

Homework 12: Systems of Linear Equations (due on May 14)

1. (a) A vector norm $\|\mathbf{x}\|$ has the following properties

- i. $\|\mathbf{x}\| \geq 0$ for all $\mathbf{x} \in \mathbb{R}^n$; $\|\mathbf{x}\| = 0$ only if $\mathbf{x} = \mathbf{0}$
- ii. $\|\alpha \mathbf{x}\| = |\alpha| \|\mathbf{x}\|$ for all $\alpha \in \mathbb{R}$ and $\mathbf{x} \in \mathbb{R}^n$
- iii. $\|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|$ for all $\mathbf{x} \in \mathbb{R}^n$ and $\mathbf{y} \in \mathbb{R}^n$

Prove that these properties are satisfied if a vector norm is defined as

$$\|\mathbf{x}\|_S = (\mathbf{x}^T \mathbf{S} \mathbf{x})^{1/2}, \quad (1)$$

where \mathbf{S} is a symmetric positive definite matrix.

(b) A matrix norm $\|\mathbf{A}\|$ has the following properties

- i. $\|\mathbf{A}\| \geq 0$ for all $n \times n$ matrices \mathbf{A} ; $\|\mathbf{A}\| = 0$ only if $\mathbf{A} = \mathbf{0}$
- ii. $\|\alpha \mathbf{A}\| = |\alpha| \|\mathbf{A}\|$
- iii. $\|\mathbf{A} + \mathbf{B}\| \leq \|\mathbf{A}\| + \|\mathbf{B}\|$
- iv. $\|\mathbf{A}\mathbf{B}\| \leq \|\mathbf{A}\| \|\mathbf{B}\|$

Prove that these properties are satisfied for the *Frobenius* norm

$$\|\mathbf{A}\|_F = \left(\sum_{i=1}^n \sum_{j=1}^n |a_{ij}|^2 \right)^{1/2} \quad (2)$$

2. Triangular matrix (**LU**) decomposition requires $\frac{n(n-1)(2n-1)}{6}$ multiplications. Triangular matrix inversion (**L** or **U**) requires $\frac{n(n-1)}{2}$ multiplications.

(a) Find the number of multiplications necessary for solving two linear systems

$$\mathbf{A} \mathbf{x} = \mathbf{b}_1, \quad \mathbf{A} \mathbf{x} = \mathbf{b}_2 \quad (3)$$

with the non-singular square matrix \mathbf{A} .

(b) Find the number of multiplications necessary for solving two linear systems

$$\mathbf{A}_1 \mathbf{x} = \mathbf{b}, \quad \mathbf{A}_2 \mathbf{x} = \mathbf{b}, \quad (4)$$

where \mathbf{A}_1 and \mathbf{A}_2 are non-singular square matrices that differ only by one element:

$$\mathbf{A}_2 - \mathbf{A}_1 = \alpha \mathbf{e}_i \mathbf{e}_j^T, \quad (5)$$

where \mathbf{e}_i is the i -th column of the identity matrix.

Hint: Recall the Sherman-Morrison formula

$$(\mathbf{A} + \mathbf{u} \mathbf{v}^T)^{-1} = \mathbf{A}^{-1} - \frac{\mathbf{A}^{-1} \mathbf{u} \mathbf{v}^T \mathbf{A}^{-1}}{1 + \mathbf{v}^T \mathbf{A}^{-1} \mathbf{u}}. \quad (6)$$

3. The following algorithm can be used for solving the equation

$$\mathbf{U}\mathbf{x} = \mathbf{b}, \quad (7)$$

where \mathbf{U} is an upper triangular matrix:

```
UPPER TRIANGULAR( $\mathbf{U}, \mathbf{x}$ )
1  for  $k \leftarrow n, n-1, \dots, 1$ 
2  do
3    for  $i \leftarrow k+1, k+2, \dots, n$ 
4    do
5       $x_k \leftarrow x_k - u_{k,i} x_i$ 
6     $x_k \leftarrow x_k / u_{k,k}$ 
```

The algorithm is initialized with the right-hand-side vector \mathbf{b} and overwrites its elements with the elements of the solution vector \mathbf{x} . The analogous algorithm for a lower triangular matrix is

```
LOWER TRIANGULAR( $\mathbf{L}, \mathbf{x}$ )
1  for  $k \leftarrow 1, 2, \dots, n$ 
2  do
3    for  $i \leftarrow 1, 2, \dots, k-1$ 
4    do
5       $x_k \leftarrow x_k - l_{k,i} x_i$ 
6     $x_k \leftarrow x_k / l_{k,k}$ 
```

Both algorithms access the elements of the corresponding matrices *by row* and use the inner loop to compute the dot product of two vectors. On many computers, the dot product algorithm

```
DOT PRODUCT( $a, \mathbf{x}, \mathbf{y}$ )
1  for  $i \leftarrow 1, 2, \dots, n$ 
2  do
3     $a \leftarrow a + x_i y_i$ 
4
```

is less efficient than the scaled vector addition algorithm

```
ADD SCALED VECTOR( $a, \mathbf{x}, \mathbf{y}$ )
1  for  $i \leftarrow 1, 2, \dots, n$ 
2  do
3     $y_i \leftarrow y_i + a x_i$ 
```

because the latter can be easily performed in parallel.

Modify the upper and lower triangular inversion algorithms so that they access the corresponding matrices *by column*. Show that this transforms the dot product algorithm in the inner loop to the scaled vector addition algorithm.

4. (Programming) In this assignment, we revisit the method of least-squares polynomial approximation. Consider a function $f(x)$, measured at a number of points x_1, x_2, \dots, x_n and approximated with the sum of Chebyshev polynomials

$$f(x_i) \approx \sum_{k=0}^m c_k T_k(x_i), \quad i = 1, 2, \dots, n \quad (8)$$

In the matrix form, the system of approximate equations is

$$\mathbf{f} \approx \mathbf{A} \mathbf{c}, \quad (9)$$

where \mathbf{f} is the vector with elements $f(x_i)$, \mathbf{c} is the vector with the elements c_k , and the $n \times (m+1)$ matrix \mathbf{A} has the elements $a_{ik} = T_k(x_i)$. The method of least squares leads to the square system

$$\mathbf{A}^T \mathbf{A} \mathbf{c} = \mathbf{A}^T \mathbf{f}, \quad (10)$$

which can be solved for the unknown coefficient vector \mathbf{c} .

The approximation algorithm consists of the following steps:

- (a) Form the matrix \mathbf{A} .

The algorithm that utilizes the recursive relationship for Chebyshev polynomials is

CHEBYSHEV MATRIX(\mathbf{x}, \mathbf{A})

```

1  for  $i \leftarrow 1, 2, \dots, n$ 
2  do
3       $a_{i,0} \leftarrow 1$ 
4       $a_{i,1} \leftarrow x_i$ 
5      for  $k \leftarrow 1, 2, \dots, m-1$ 
6      do
7           $a_{i,k+1} \leftarrow 2x_i a_{i,k} - a_{i,k-1}$ 

```

- (b) Form the normal matrix $\mathbf{C} = \mathbf{A}^T \mathbf{A}$.

NORMAL MATRIX(\mathbf{A}, \mathbf{C})

```

1  for  $i \leftarrow 0, 1, 2, \dots, m$ 
2  do
3      for  $j \leftarrow 0, 1, 2, \dots, i$ 
4      do
5           $c_{i,j} \leftarrow 0$ 
6          for  $k \leftarrow 1, 2, \dots, n$ 
7          do
8               $c_{i,j} \leftarrow c_{i,j} + a_{k,i} a_{k,j}$ 

```

The algorithm fills only the lower triangular part of \mathbf{C} .

- (c) Form the right-hand side $\mathbf{b} = \mathbf{A}^T \mathbf{f}$

RIGHT-HAND SIDE(**A**, **f**, **b**)

```

1  for  $k \leftarrow 0, 1, 2, \dots, m$ 
2  do
3       $b_k \leftarrow 0$ 
4      for  $i \leftarrow 1, 2, \dots, n$ 
5      do
6           $b_k \leftarrow b_k + a_{i,k} f_i$ 

```

(d) Cholesky factorization of $\mathbf{C} = \mathbf{L}\mathbf{L}^T$

CHOLESKY(**C**)

```

1  for  $k \leftarrow 0, 1, 2, \dots, m$ 
2  do
3       $c_{k,k} = \sqrt{c_{k,k}}$ 
4      for  $i \leftarrow k + 1, k + 2, \dots, m$ 
5      do
6           $c_{i,k} = c_{i,k} / c_{k,k}$ 
7      for  $j \leftarrow k + 1, k + 2, \dots, m$ 
8      do
9          for  $i \leftarrow j, j + 1, \dots, m$ 
10         do
11              $c_{i,j} = c_{i,j} - c_{i,k} c_{j,k}$ 

```

The algorithm overwrites the lower triangular part of \mathbf{C} with \mathbf{L} .

- (e) Upper and lower triangular inversion using the Cholesky factor \mathbf{L} and the right-hand side \mathbf{b} . The output is the coefficient vector \mathbf{c} .
- (f) At each point x , evaluate the approximation using the fast algorithm from Homework 7:

CHEBYSHEV SUM(x , \mathbf{c})

```

1   $\hat{c}_1 \leftarrow 0$ 
2   $\hat{c}_0 \leftarrow c_n$ 
3  for  $k \leftarrow n - 1, n - 2, \dots, 0$ 
4  do
5       $t \leftarrow \hat{c}_1$ 
6       $\hat{c}_1 \leftarrow \hat{c}_0$ 
7       $\hat{c}_0 \leftarrow c_k + 2x \hat{c}_0 - t$ 
8  return ( $\hat{c}_0 - x \hat{c}_1$ )

```

Using the data from Homework 5

y	24	28	32	36	48	52	56	60	64	68	72	76	80	84	88	92	94	98
p	8	15	28	6	21	25	14	20	11	12	16	19	28	20	11	25	30	28

where y stands for the year, and p stands for the number of Olympic points, perform the steps above to approximate the dependence $p(y)$. Output the coefficient vector \mathbf{c} and the Cholesky factor \mathbf{L} for $m = 1, 2, 4, 8$ and plot the corresponding approximations in the interval $[22, 100]$ with the step size of one year.