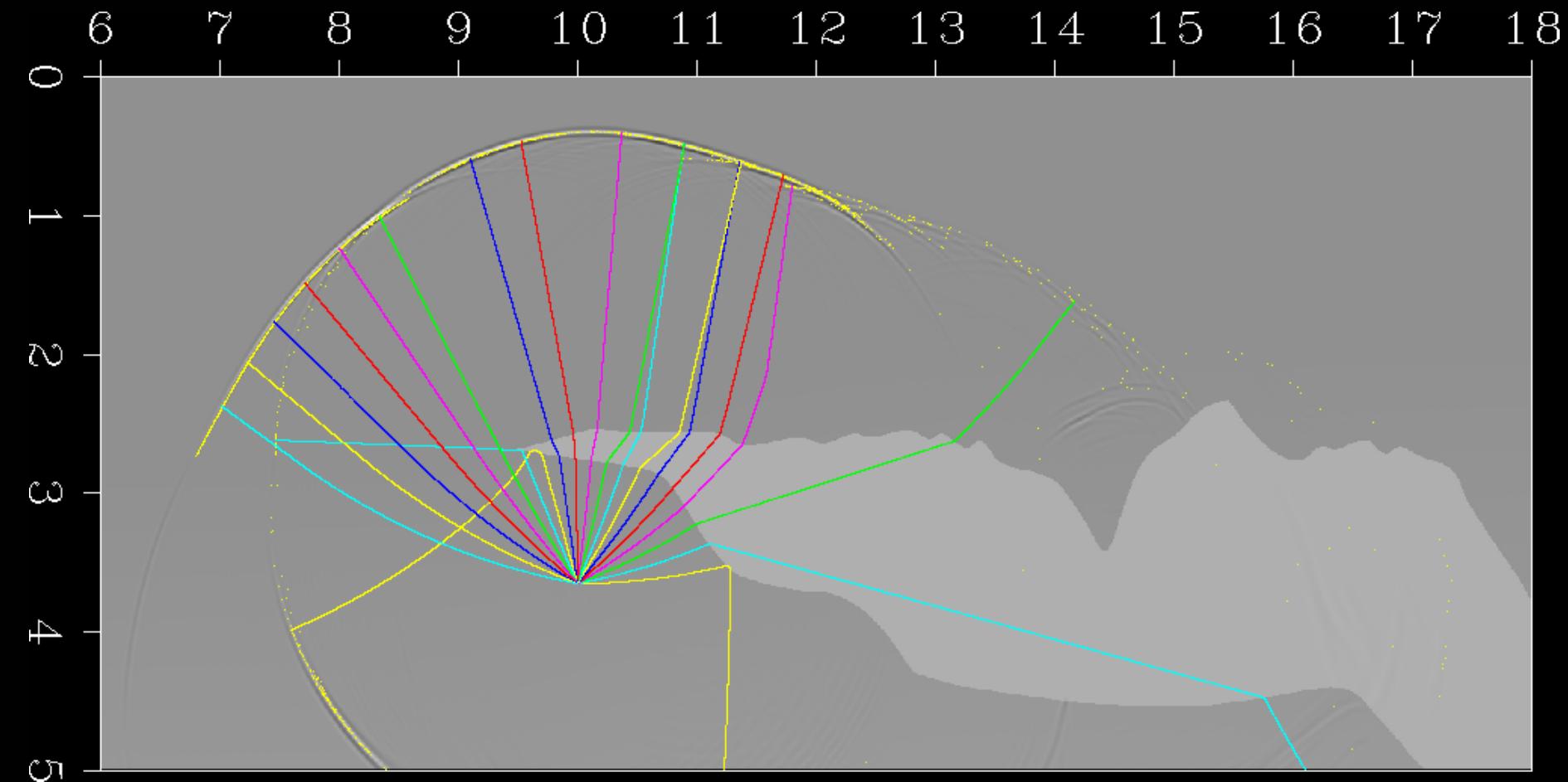
Sigsbee data - Well illuminated CIG



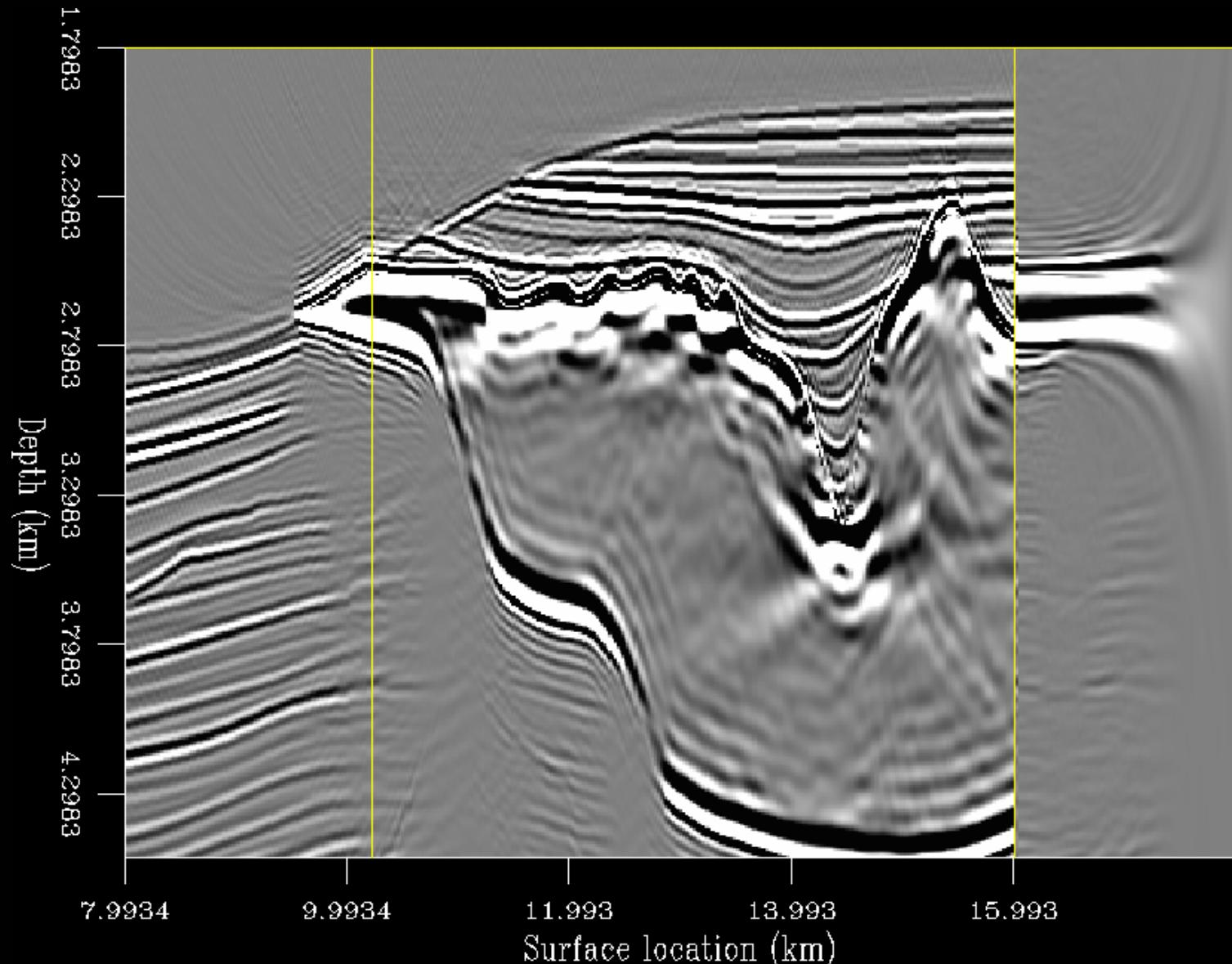
Sigsbee data - Partially illuminated CIG



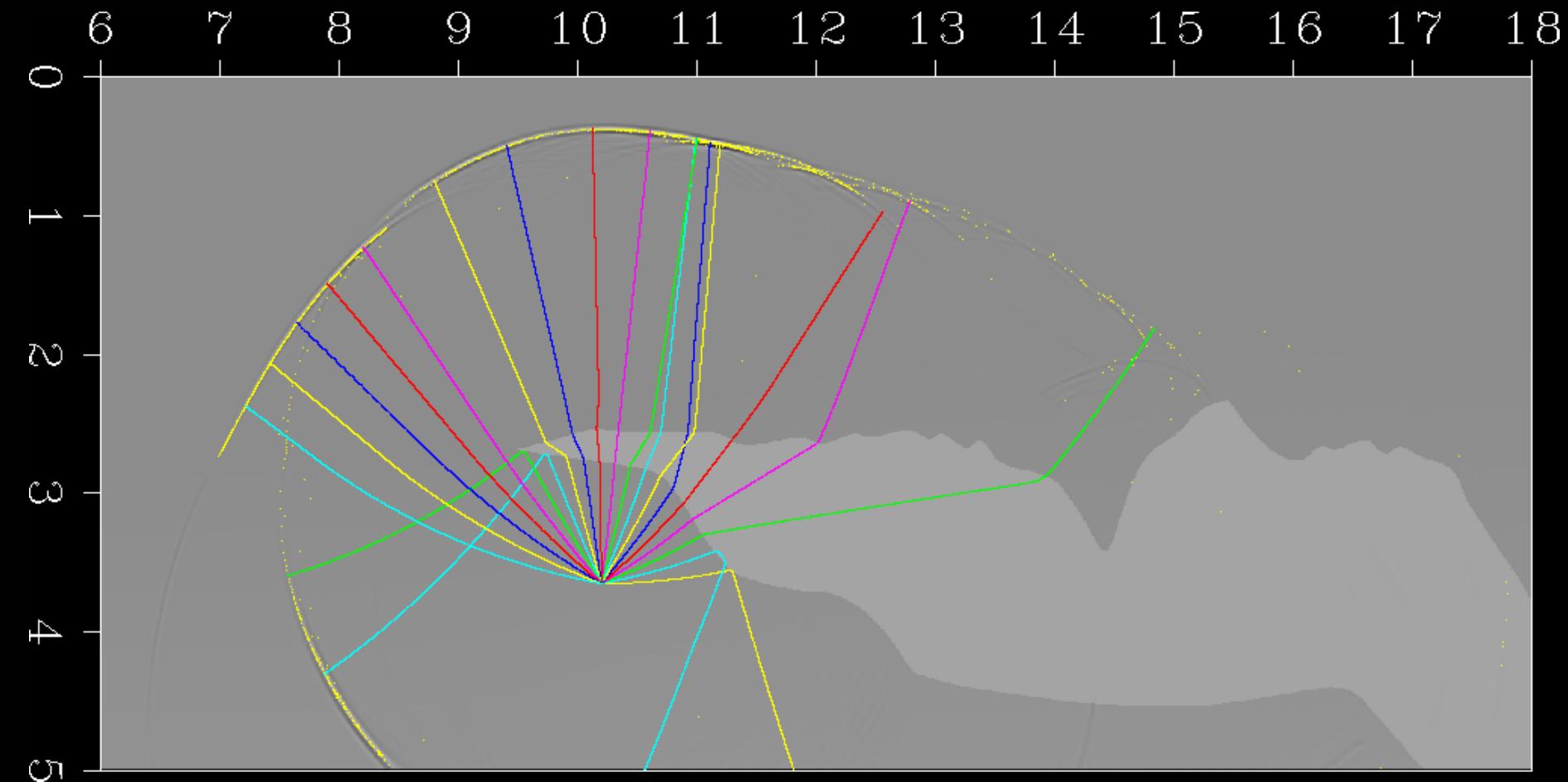
Sigsbee data - Partially illuminated CIG



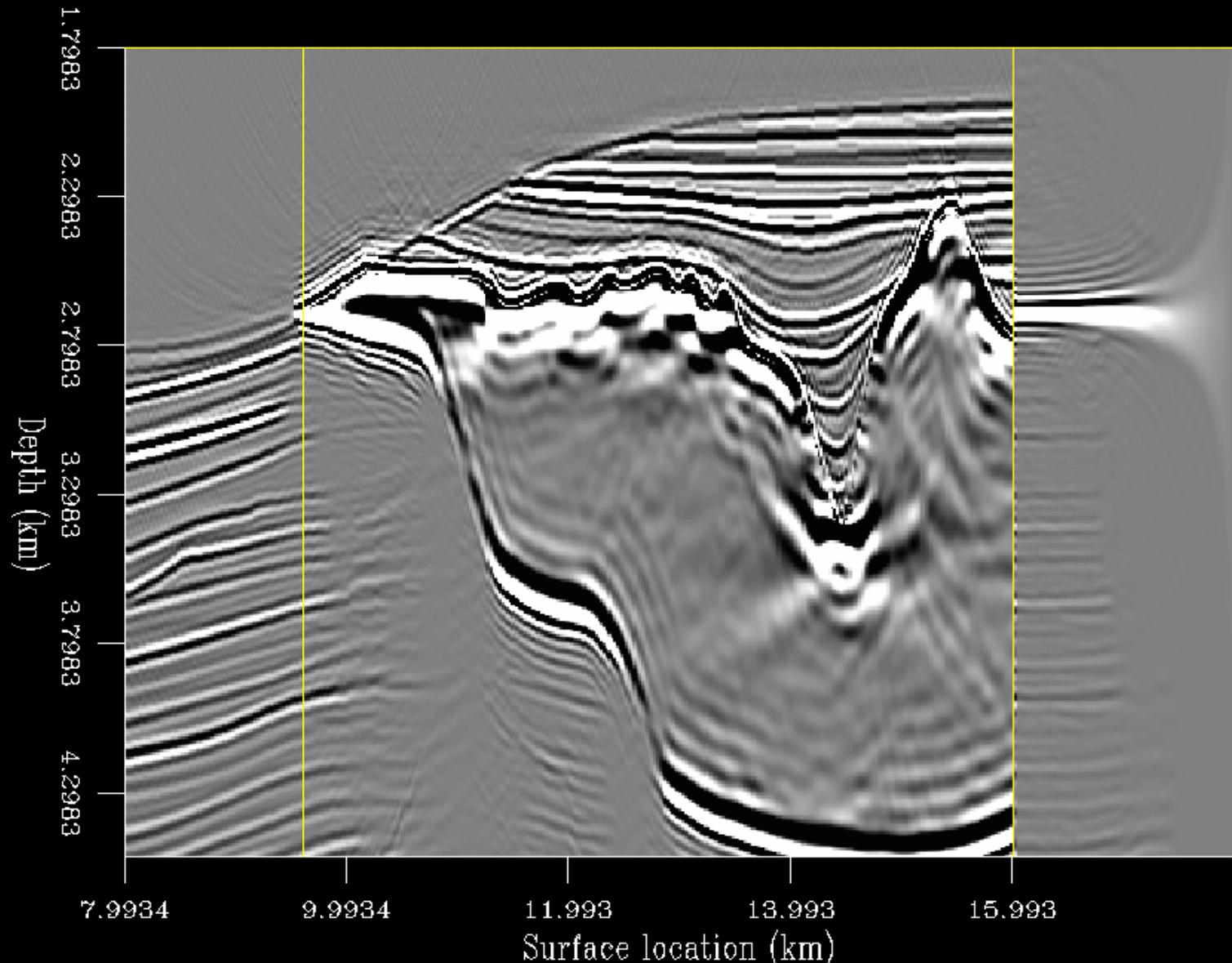
Sigsbee data - Poorly illuminated CIG



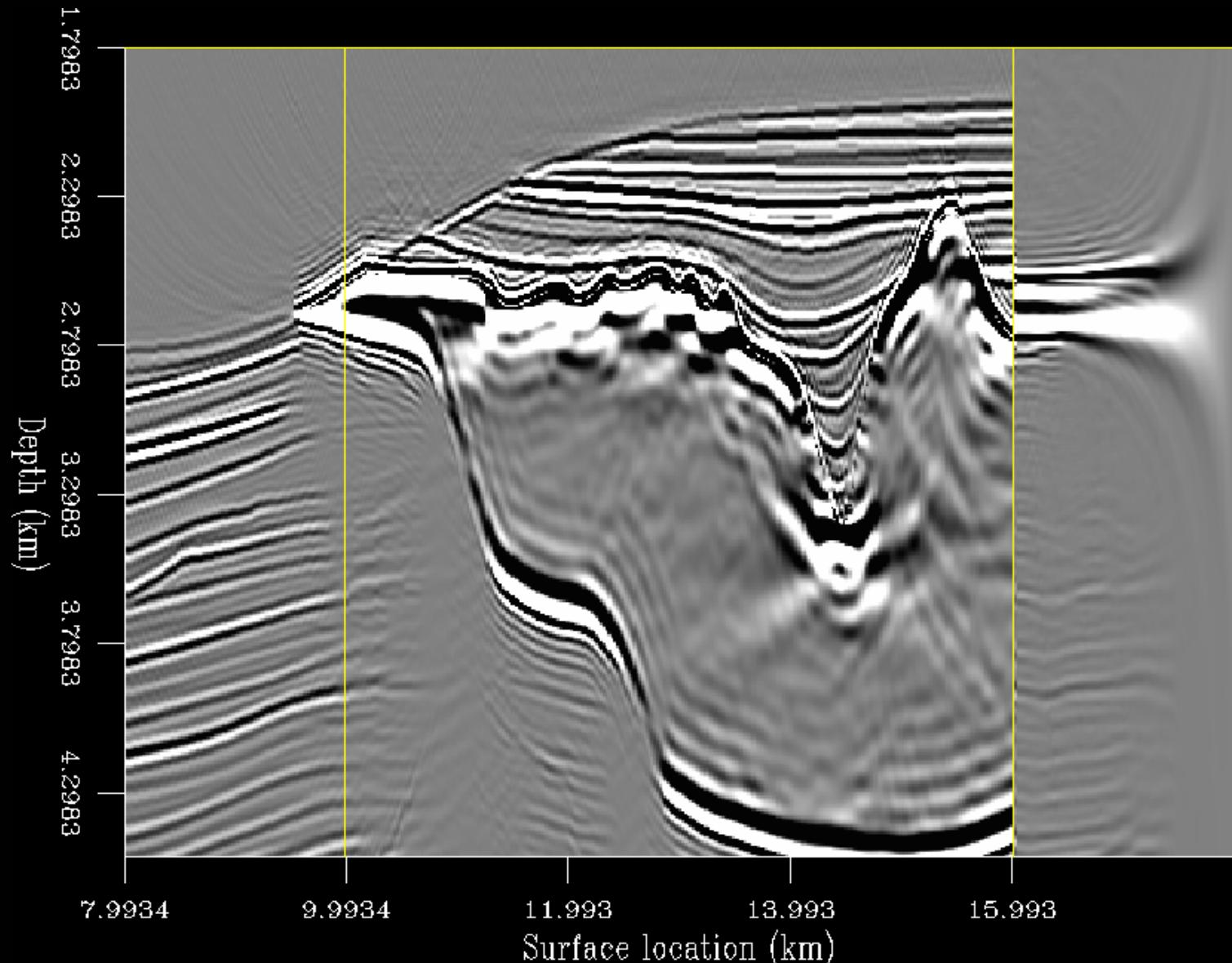
Sigsbee data - Poorly illuminated CIG



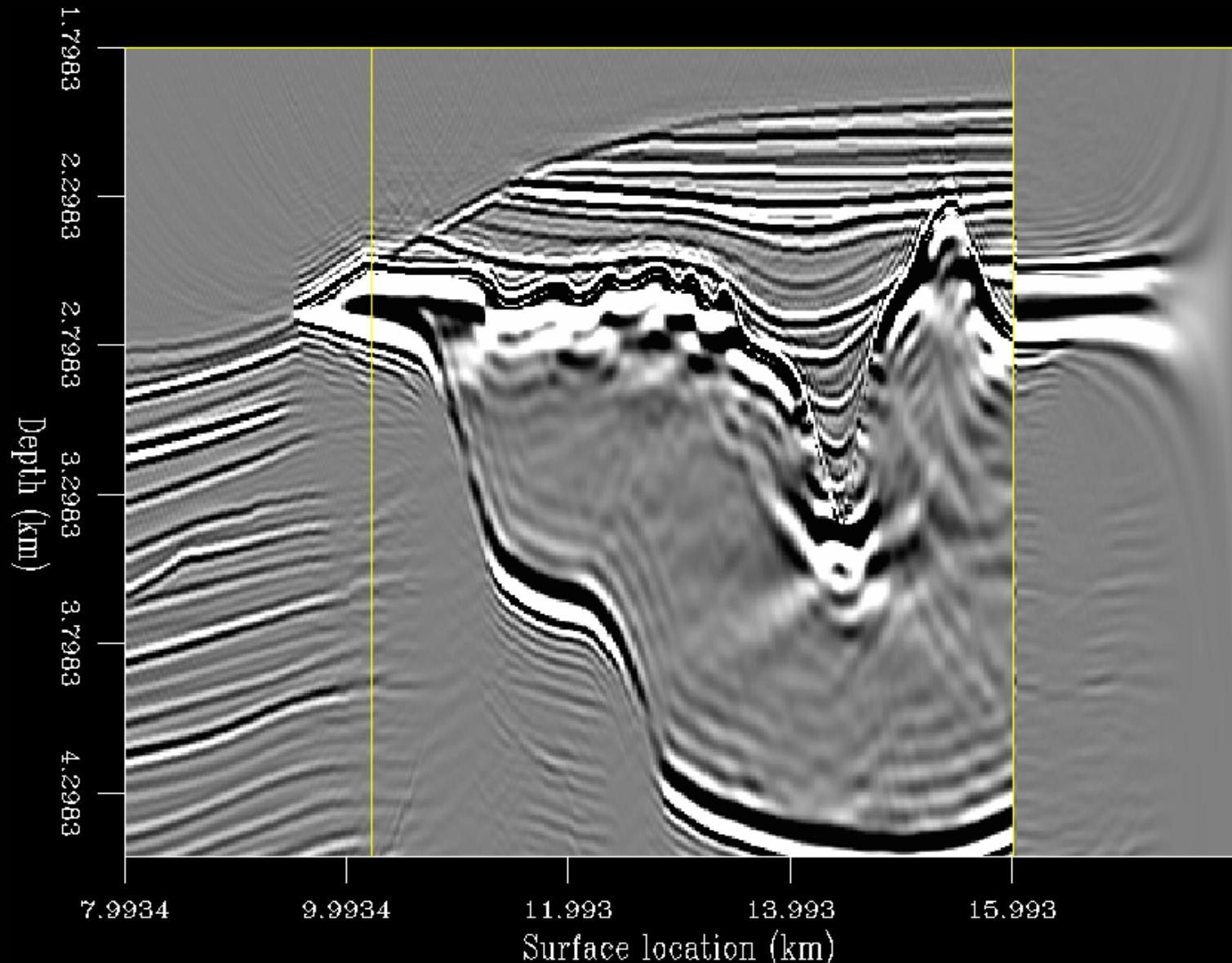
Sigsbee data - Well illuminated CIG



Sigsbee data - Partially illuminated CIG



Sigsbee data - Poorly illuminated CIG



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Migration => Normalized Migration

- ❖ Migration

$$m = \mathbf{L}^* d$$

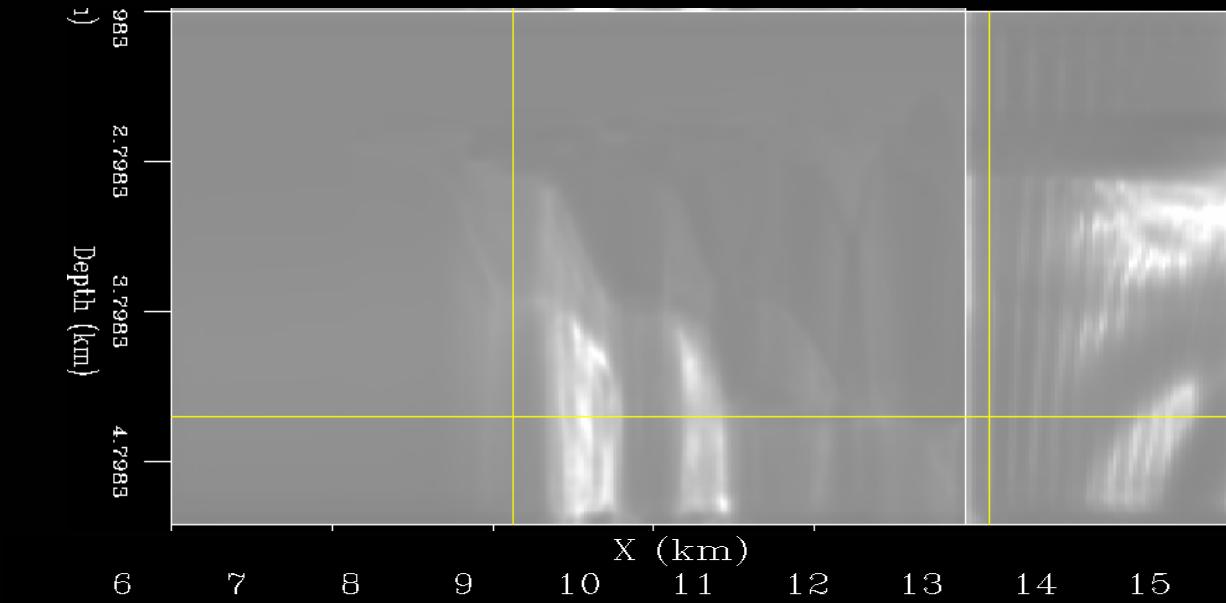
- ❖ Least-Squares Migration

$$m = (\mathbf{L}^* \mathbf{L})^{-1} \mathbf{L}^* d$$

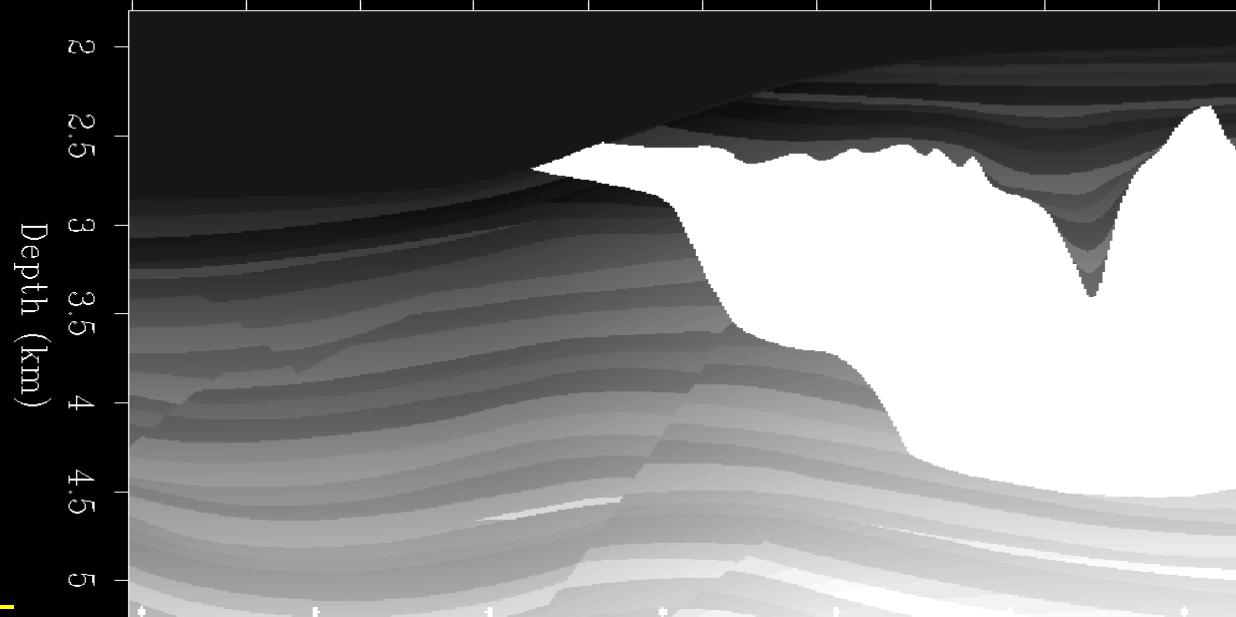
- ❖ Normalized Migration

$$m = \mathbf{W}^{-1} \mathbf{L}^* d$$

Normalized Migration



Normalization
factor
W



Velocity
model

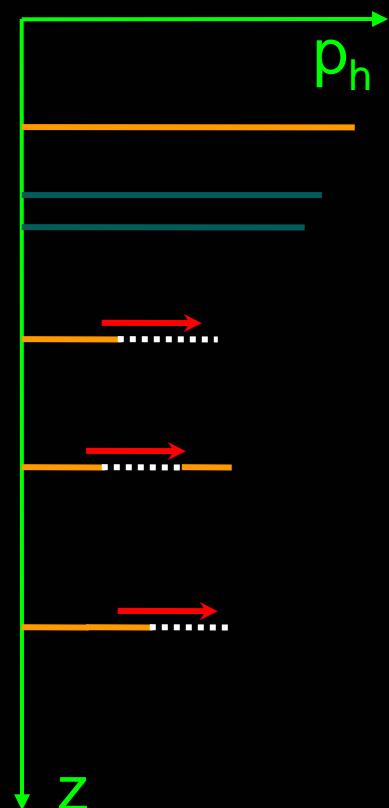
- ❖ Least-Squares Migration

$$m = (\mathbf{L}^* \mathbf{L})^{-1} \mathbf{L}^* d$$

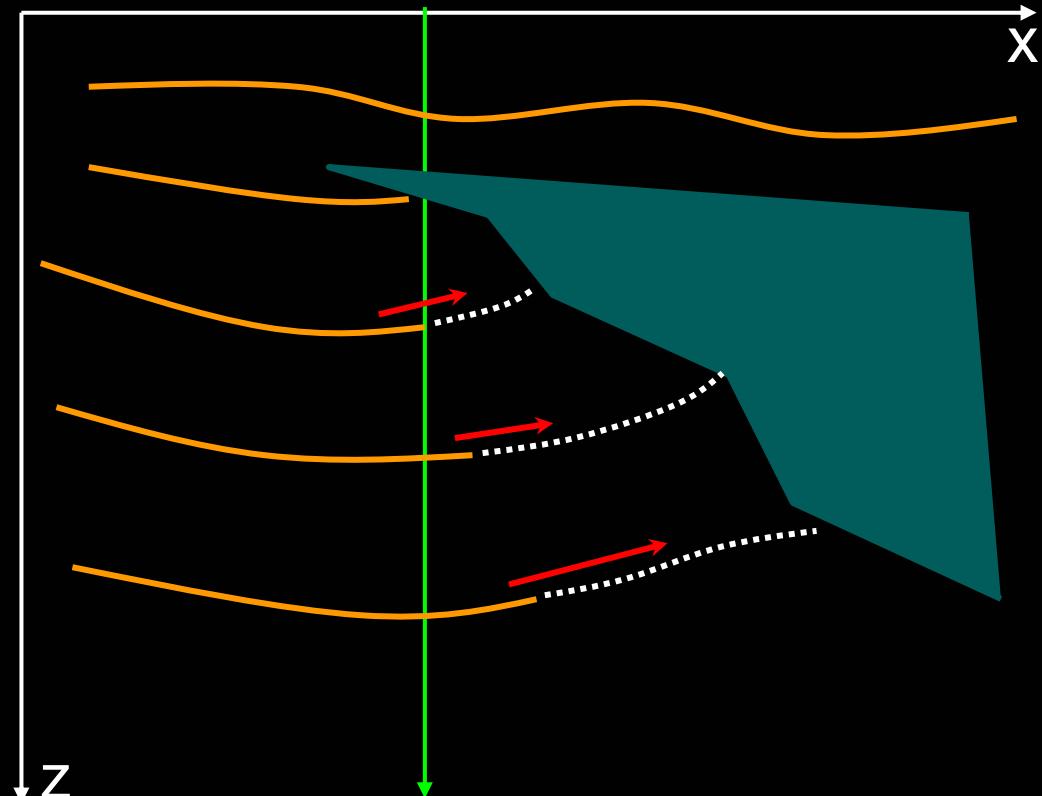
- ❖ Iterative Regularized Inversion

$$m = (\mathbf{L}^* \mathbf{L} + \varepsilon^2 \mathbf{A}^* \mathbf{A})^{-1} \mathbf{L}^* d$$

Regularization operator (A)

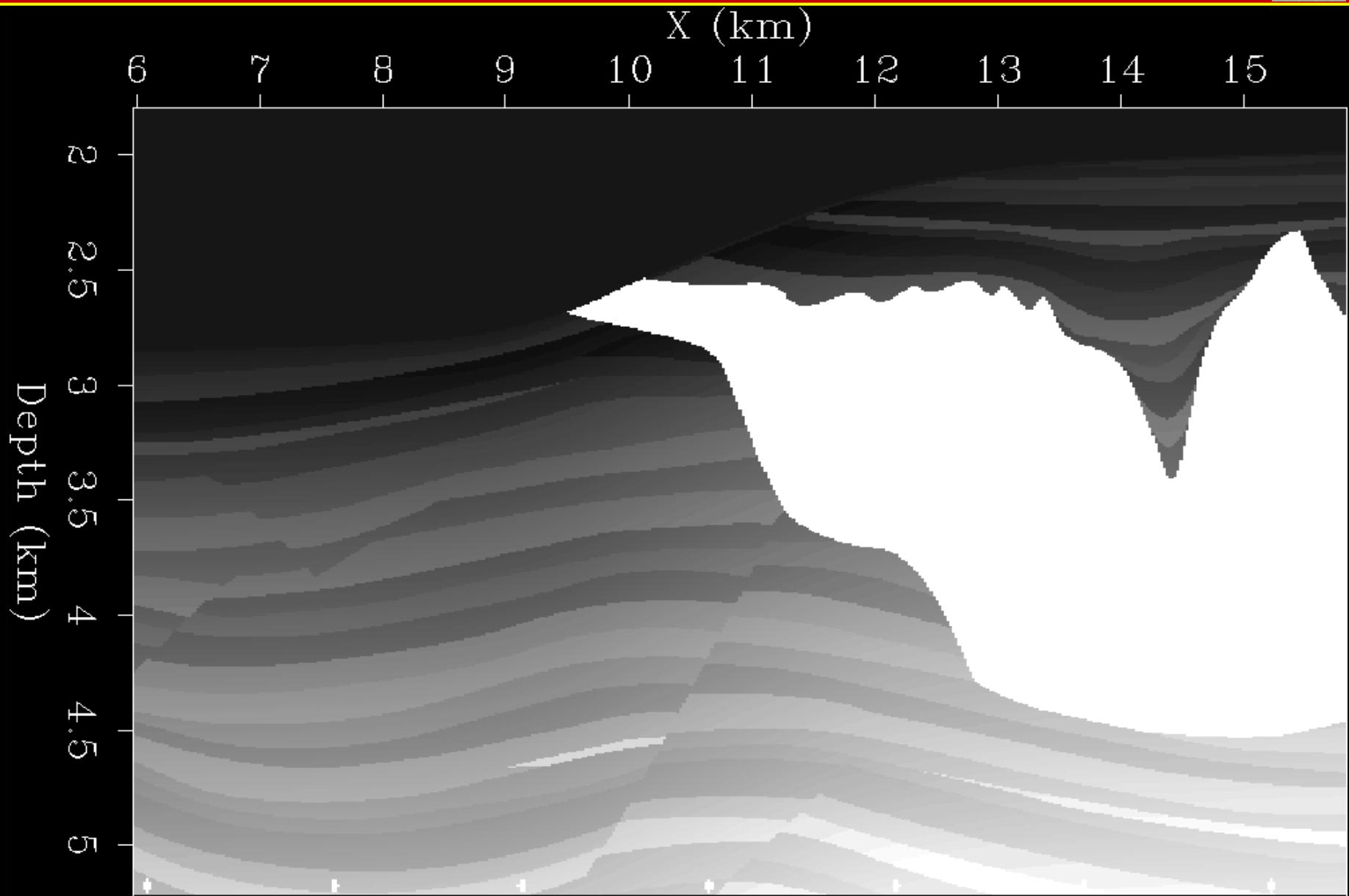


Geophysical regularization

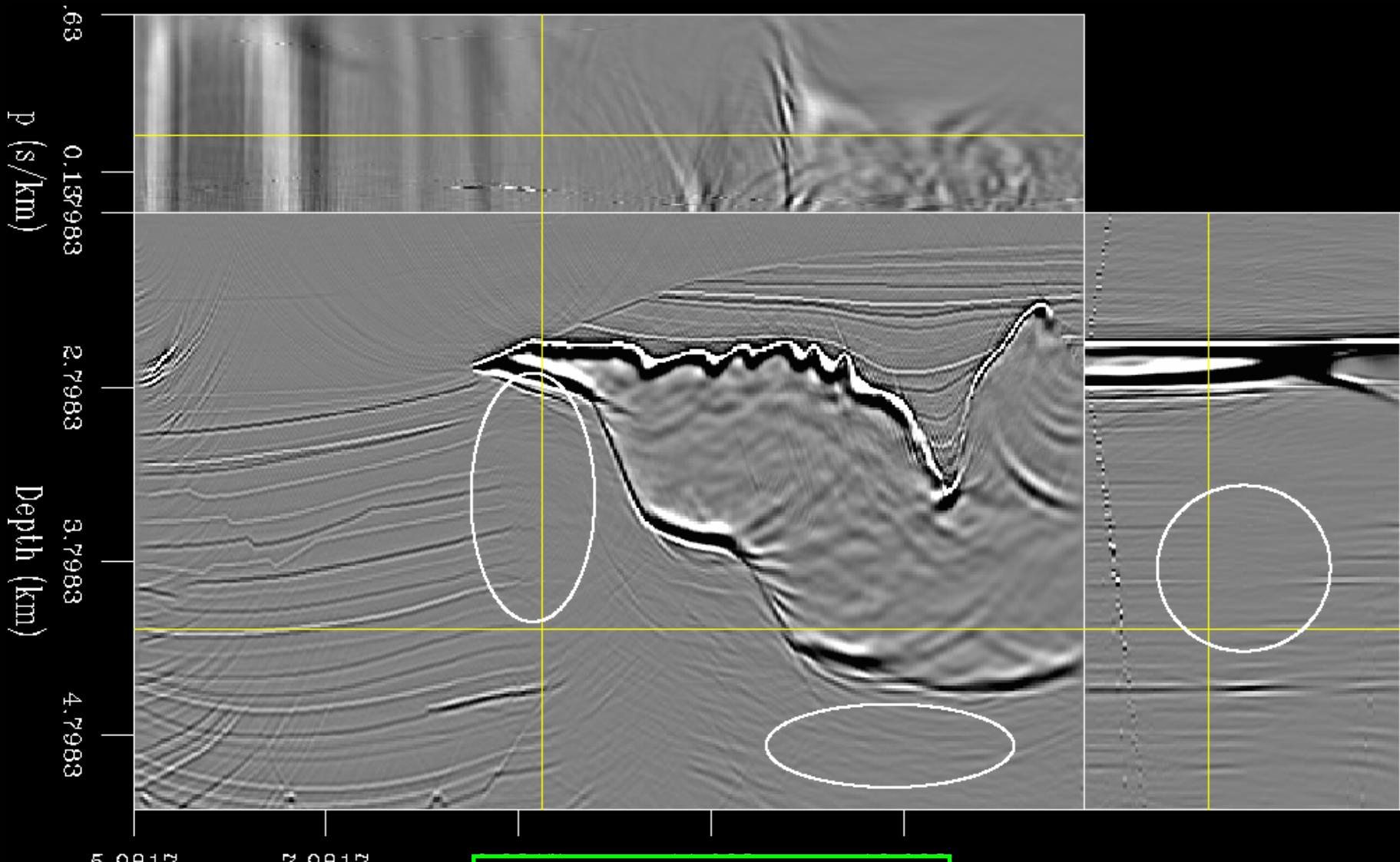


Geological regularization

Layered velocity model

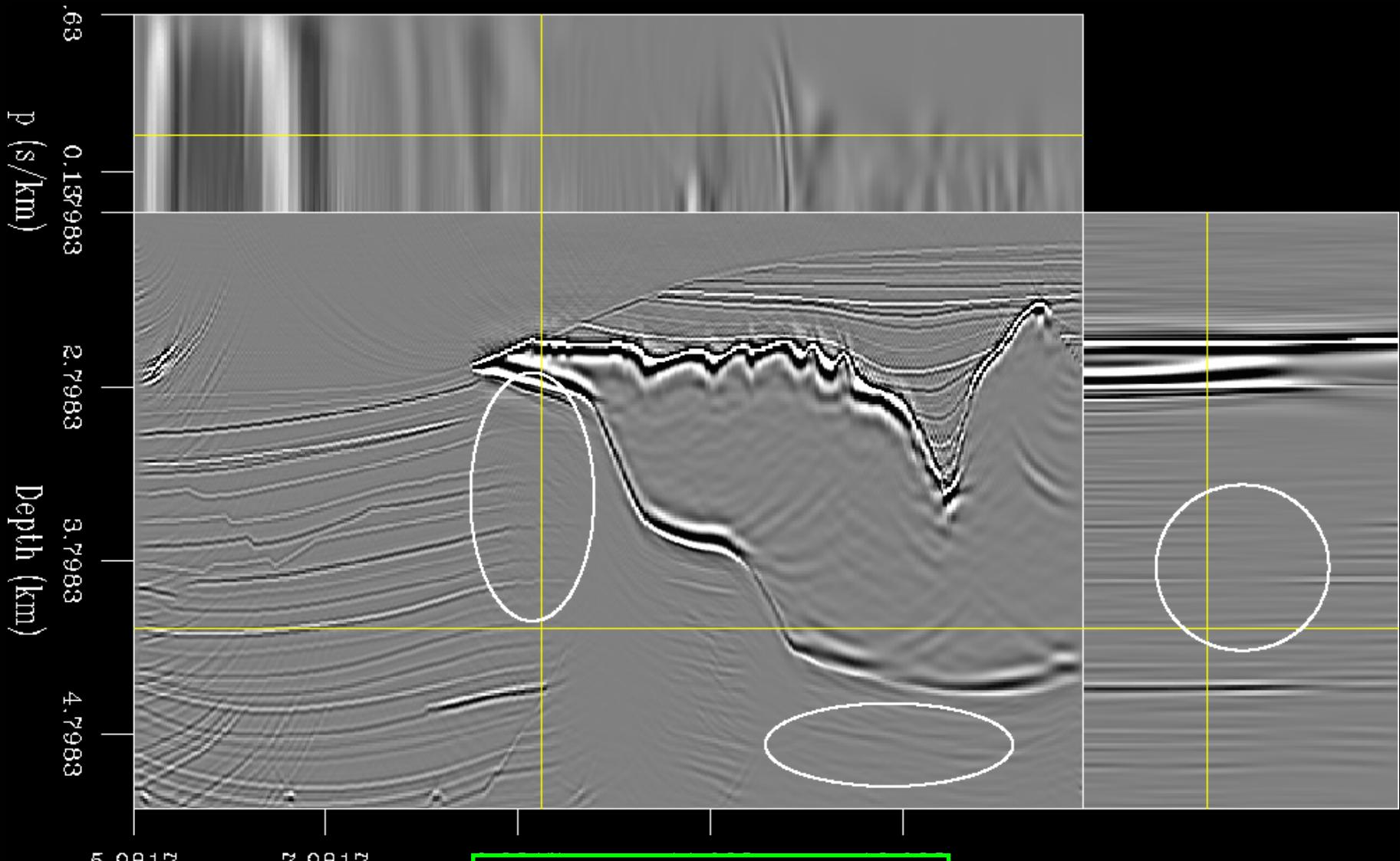


Migration



Courtesy of Marie Clapp (SEP)

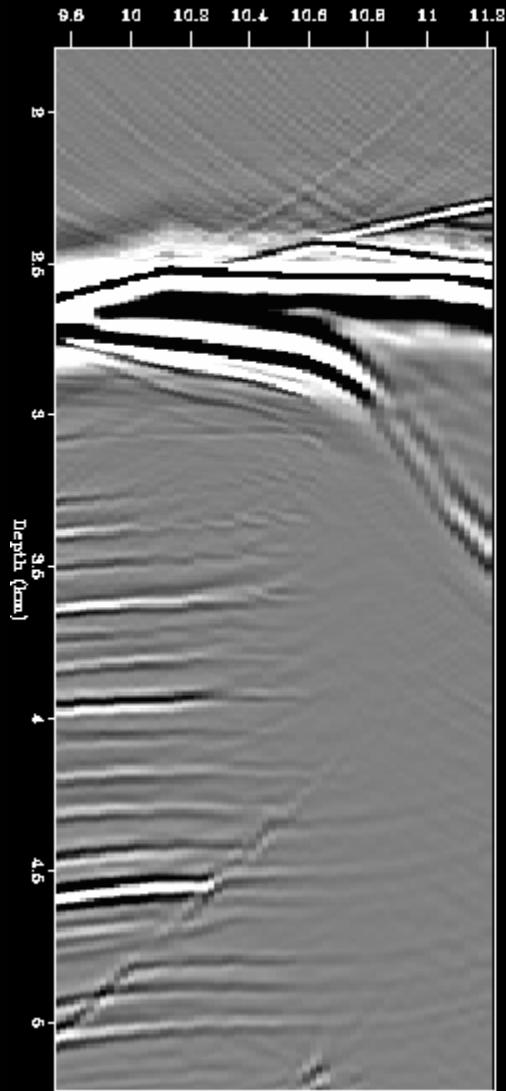
Inversion with Geophysical regularization



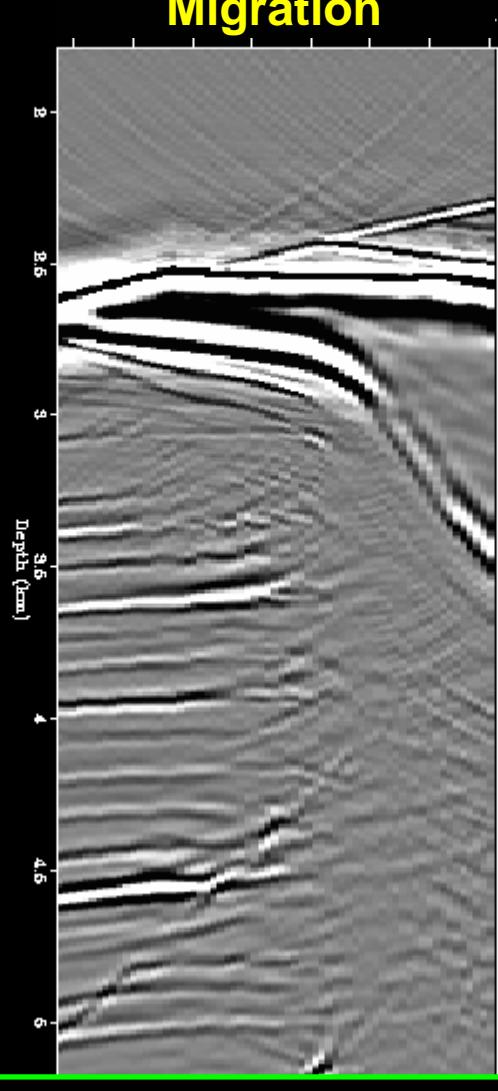
Courtesy of Marie Clapp (SEP)

Inversion with Geophysical regularization

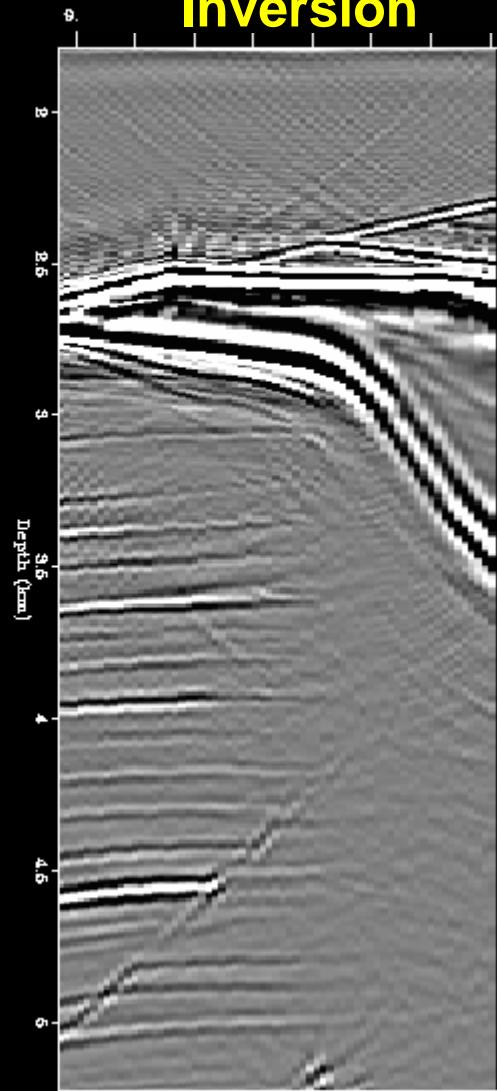
Migration



Normalized
Migration



Regularized
Inversion

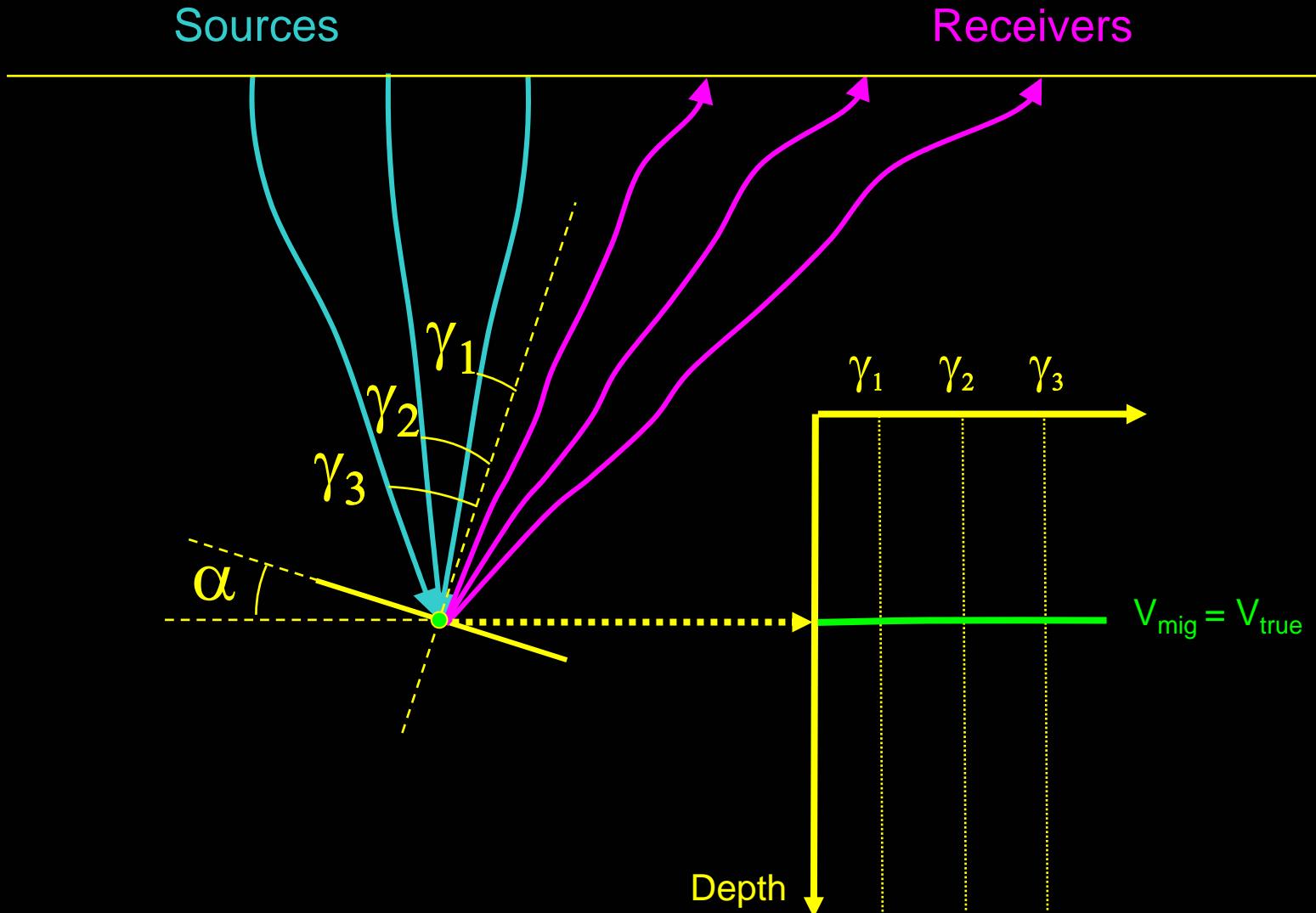


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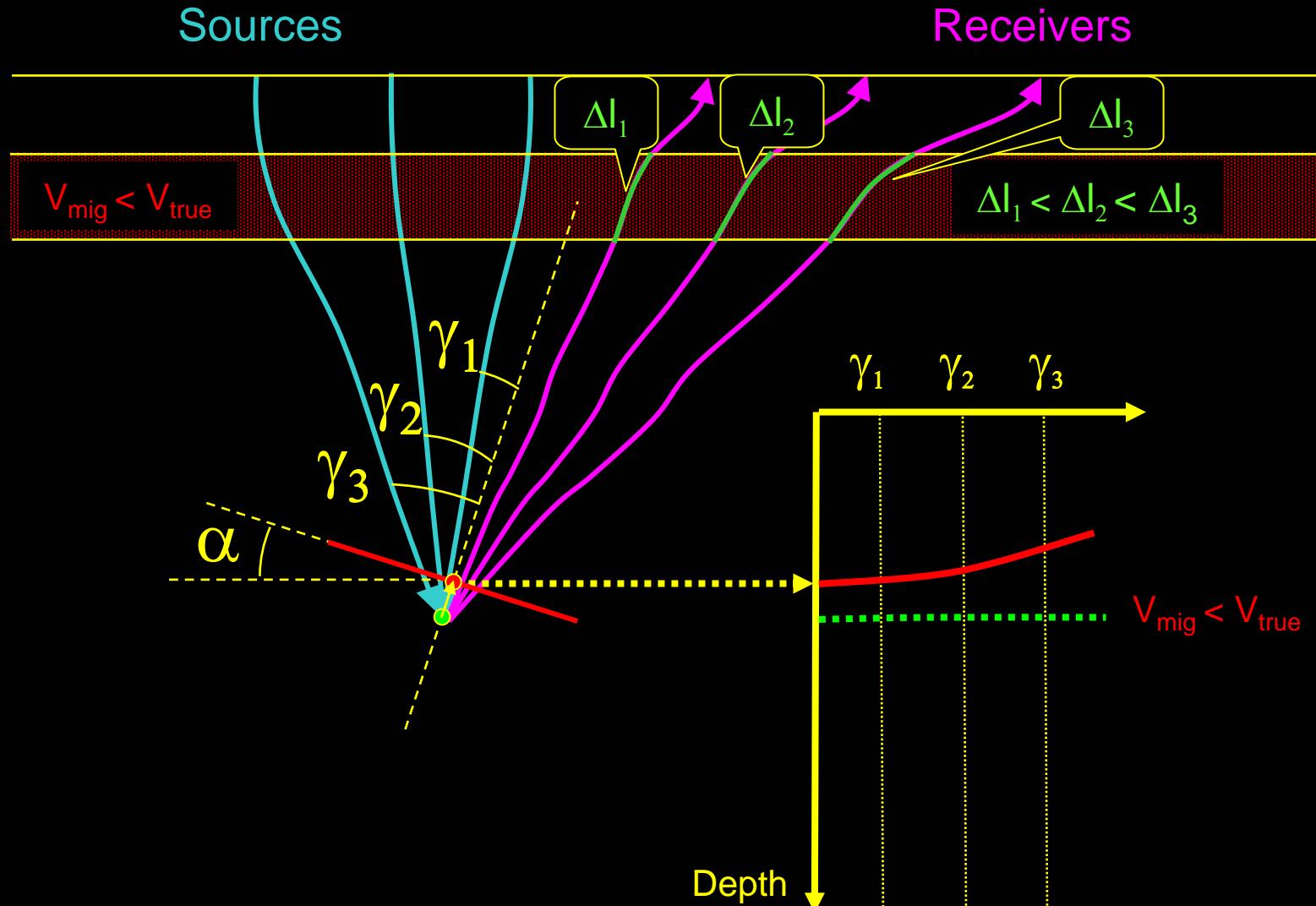
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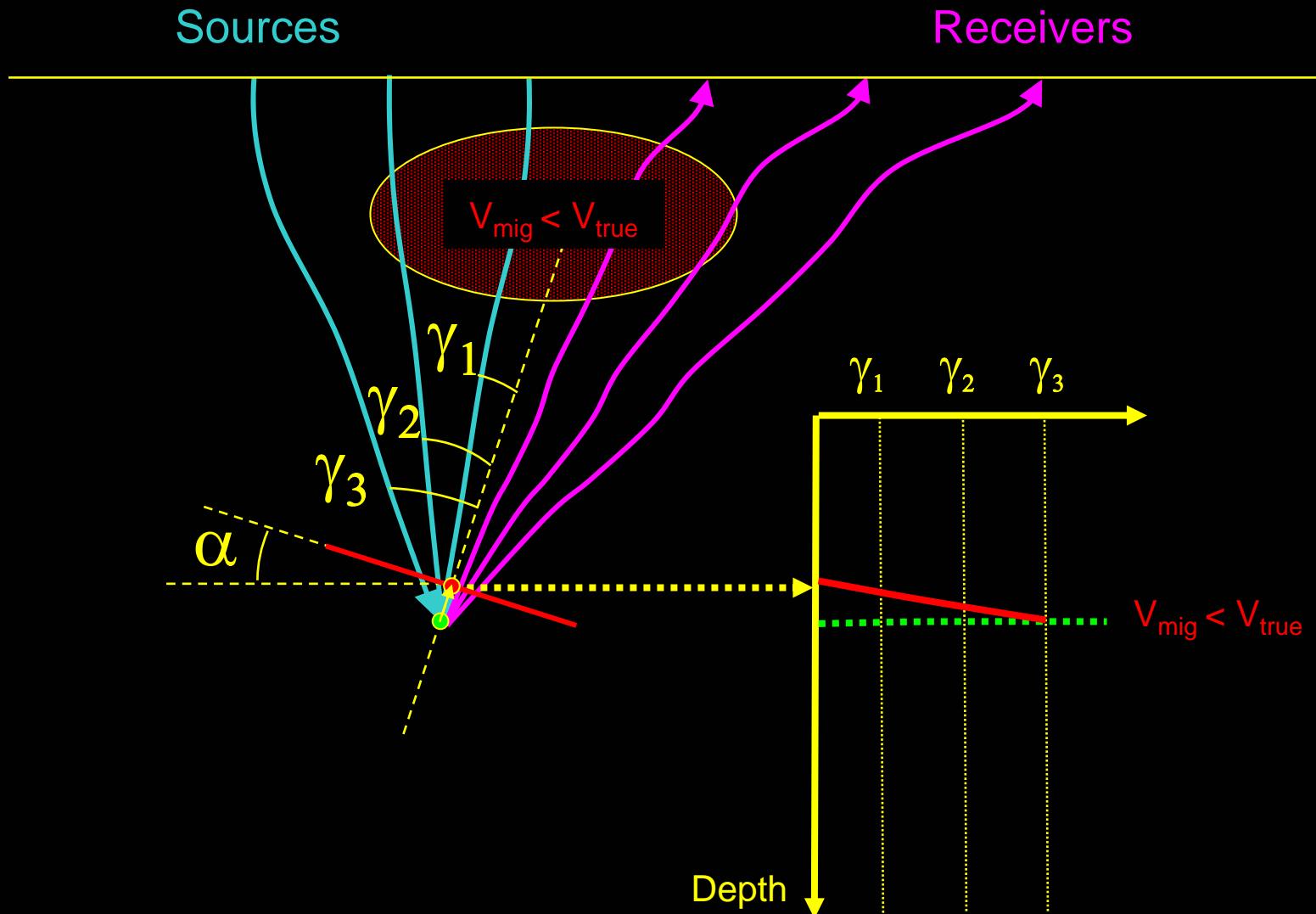
ADCIGs with correct velocity



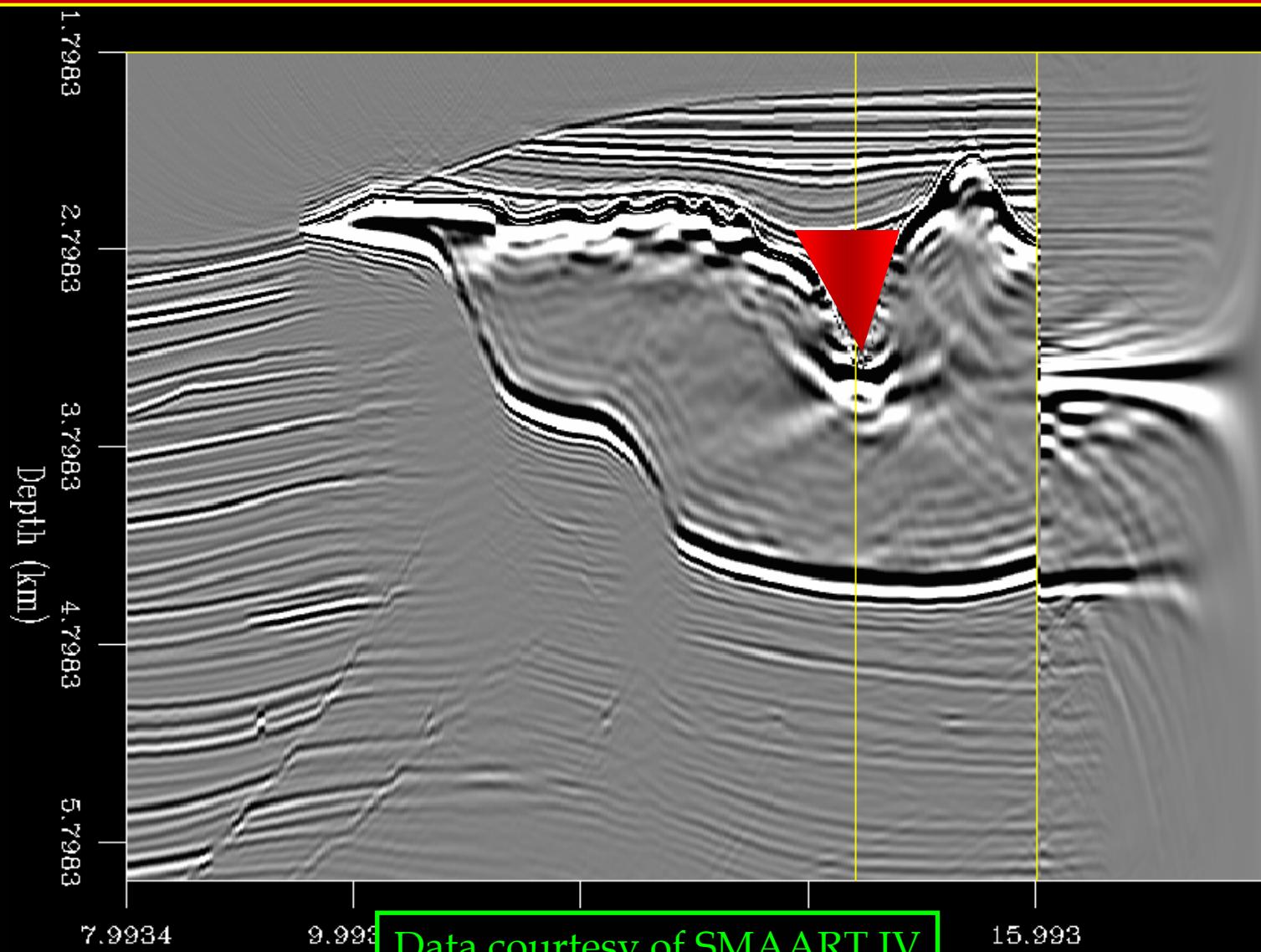
ADCIGs and velocity errors



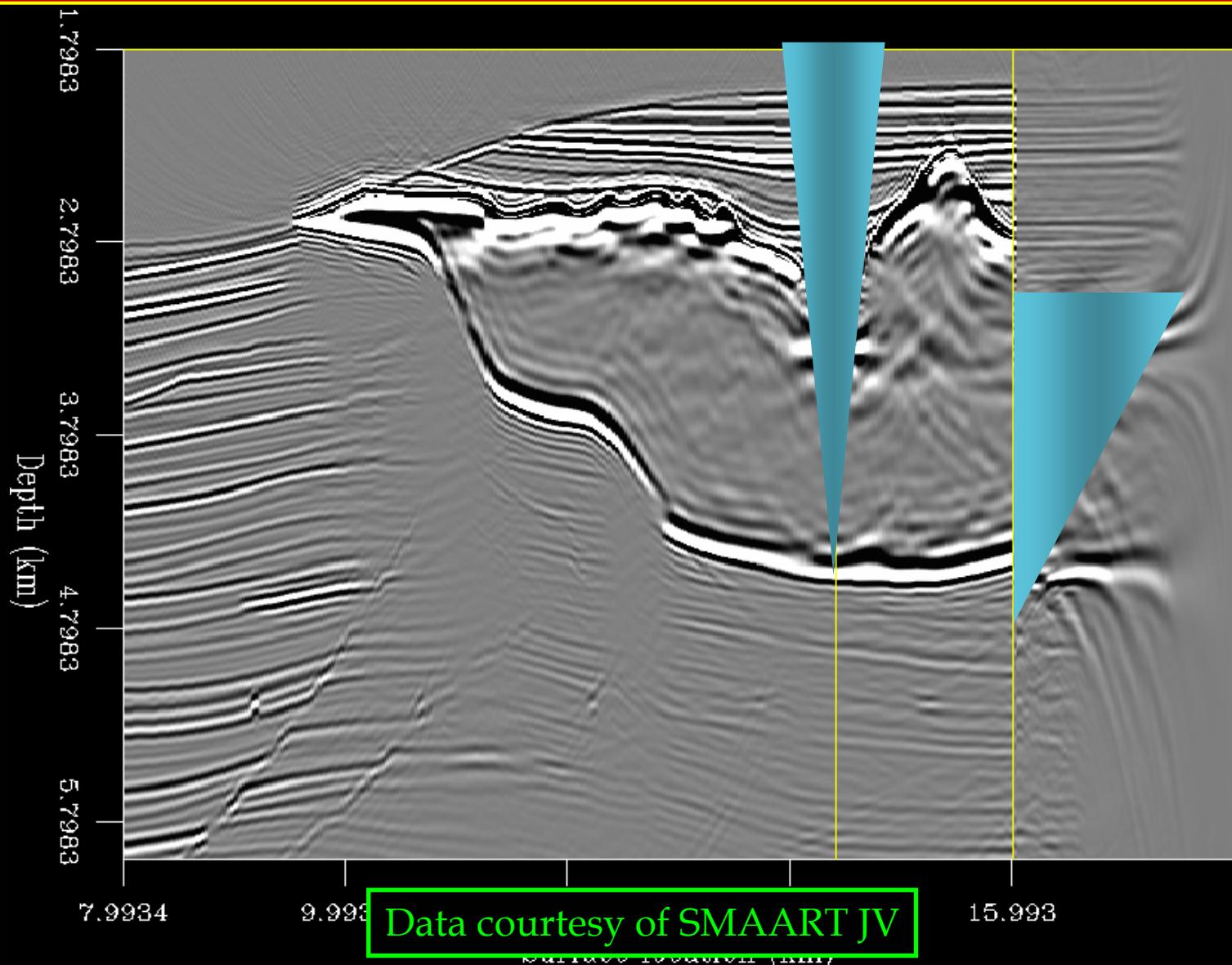
ADCIGs and local velocity errors



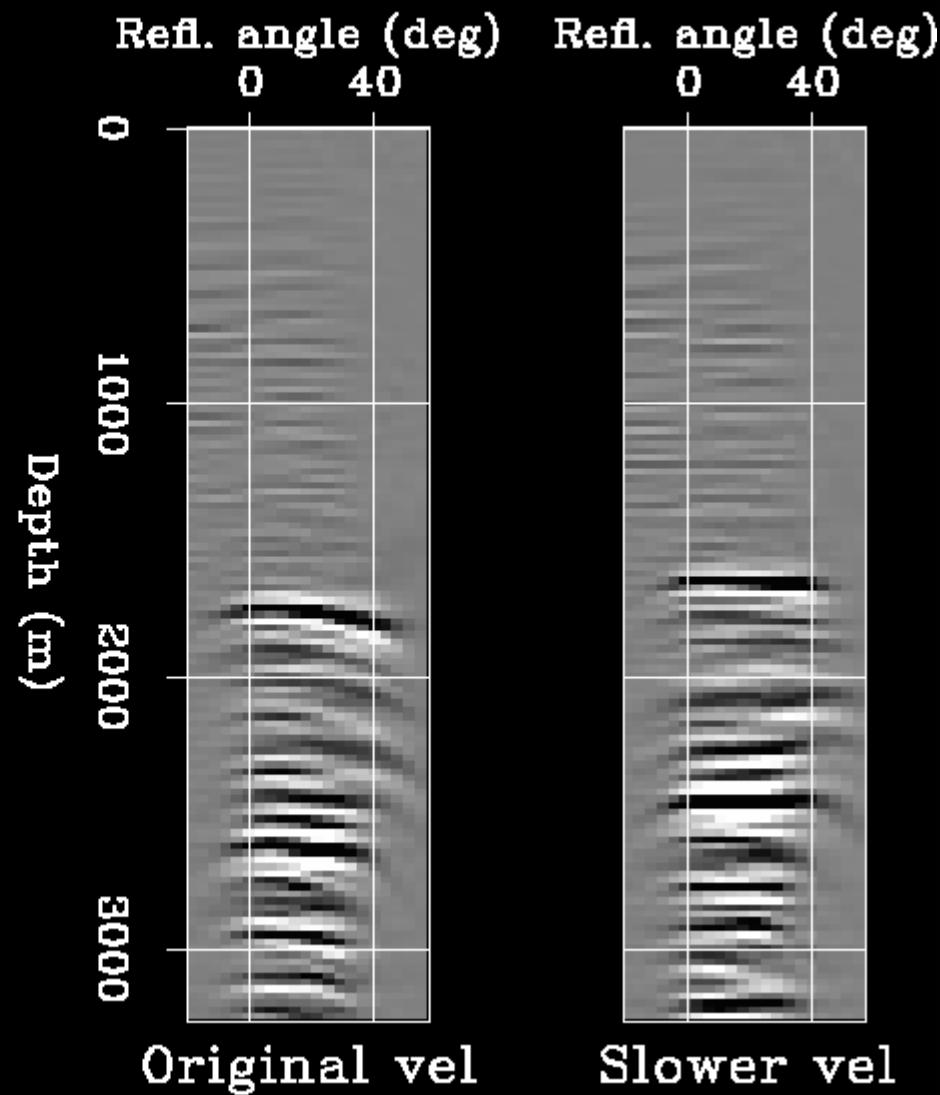
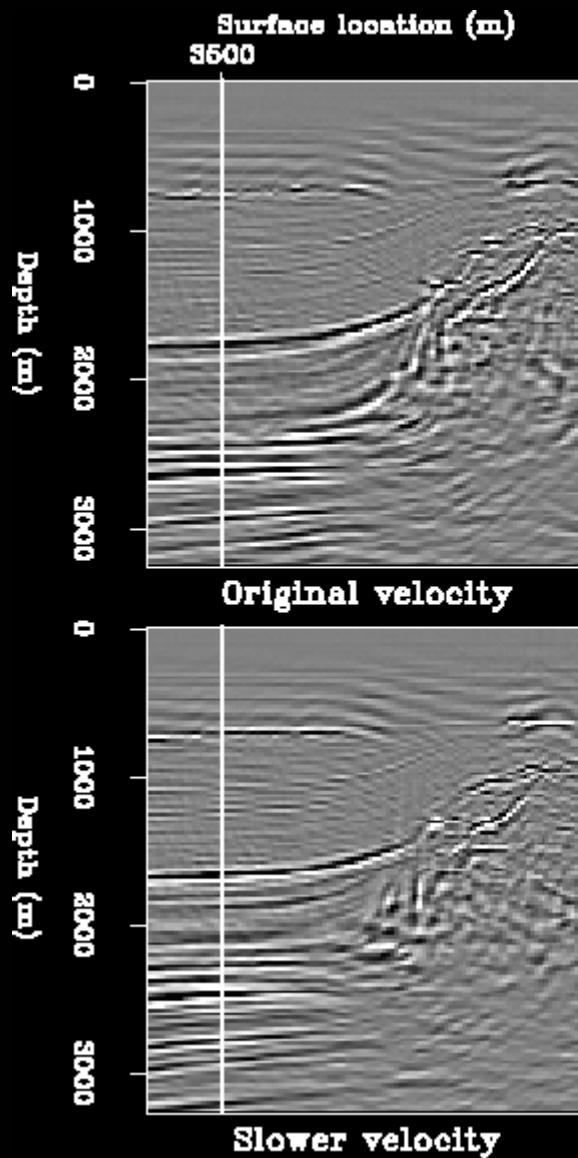
Sigsbee data - Correct velocity



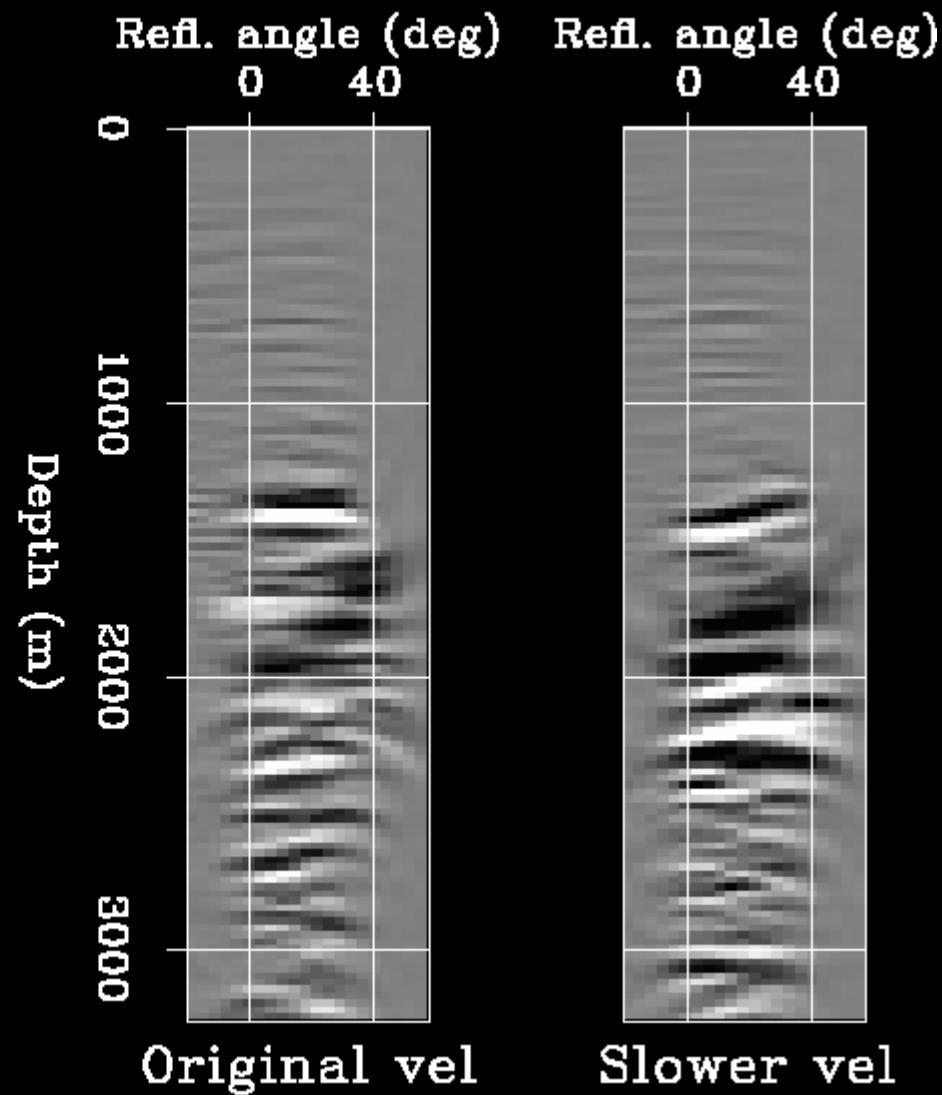
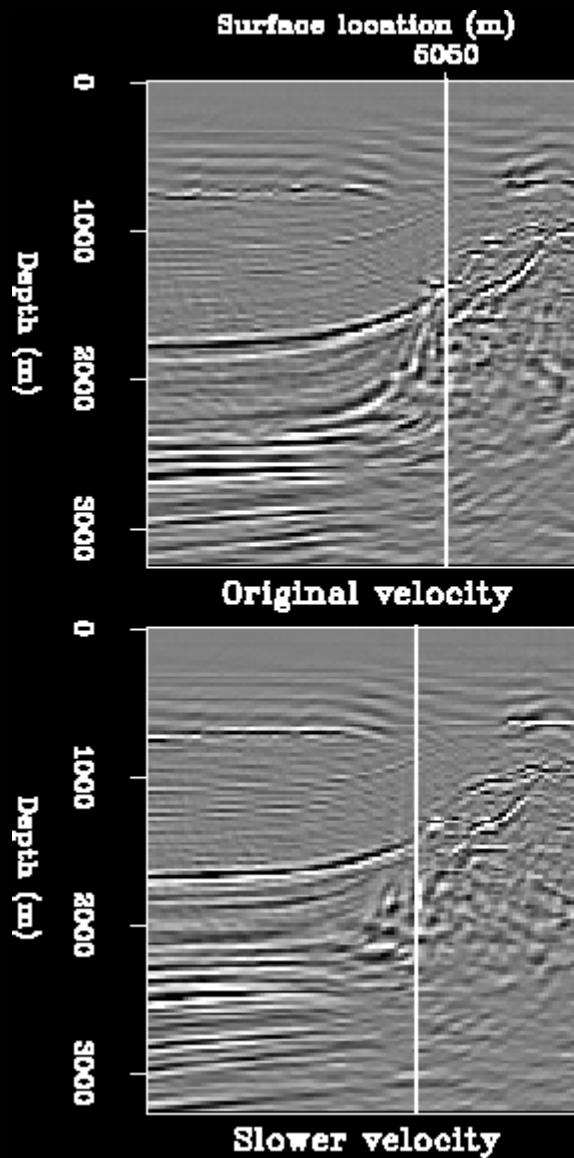
Sigsbee data - Wrong velocity



ADCIGs and velocity in simple structure



Velocity sensitivity of Angle-Domain DDCIGs



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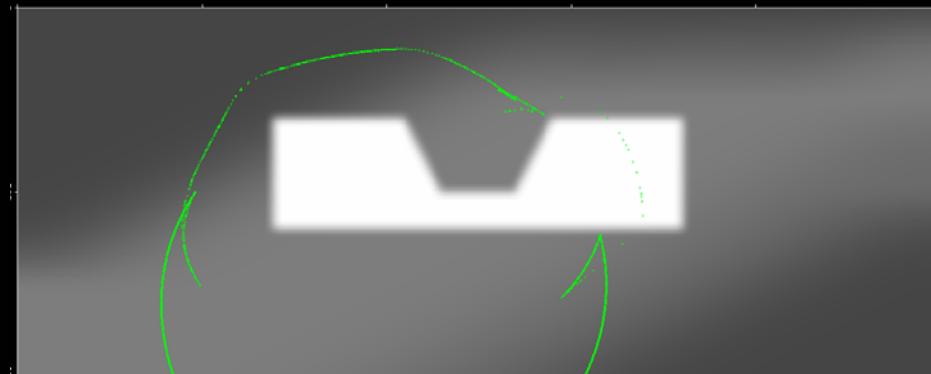
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Migration \leftrightarrow Migration Velocity Analysis



wavefronts



wavefields

❖ Kirchhoff migration

❖ traveltime tomography

❖ Wave-equation migration

❖ Wave-equation MVA

Courtesy of Paul Sava (SEP)

A tomography problem

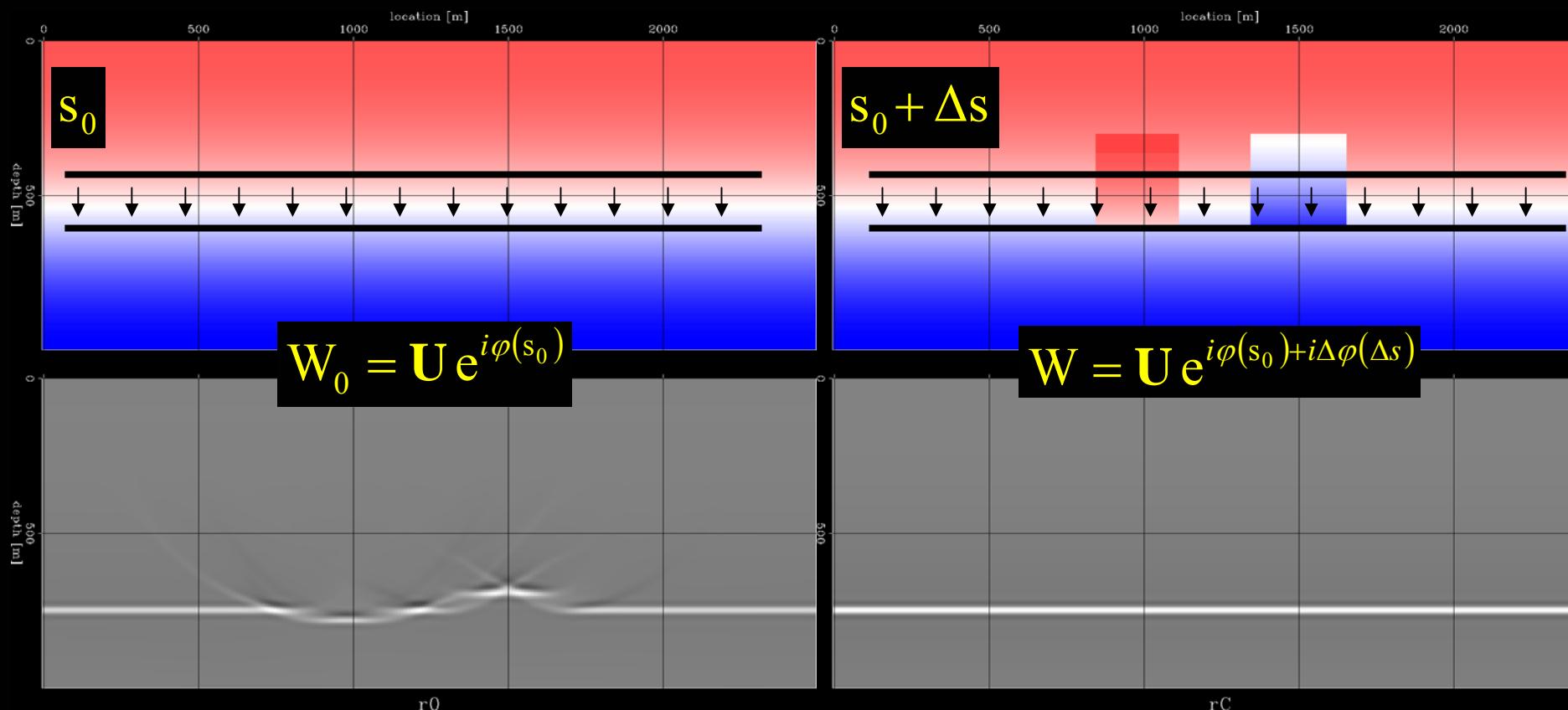
$$\min_{\Delta s} \|\Delta q - \mathbf{L}\Delta s\|$$

	Traveltime MVA	Wave-equation tomography	Wave-equation MVA
Δq	Δt traveltime	Δd data	ΔR image
L	ray field	wavefield	wavefield

Courtesy of Paul Sava (SEP)

WEMVA: main idea

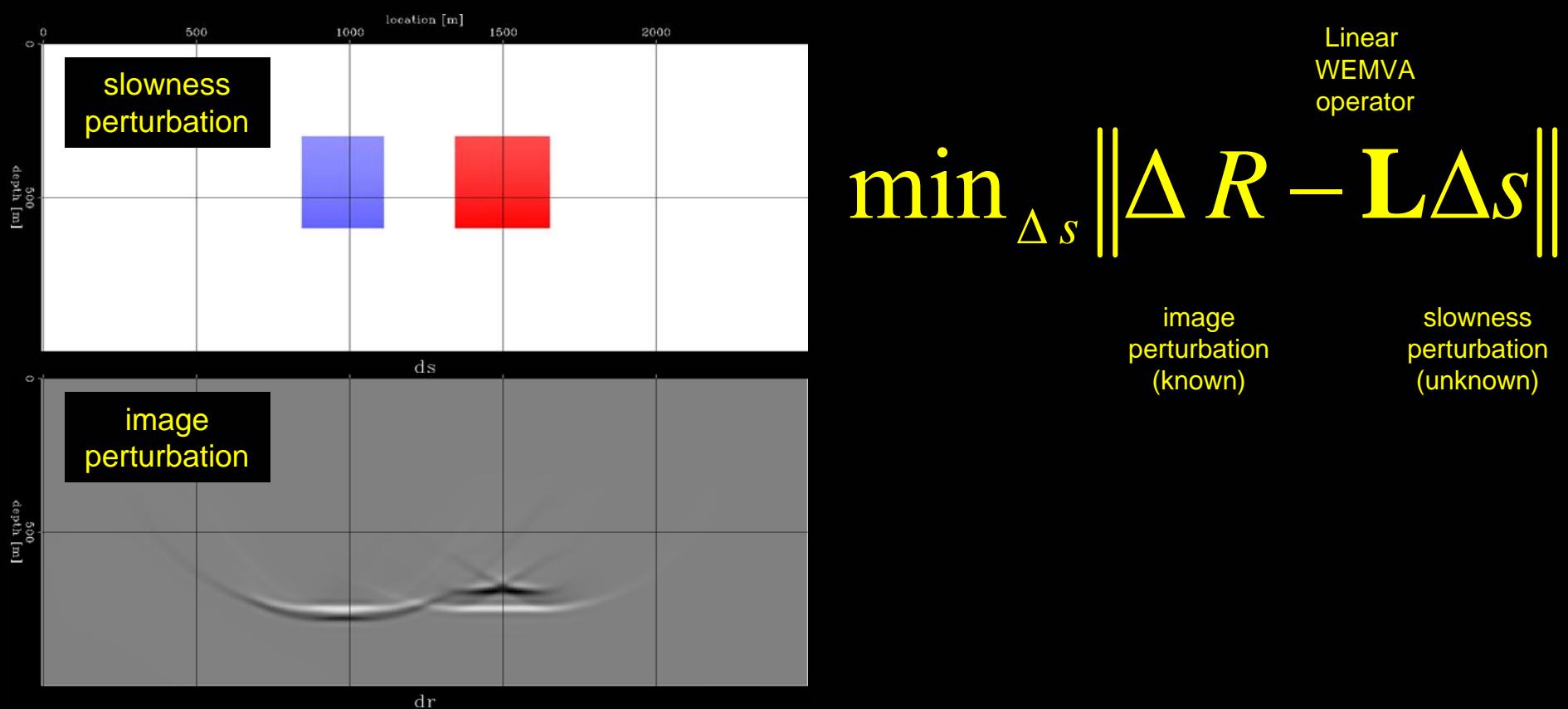
$$\Delta W = W - W_0$$



Courtesy of Paul Sava (SEP)

WEMVA: objective function

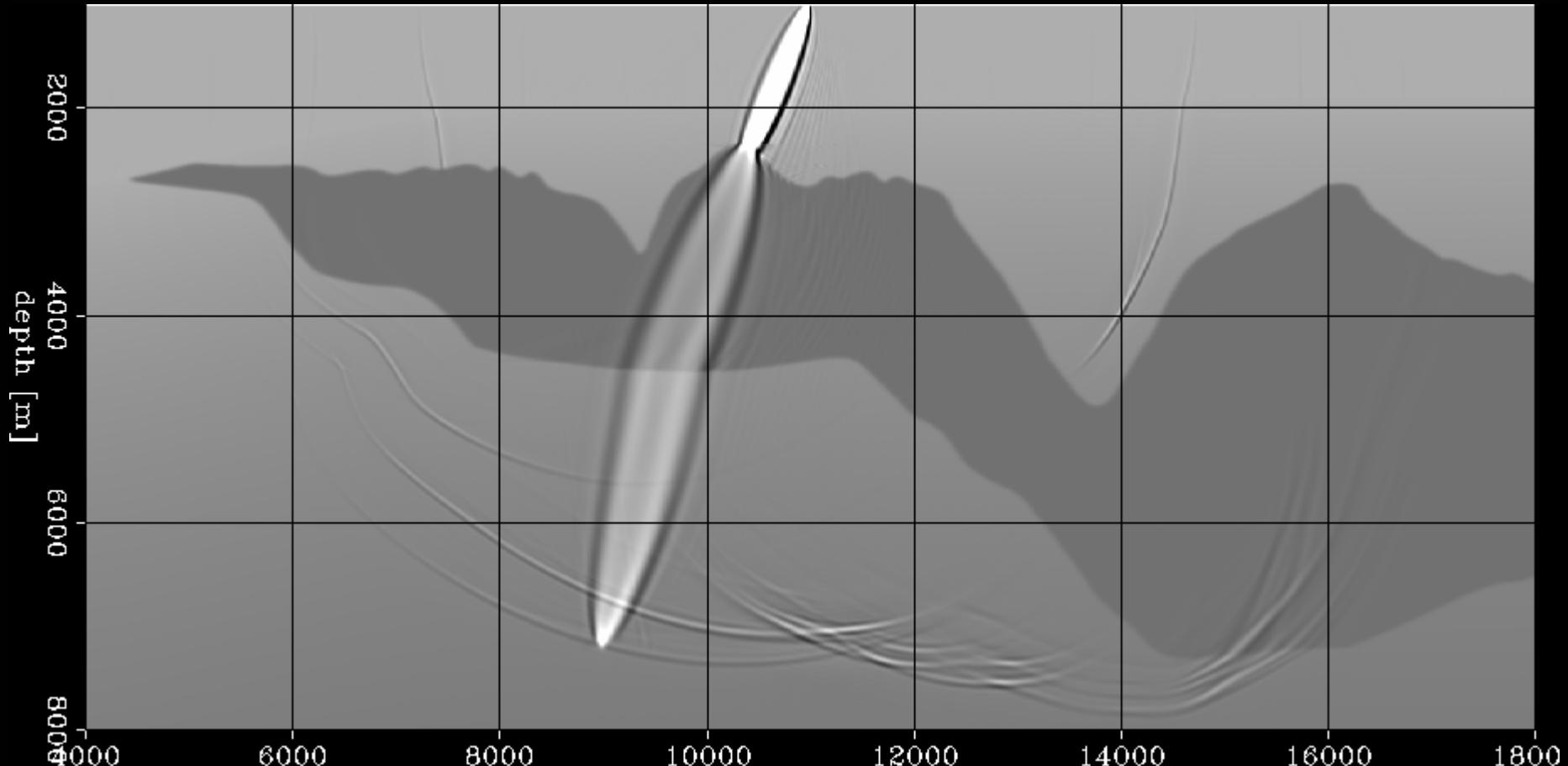
62



Courtesy of Paul Sava (SEP)

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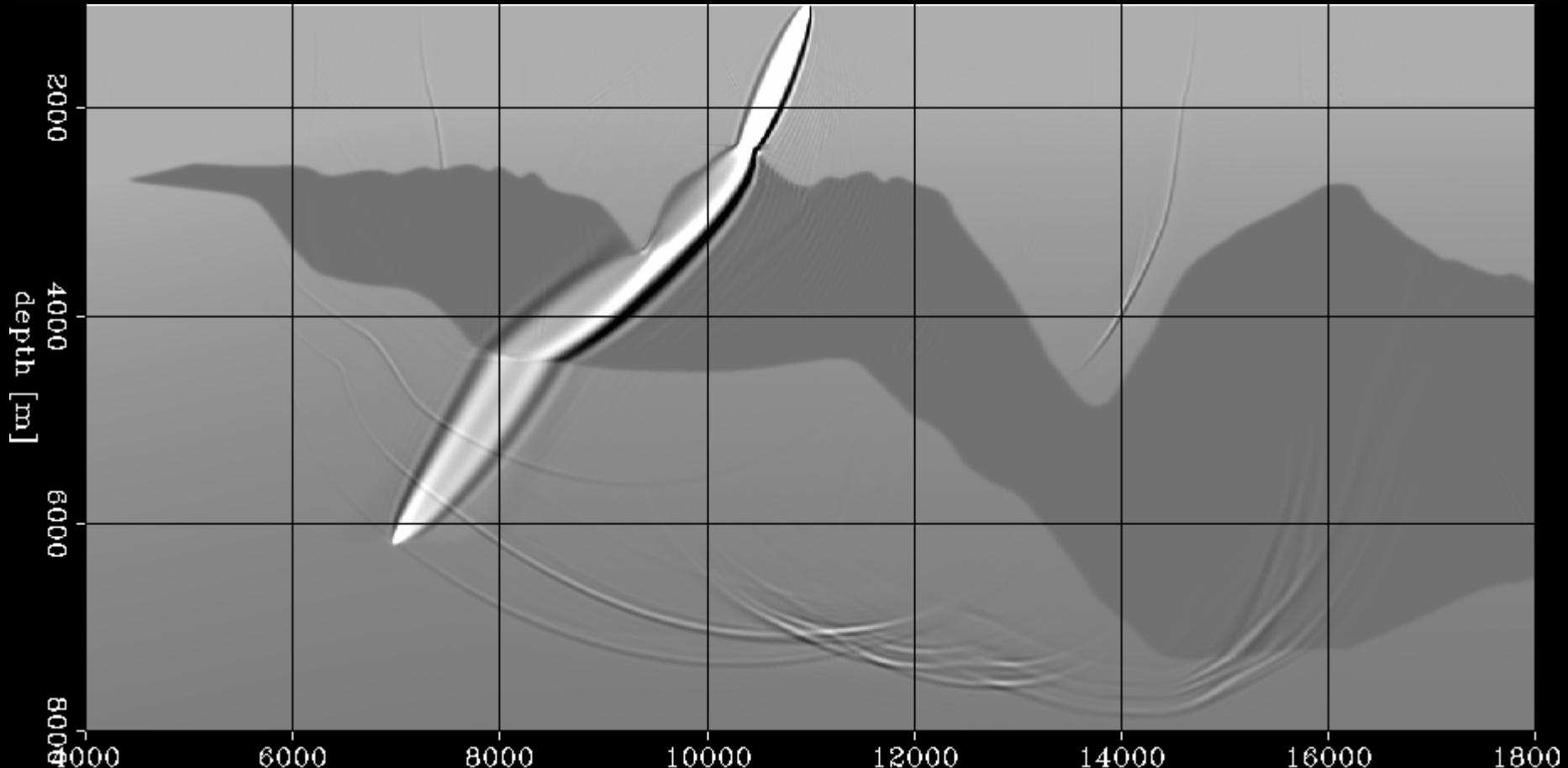
“Simple” wavepath with $f=1 \leftrightarrow 26$ Hz



Courtesy of Paul Sava (SEP)

biondo@stanford.edu

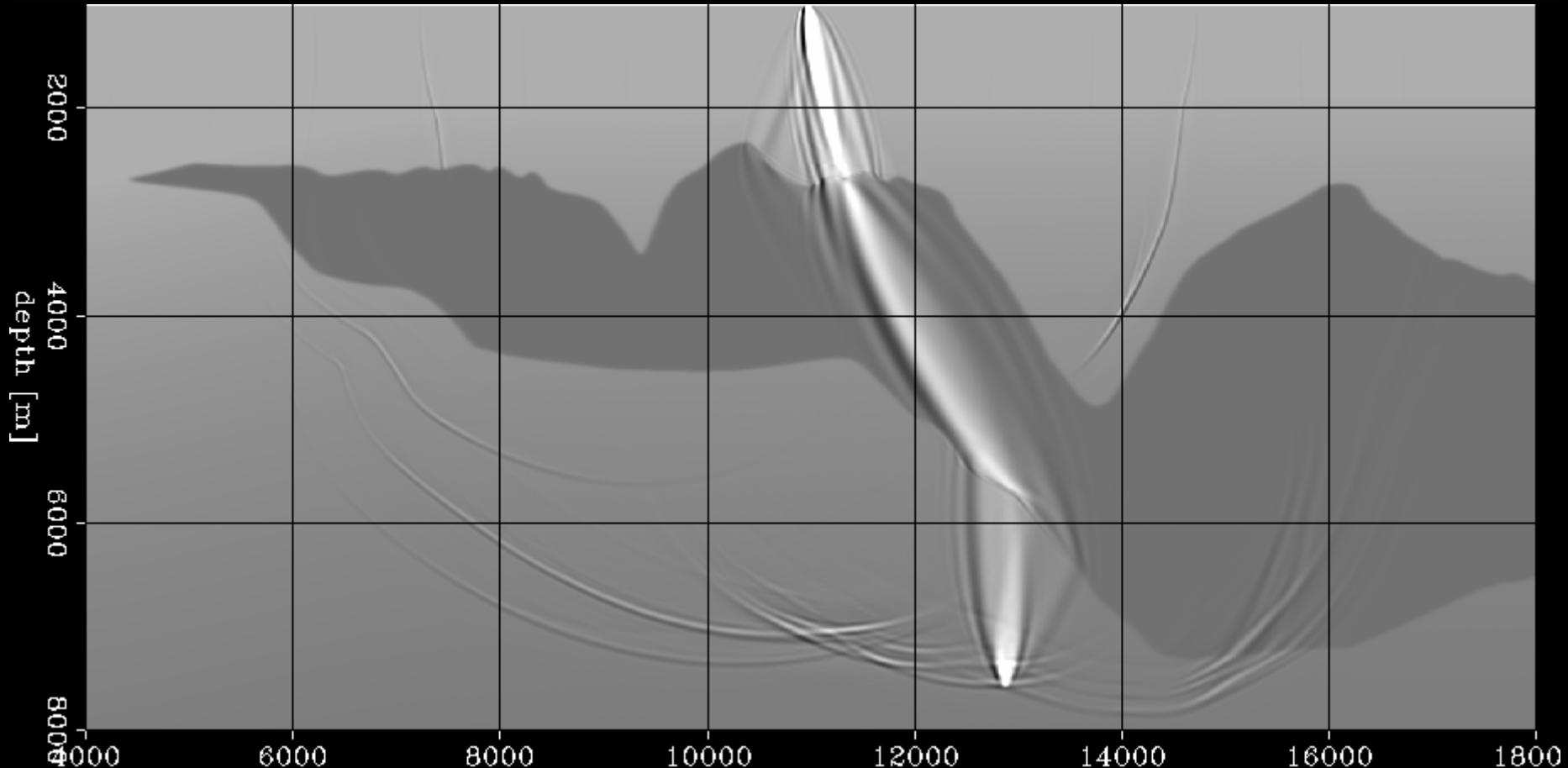
“Complex” wavepath with $f=1 \leftrightarrow 26$ Hz



Courtesy of Paul Sava (SEP)

biondo@stanford.edu

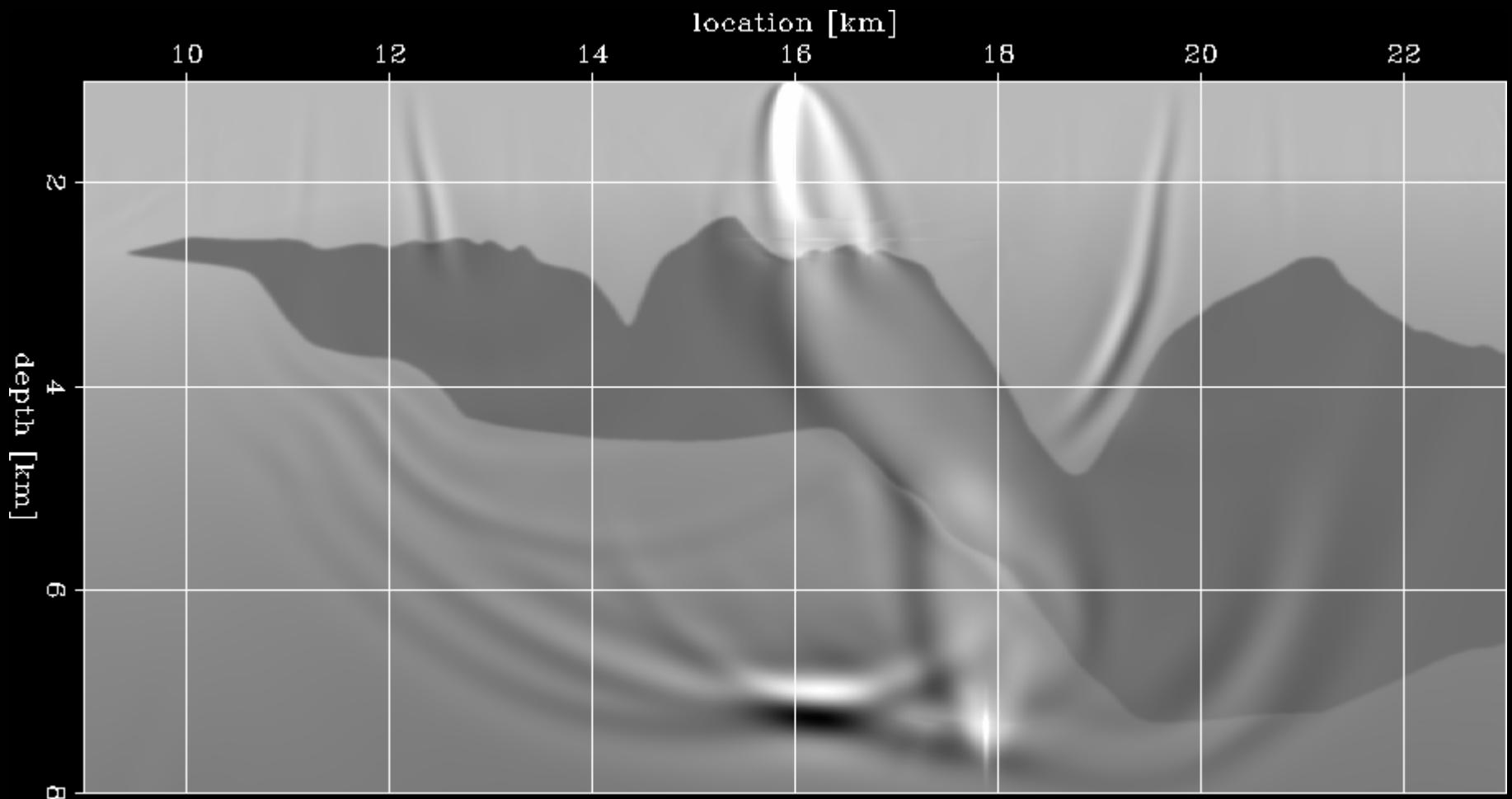
“Messy” wavepath with $f=1 \leftrightarrow 26$ Hz



Courtesy of Paul Sava (SEP)

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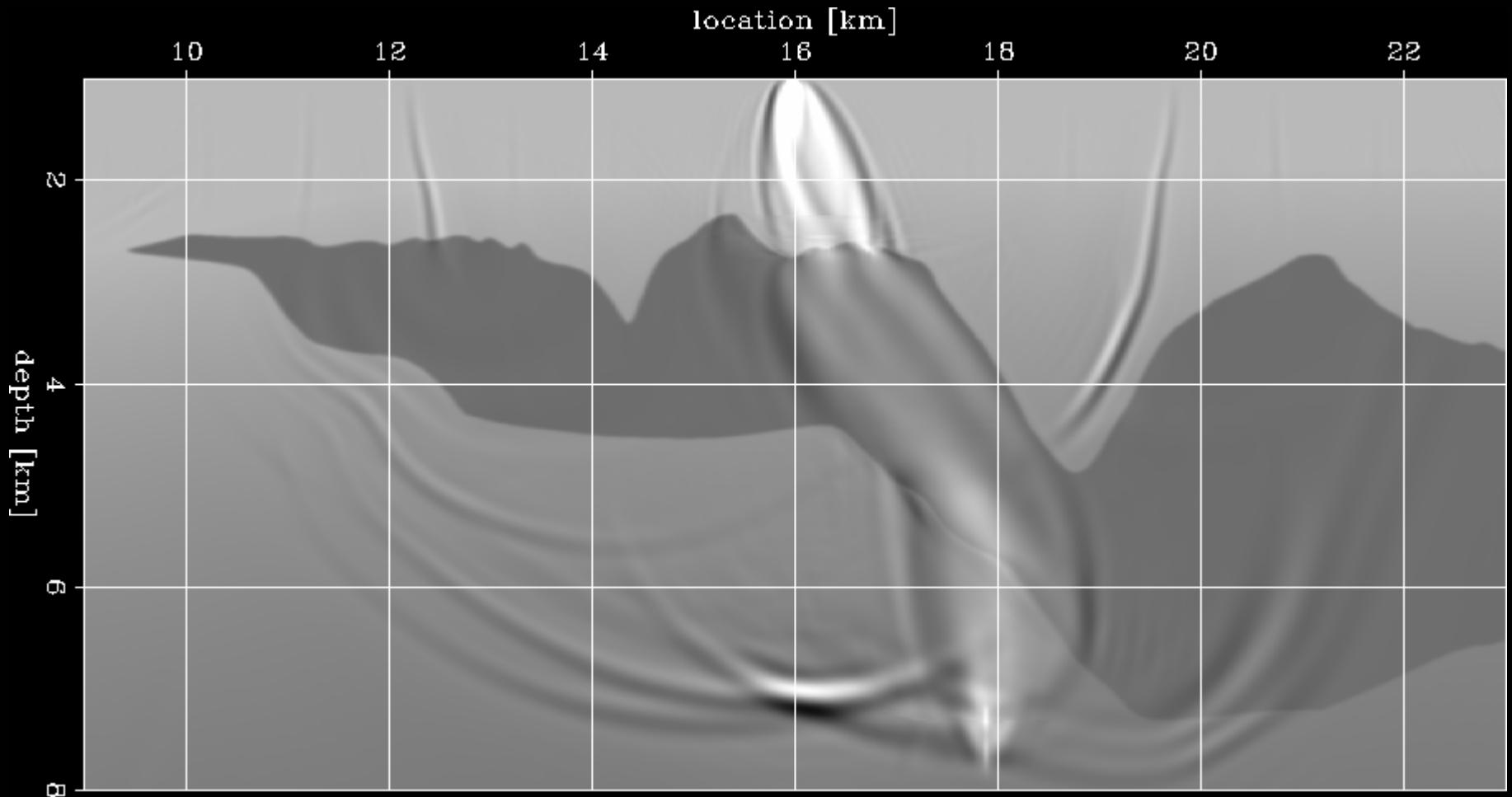
“Messy” wavepath with $f=1 \leftrightarrow 3$ Hz



Courtesy of Paul Sava (SEP)

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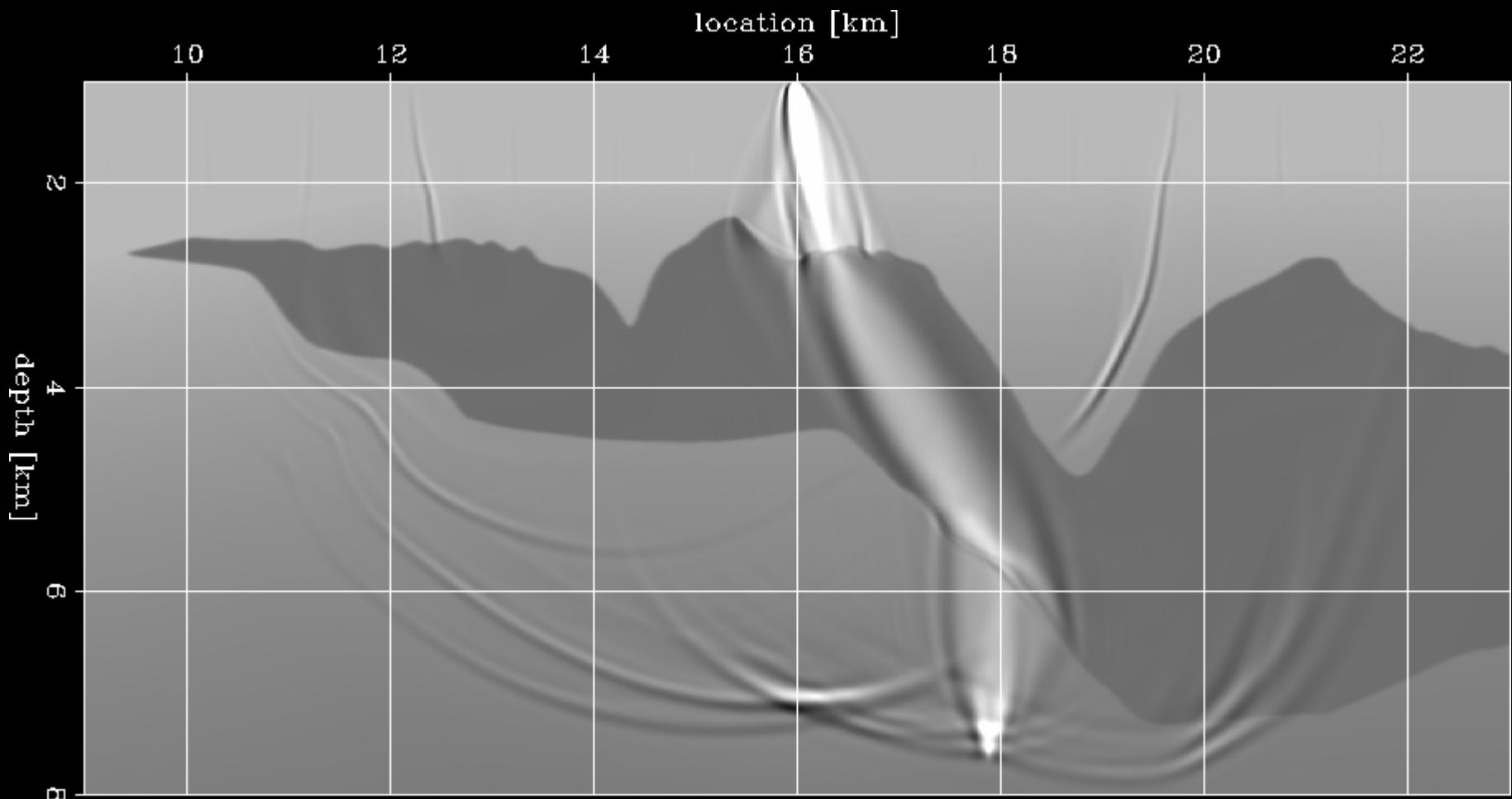
“Messy” wavepath with $f=1 \leftrightarrow 5$ Hz



Courtesy of Paul Sava (SEP)

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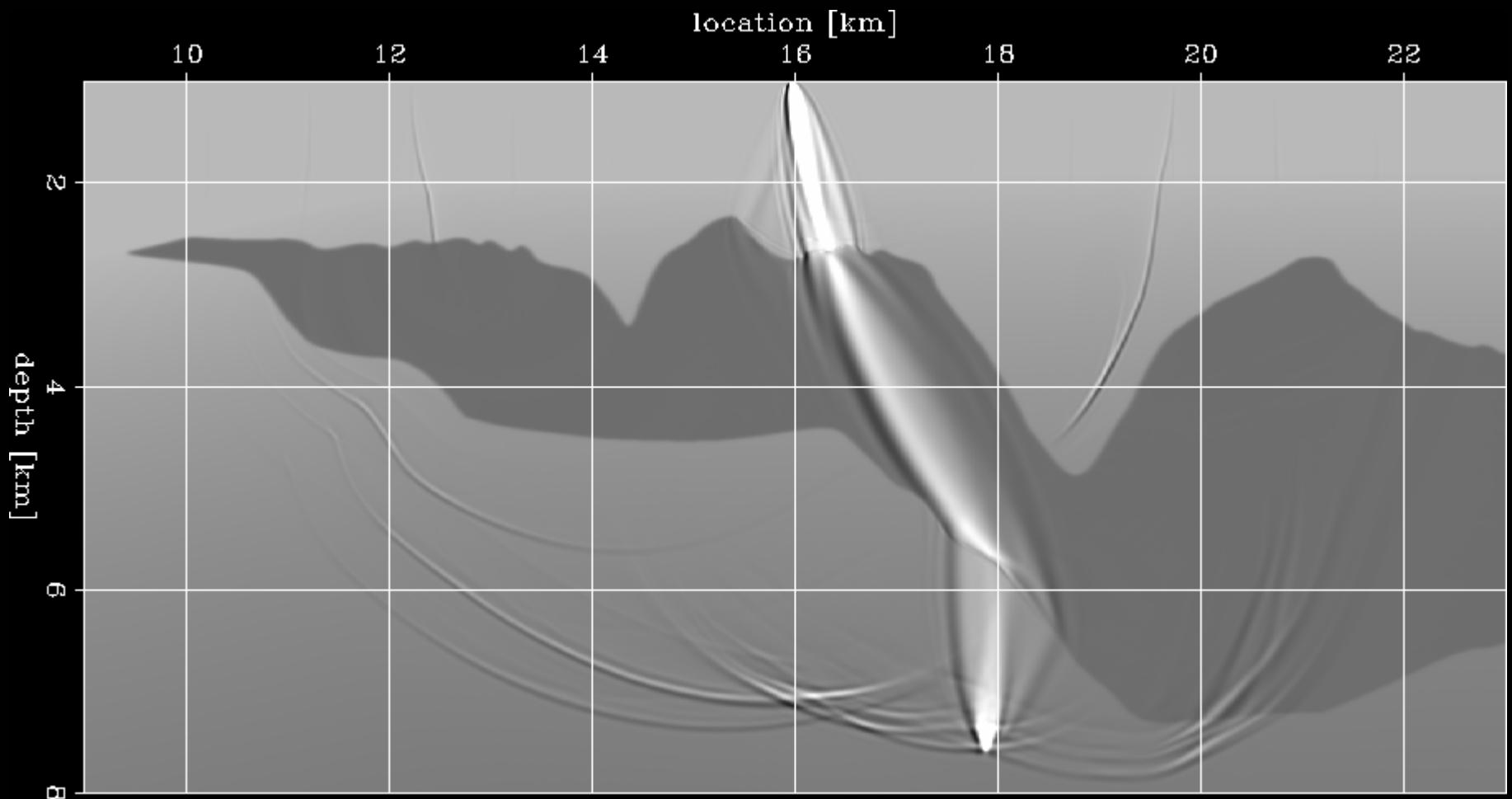
“Messy” wavepath with $f=1 \leftrightarrow 12$ Hz



Courtesy of Paul Sava (SEP)

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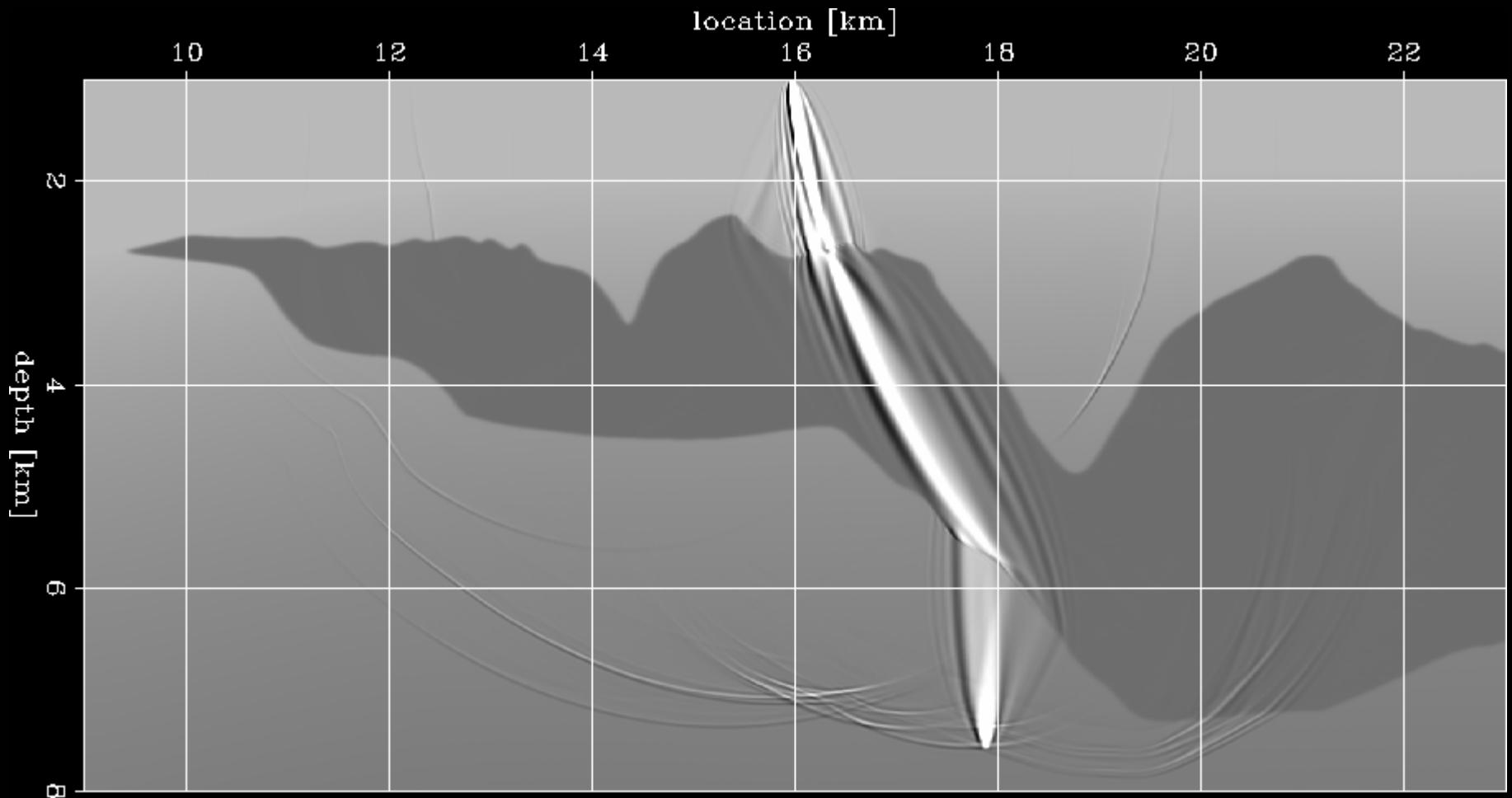
“Messy” wavepath with $f=1 \leftrightarrow 16$ Hz



Courtesy of Paul Sava (SEP)

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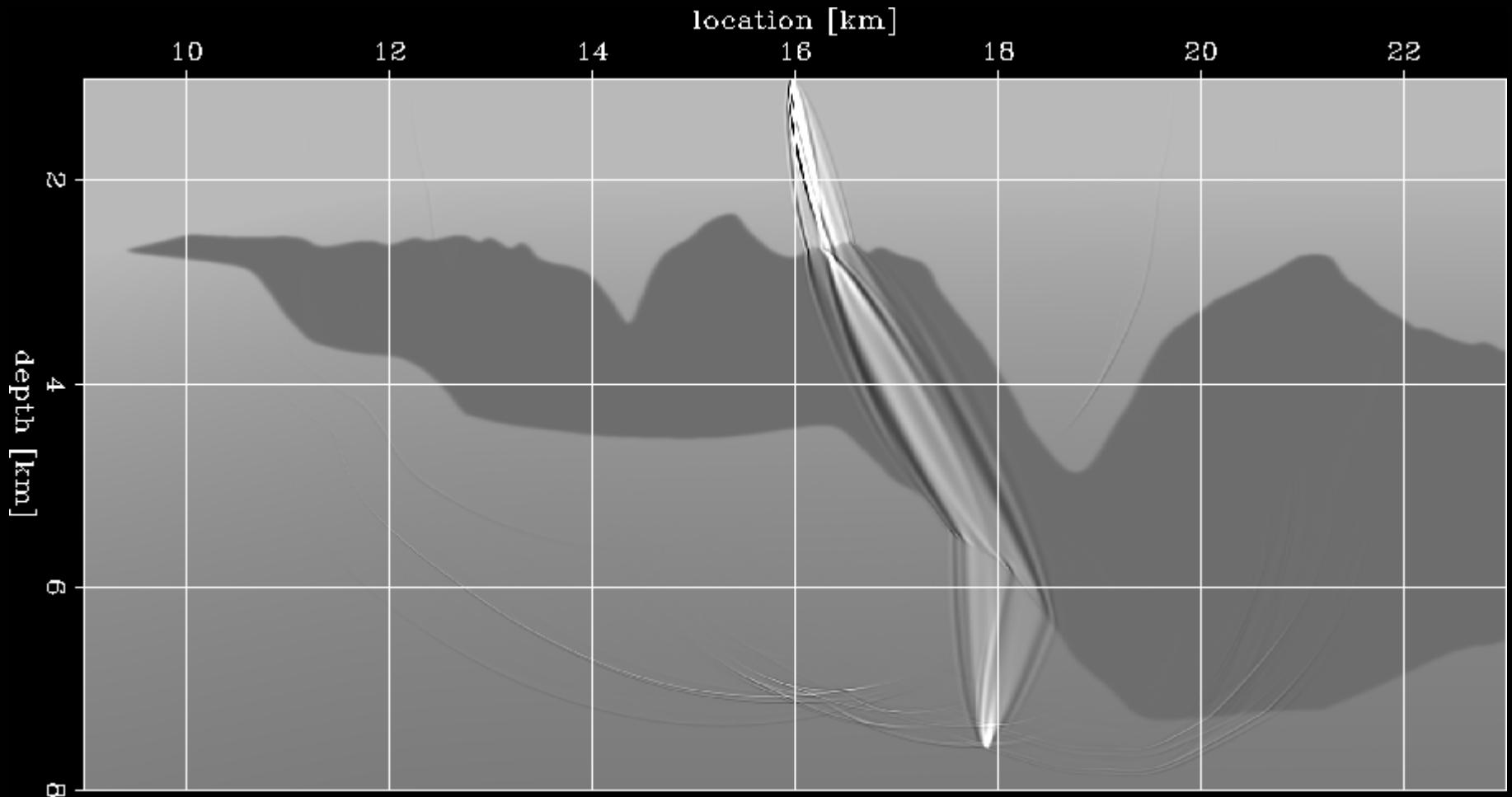
“Messy” wavepath with $f=1 \leftrightarrow 26$ Hz



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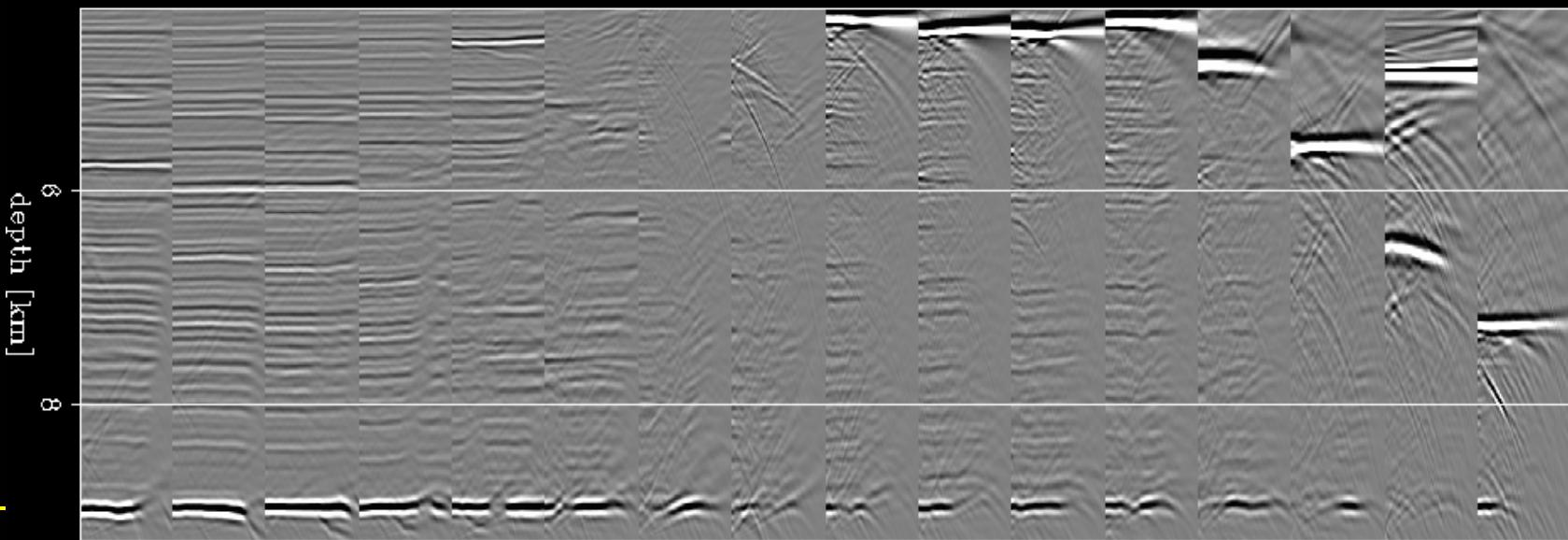
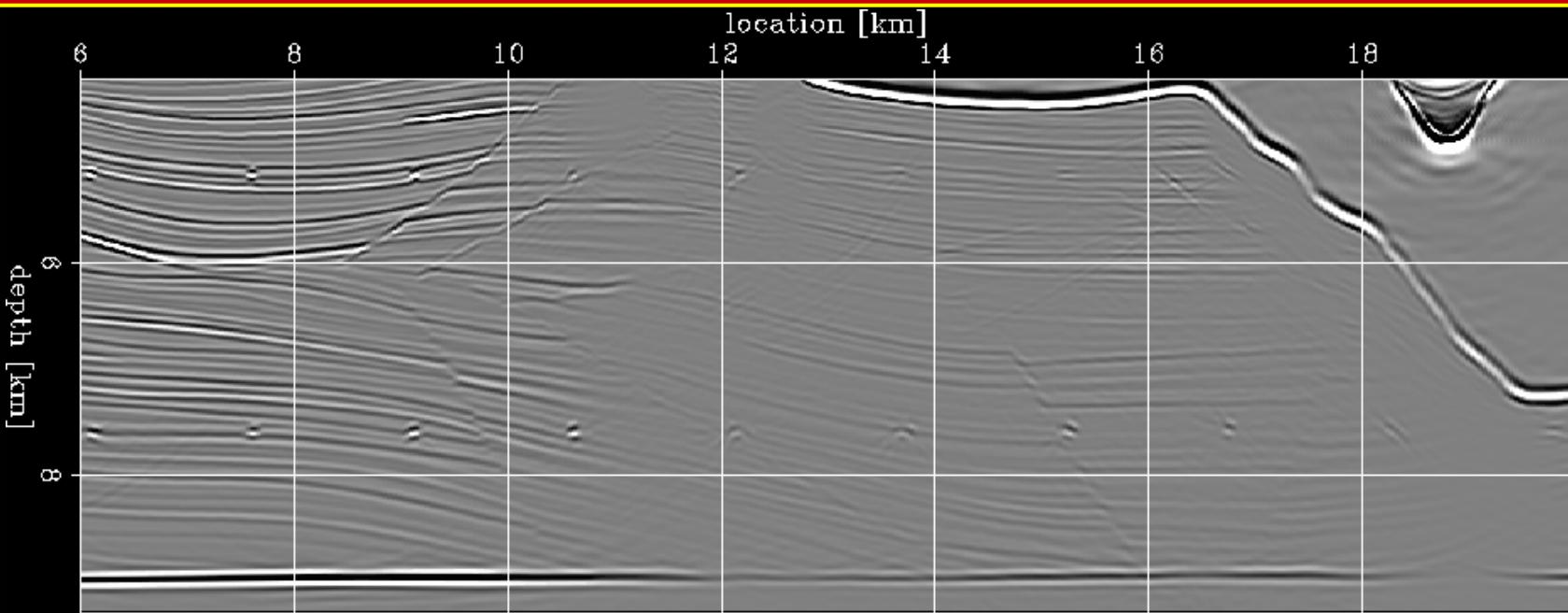
“Messy” wavepath with $f=1 \leftrightarrow 64$ Hz



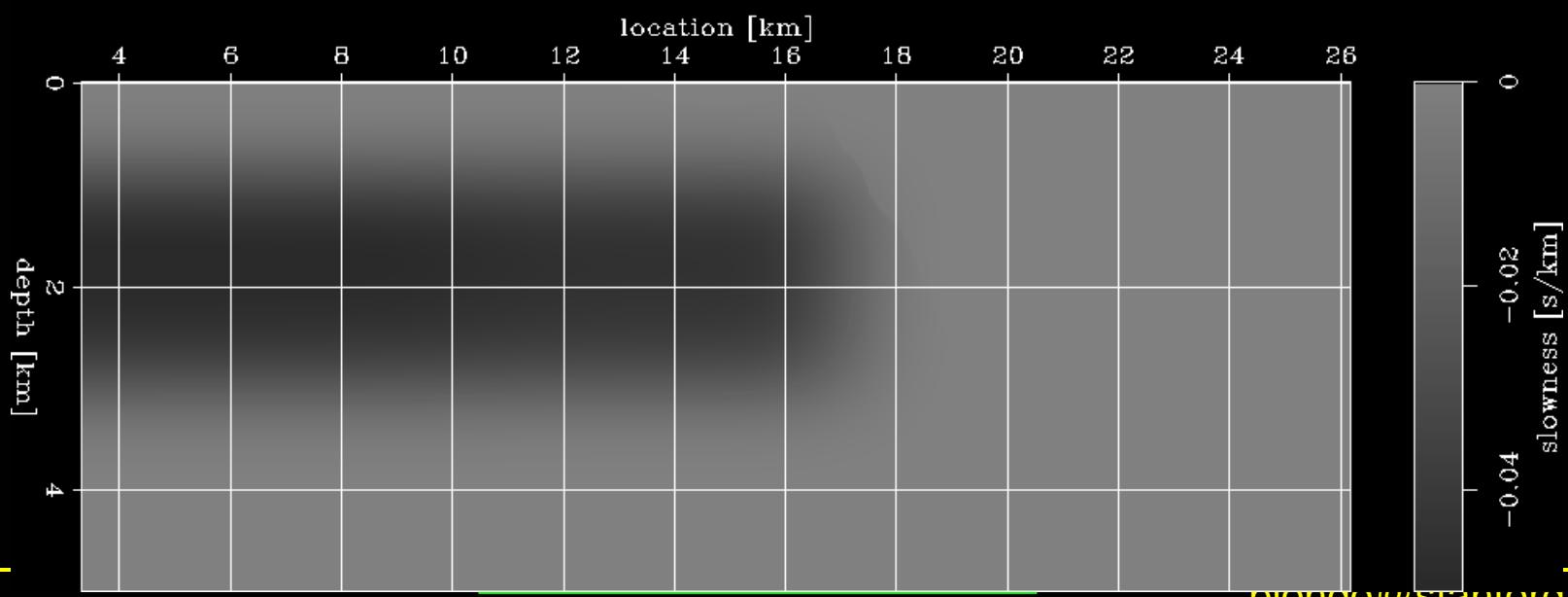
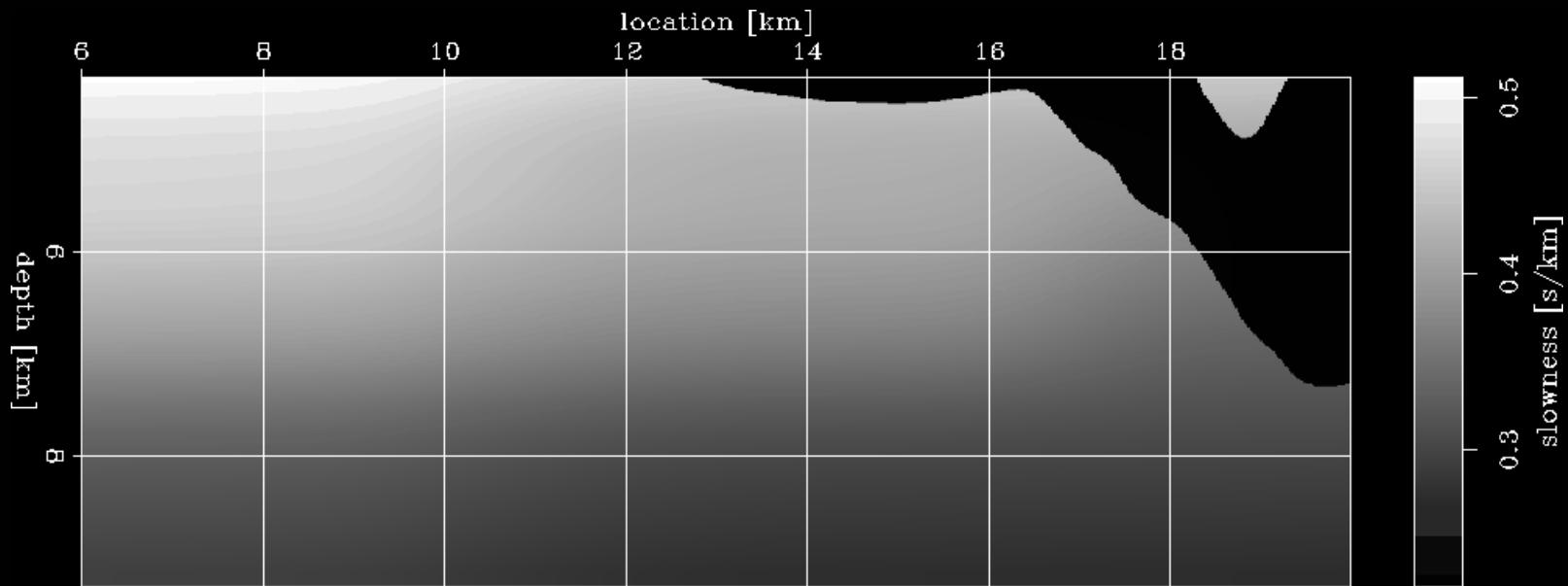
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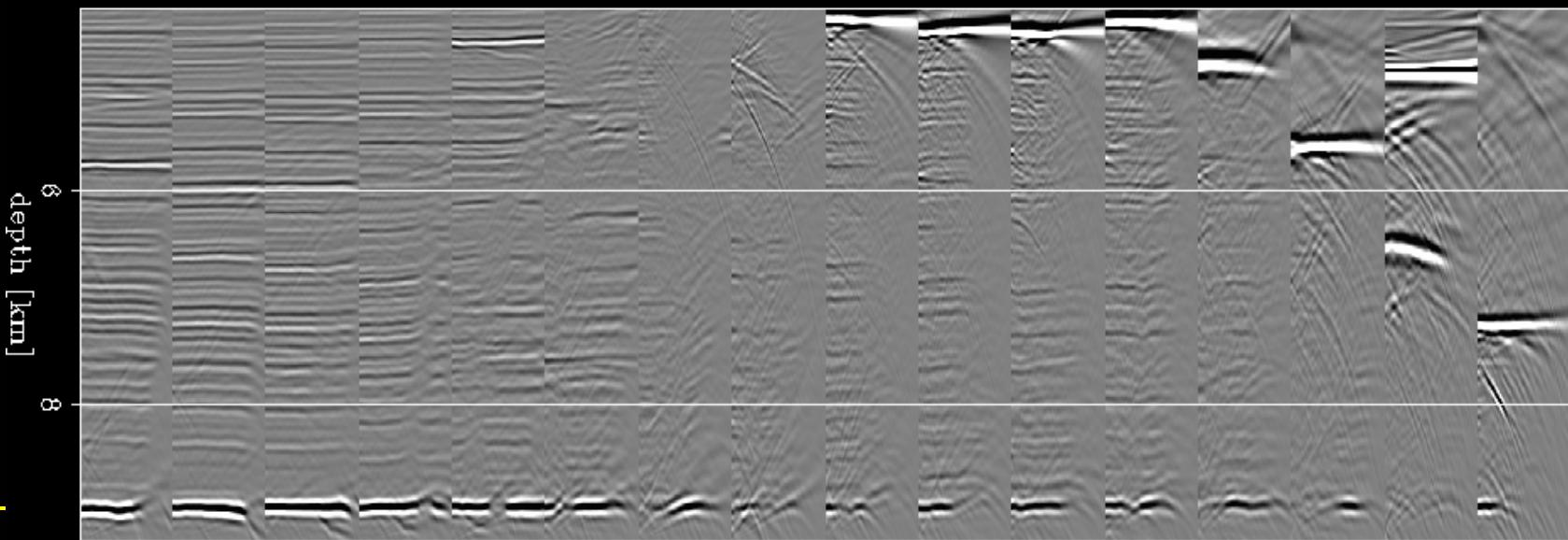
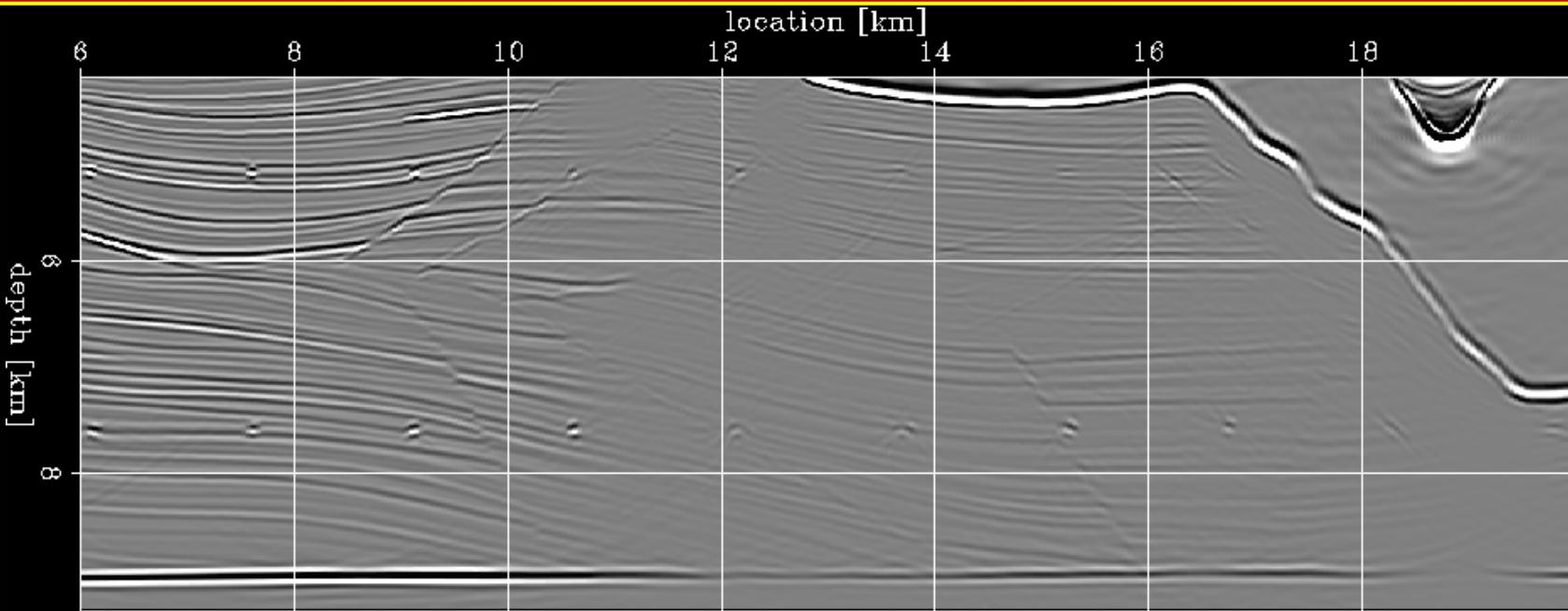
Migration and ADCIGs with correct velocity



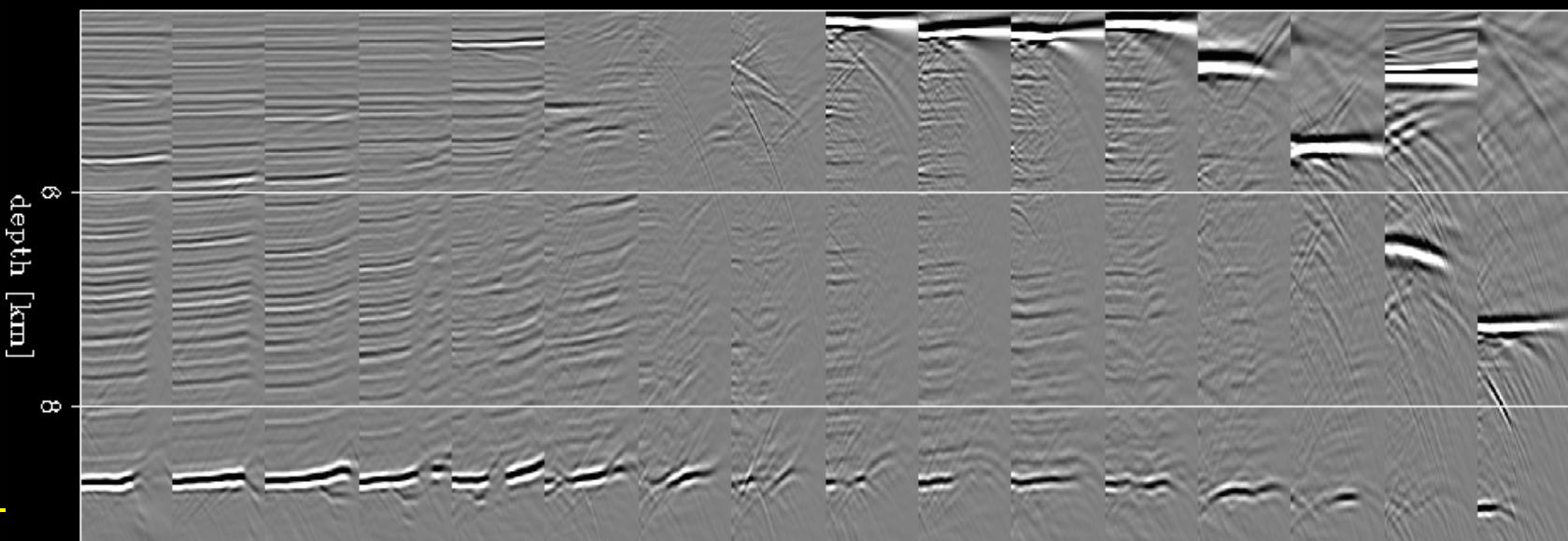
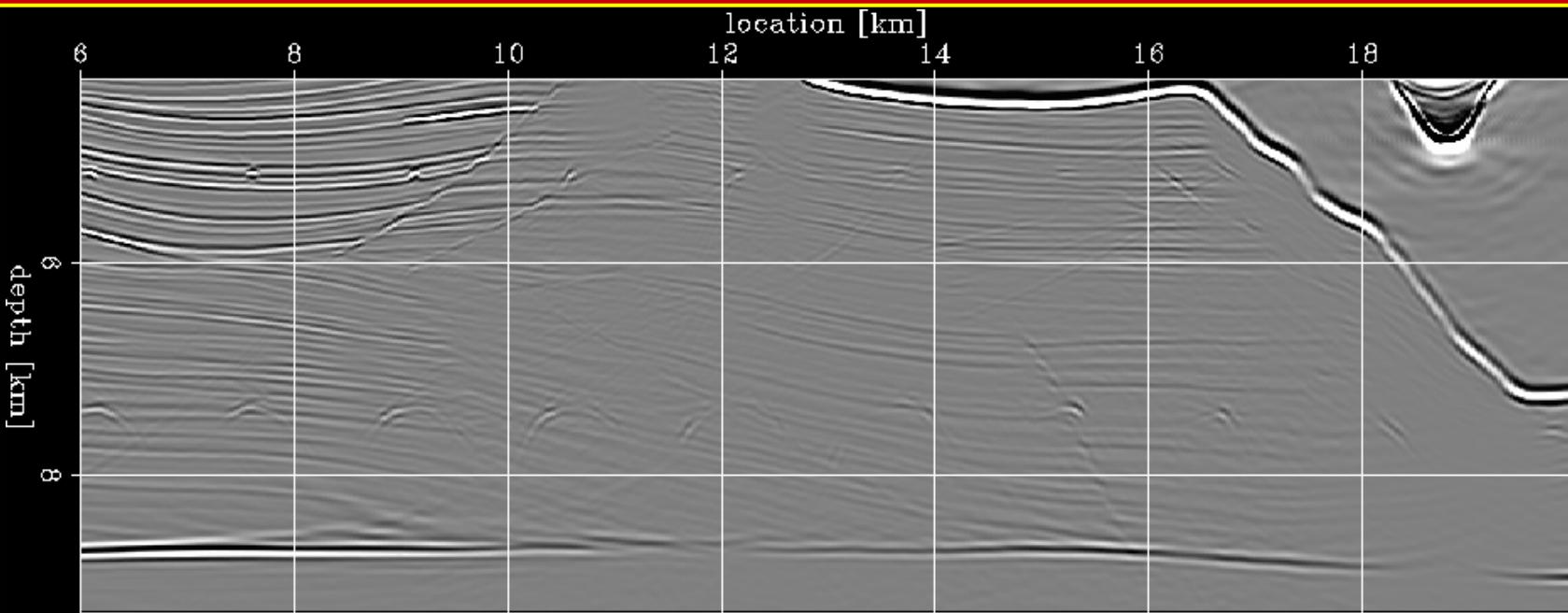
Correct velocity model and initial velocity error



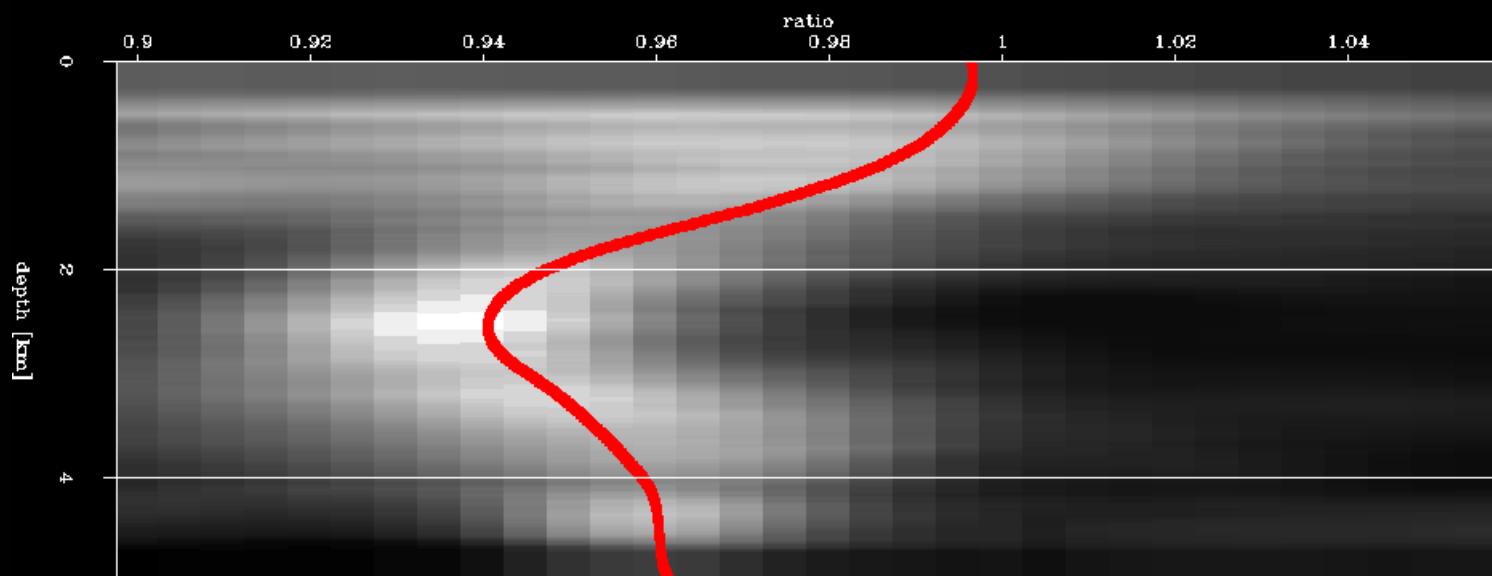
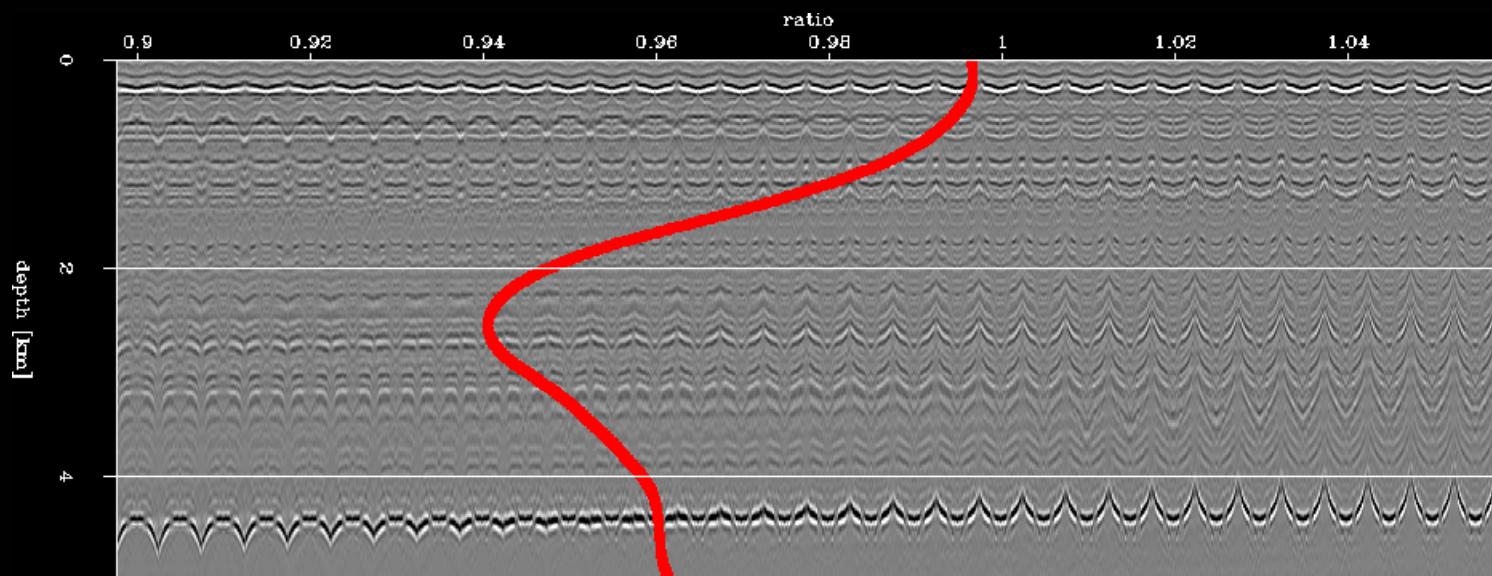
Migration and ADCIGs with correct velocity



Migration and ADCIGs with initial velocity



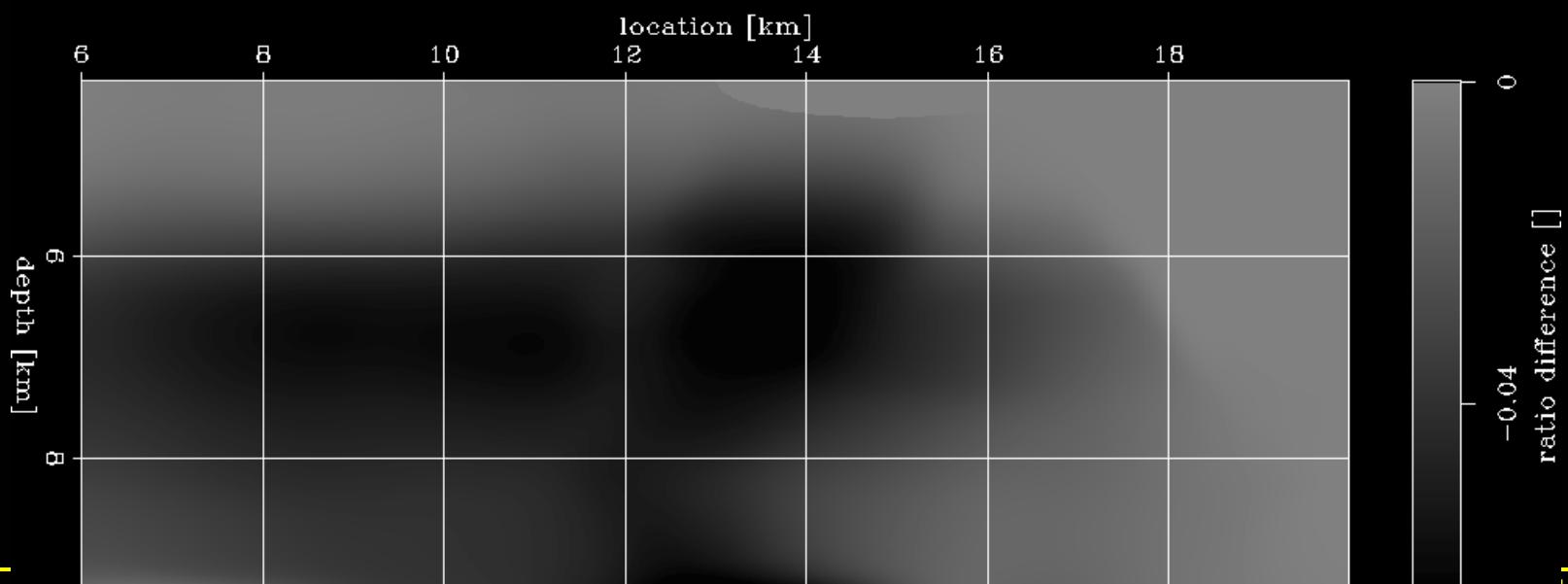
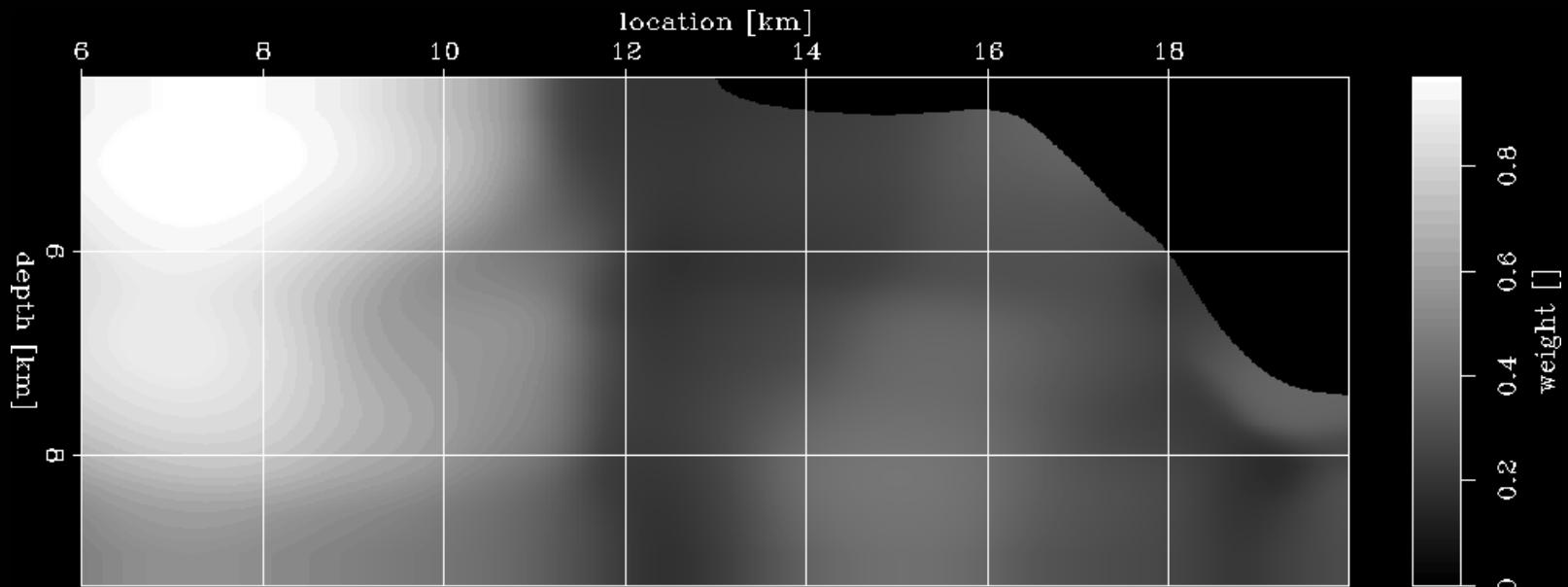
Measuring velocity errors by residual migration



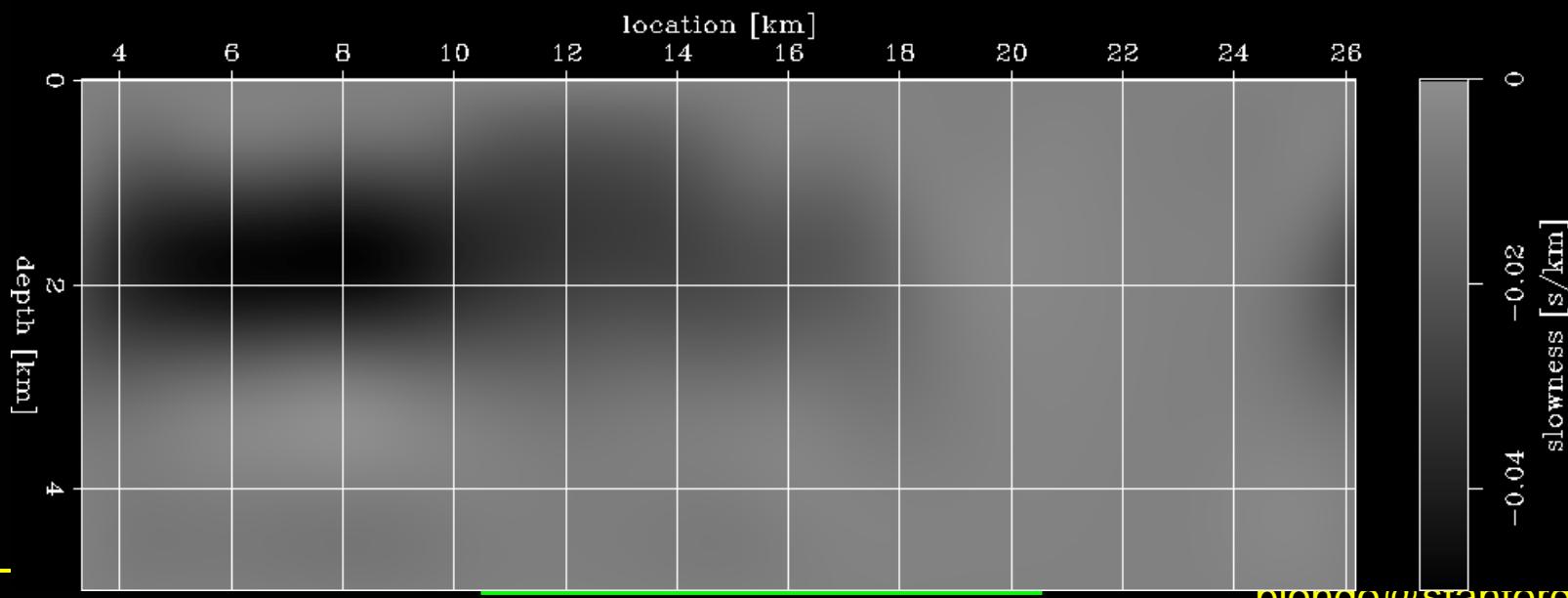
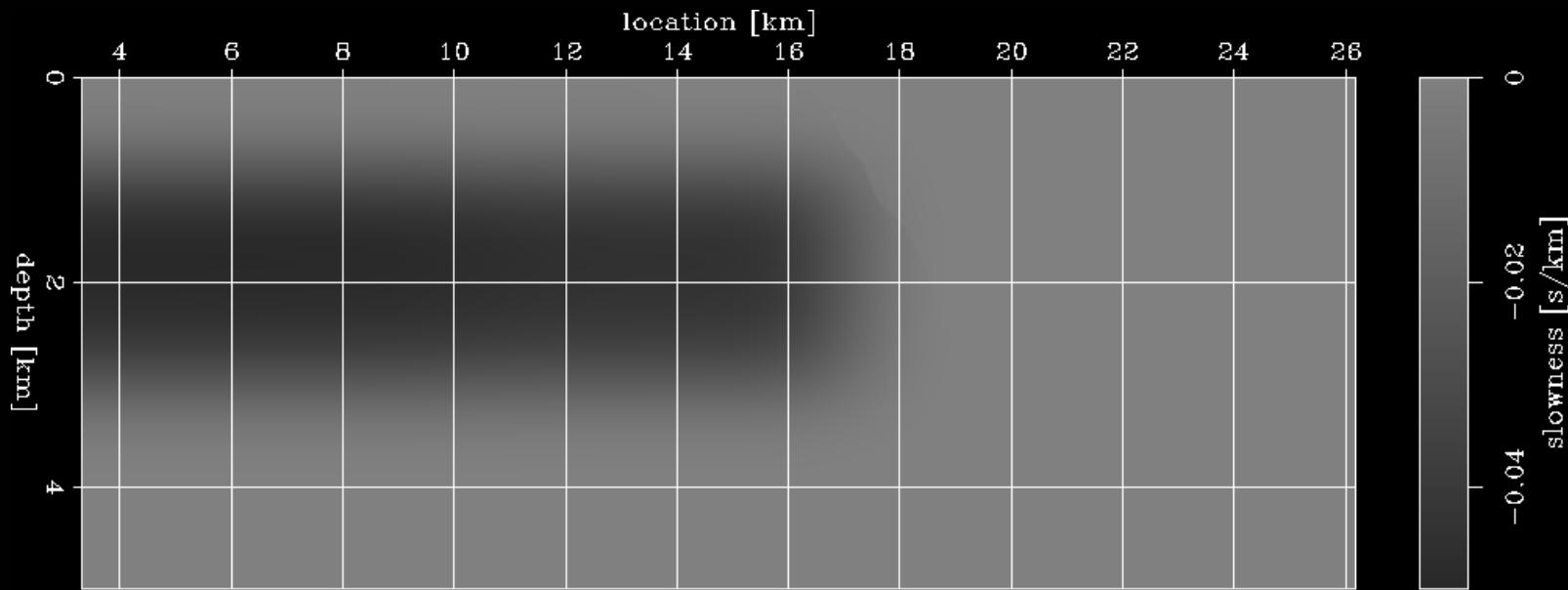
Courtesy of Paul Sava (SLT)

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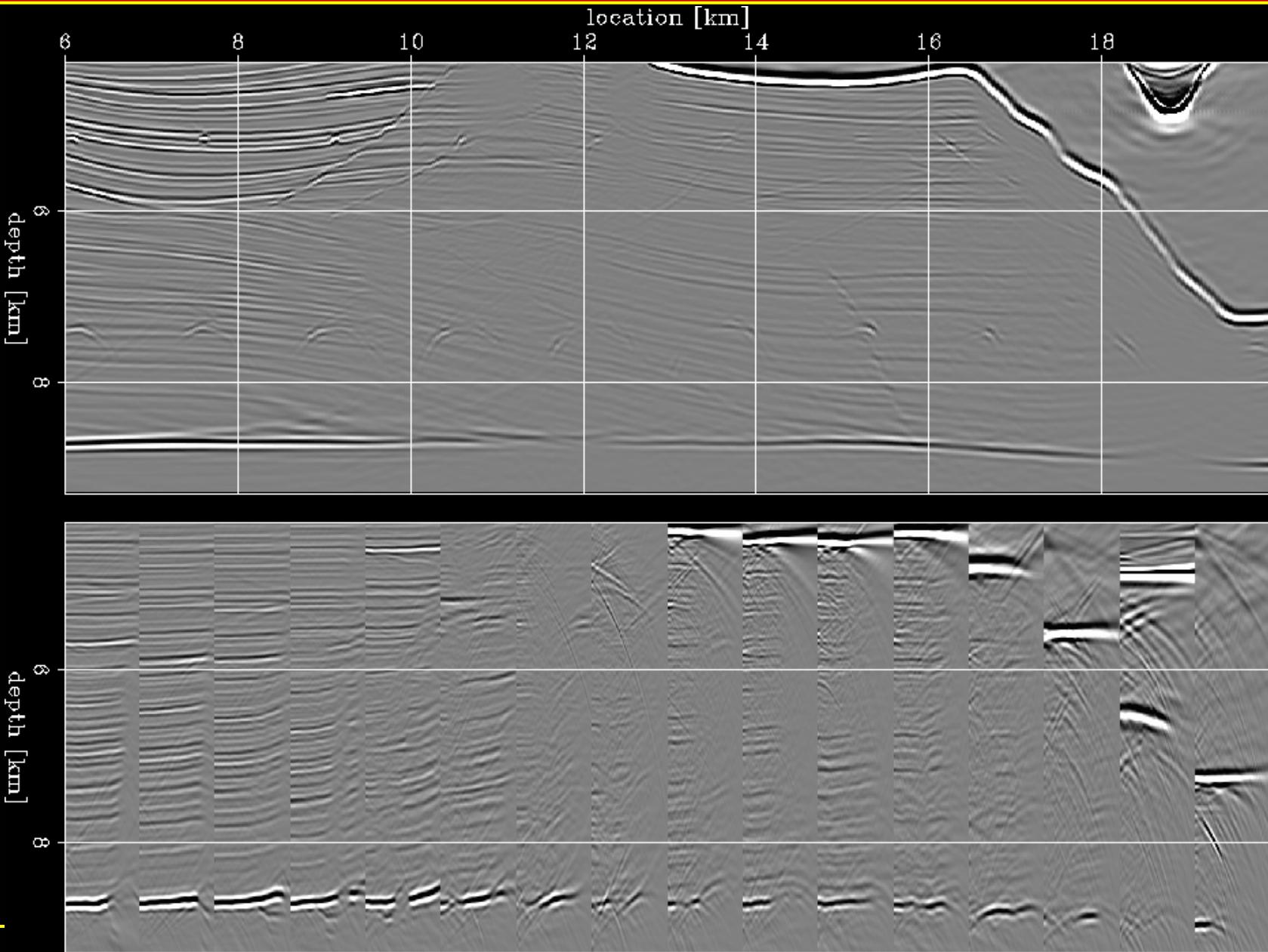
Reliability of measurements and velocity errors



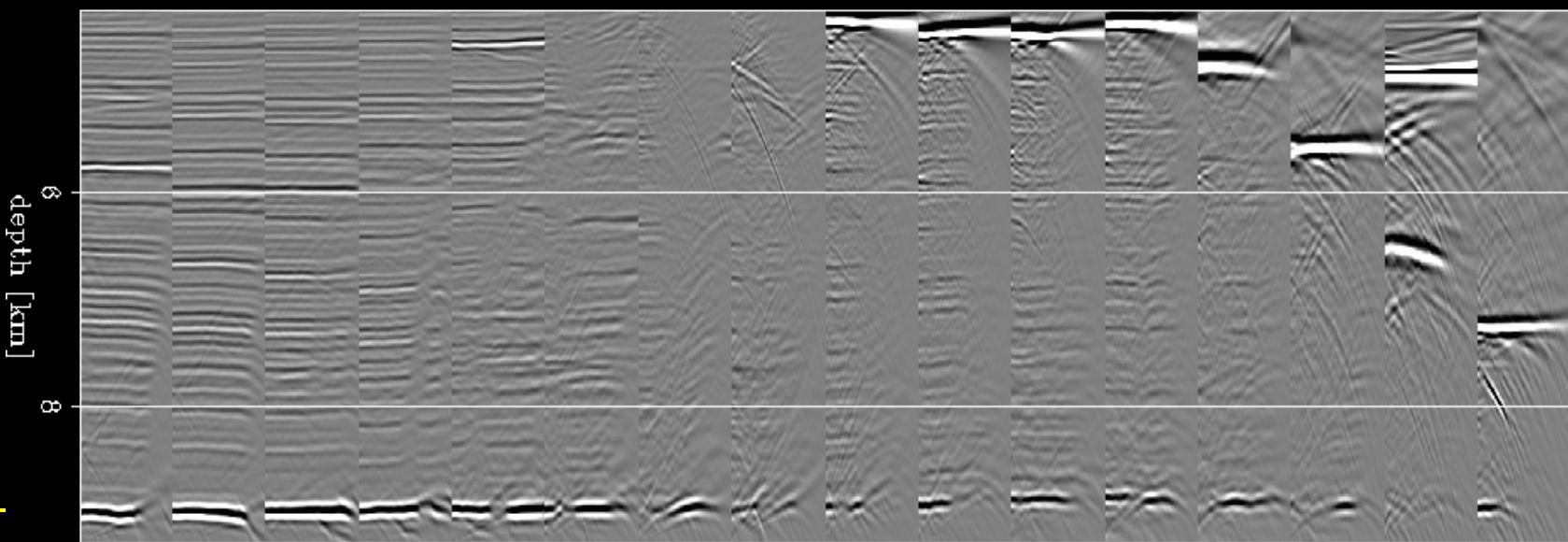
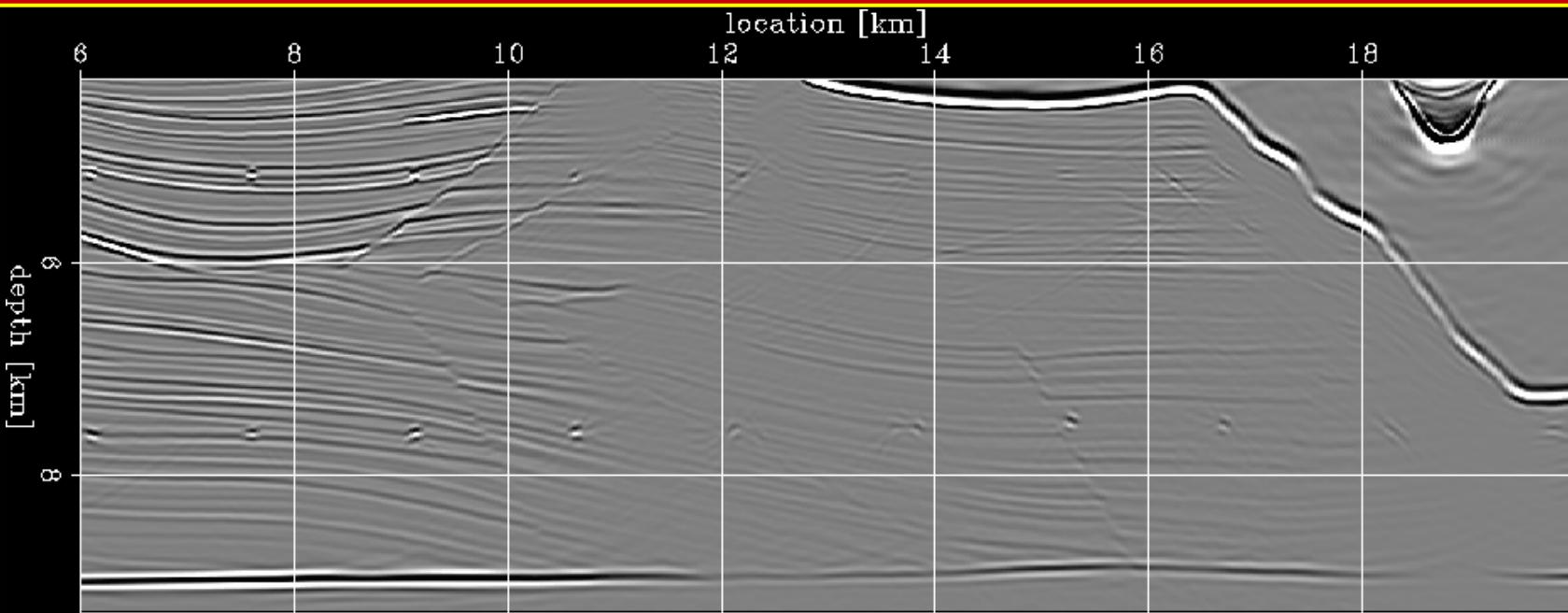
True and estimated velocity error



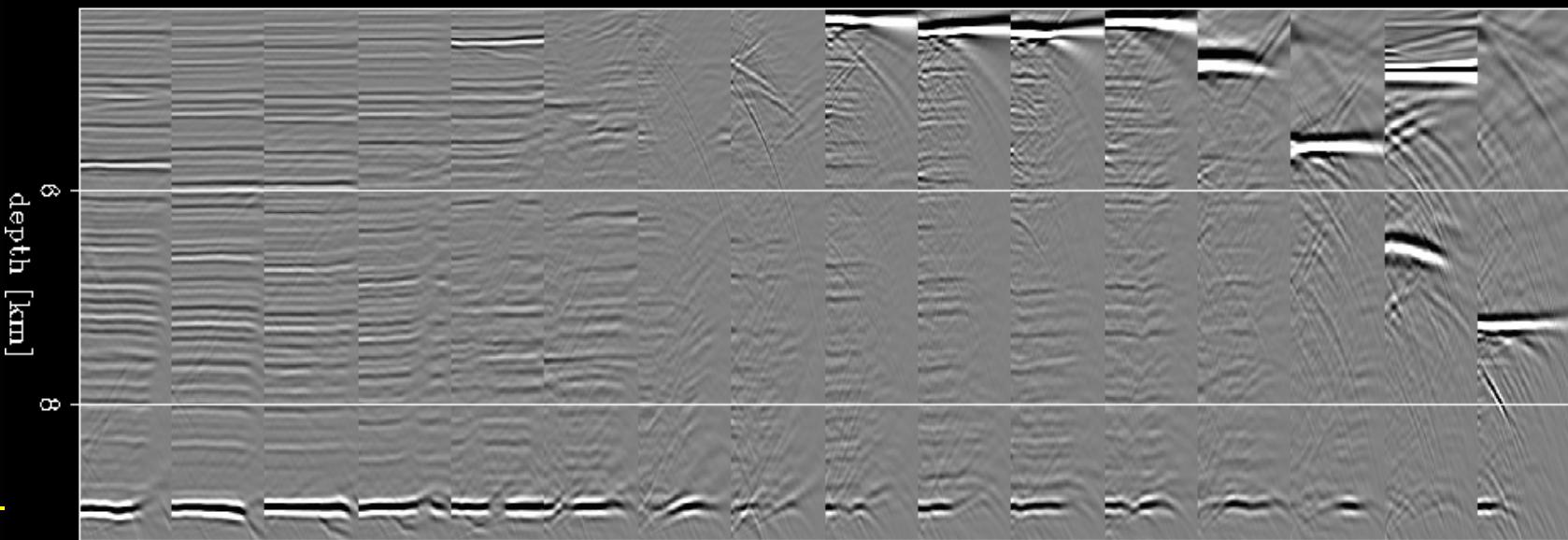
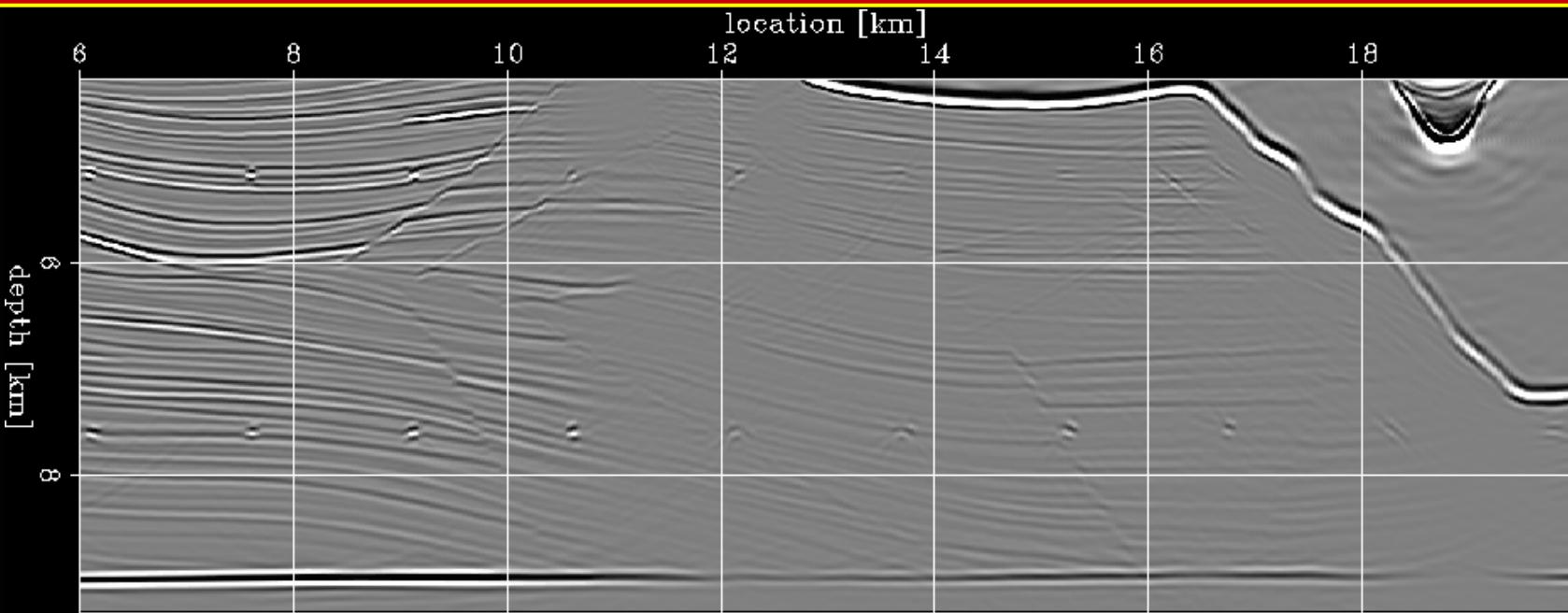
Migration and ADCIGs with initial velocity



Migration and ADCIGs with estimated velocity



Migration and ADCIGs with correct velocity



Conclusions

- **Complex structures require accurate and expensive wavefield-continuation imaging operators.**
- **To image reflectors that are poorly illuminated we need to go beyond the application of the adjoint operator (migration) and move towards “intelligent” (regularized) inversion.**
- **Wavefield-continuation operators are beneficial not only for migration but also for velocity estimation.**
- **The estimation of holes in poorly illuminated reflectors and of velocity errors are tightly coupled problems.**

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