

Synthetic model building for training neural networks in a Jupyter notebook

Robert G. Clapp

Abstract

Neural networks require tens of thousands of correctly labeled datasets, something that does not exist in reflection seismology. Synthetic data can be used to help fill this data gap. In this paper I describe an update to a synthetic model generator aimed at producing realistic labeled datasets for training neural nets.

Introduction

Synthetic data can be used to help train neural networks . In a previous work I described a simple basin modeling approach to create realistic synthetics . In this paper I extend that work, rewriting the modules in C++, binding to python with pybind , and using python to create the modules. I will be reviewing the basic synthetic generation modules. I then will describe how to use the python interface. I will finish by talking about the types of synthetic models I am generating and future plans for expansion of the code.

Running the code

The basic idea of the synthetic model generator is to describe a series of geologic events such as deposition, faulting, emplacement, and compression. Each event is described by a series of parameters that attempt to simulate the geologic event.

The original version of the synthetic model generator was written in Fortran. To build a model meant writing/generating parameters file hundreds of lines long. Changing a single parameter required regenerating the entire model.

This new version keeps the same idea of building a model from a series of geologic events. The code is rewritten in C++ and parallelized using Thread Building blocks . Each module is wrapped using pybind11 into the python module `pySyntheticGen`, which in turned is wrapped in the pure python module `syntheticGen`.

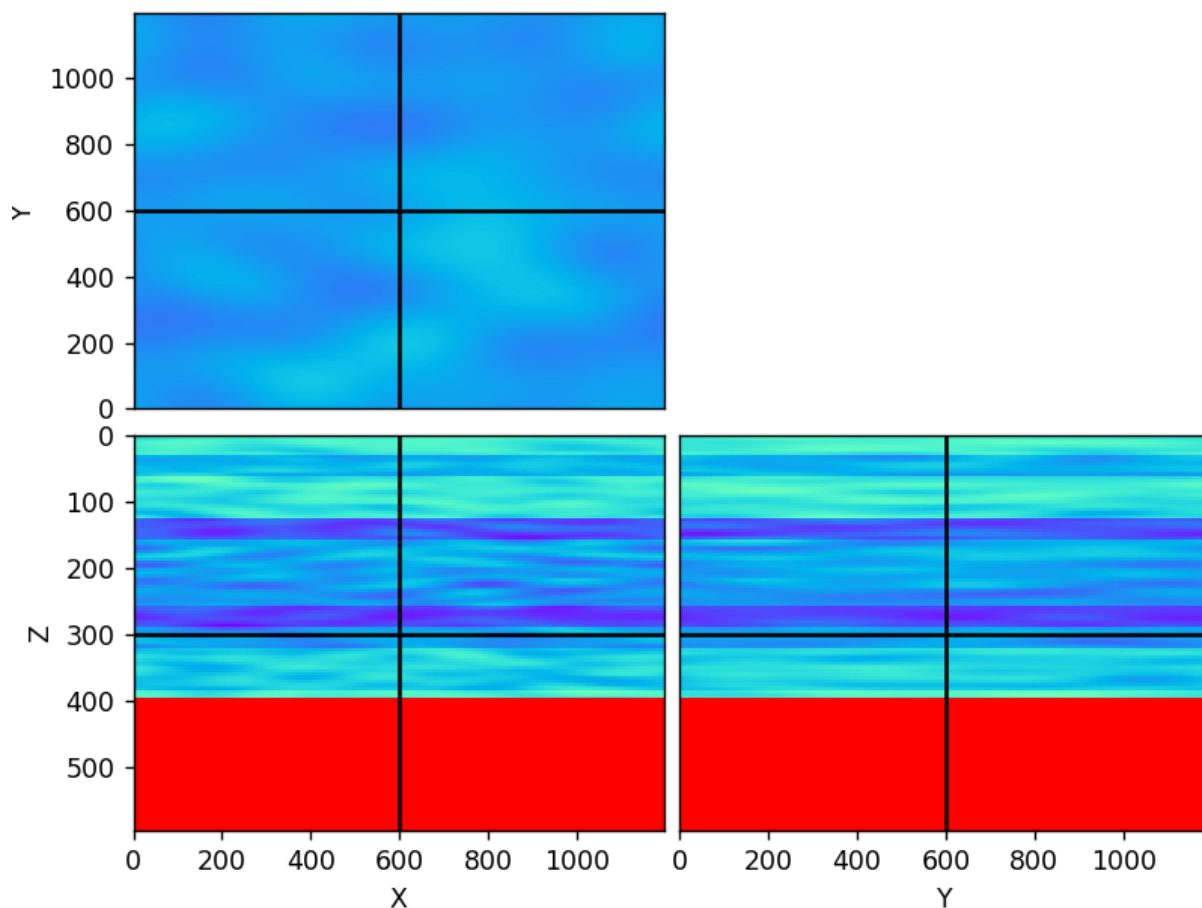
To start a new model we import the `syntheticGen` module, the full self-doc can be found in the appendix. We initialize the model by describing the size of the domain in x and y. For our first example we will create a small model with 300 samples in x and y.

```
In [1]: import pySepVector
import syntheticModel
mod=syntheticModel.geoModel(500300,ny=300)
```

The most basic module is deposition. The deposition model adds a layer with a given parameter value (such as velocity). We can also decide to add spatial variations and interbed layers. In this case we will add two different layers. The first layer with an average velocity of 2700 m/s, a thickness of 100 samples. We will allow interbedding, where the velocity can vary by 30%. In addition we will allow variation as a function of space.

```
In [2]: %matplotlib notebook
from latex_envs.latex_envs import figcaption
import Cubeplot
mod.deposit(prop=2700,thick=100,var=.3,dev_pos=.1,layer=25,dev_layer=.3,
layer_rand=.3,band2=.01, band3=.01)
figcaption("An example of using the deposition module.", label="fig:depo
sition")
b=Cubeplot.plot(mod.getProp("velocity"))
```

Caption: An example of using the deposition module.



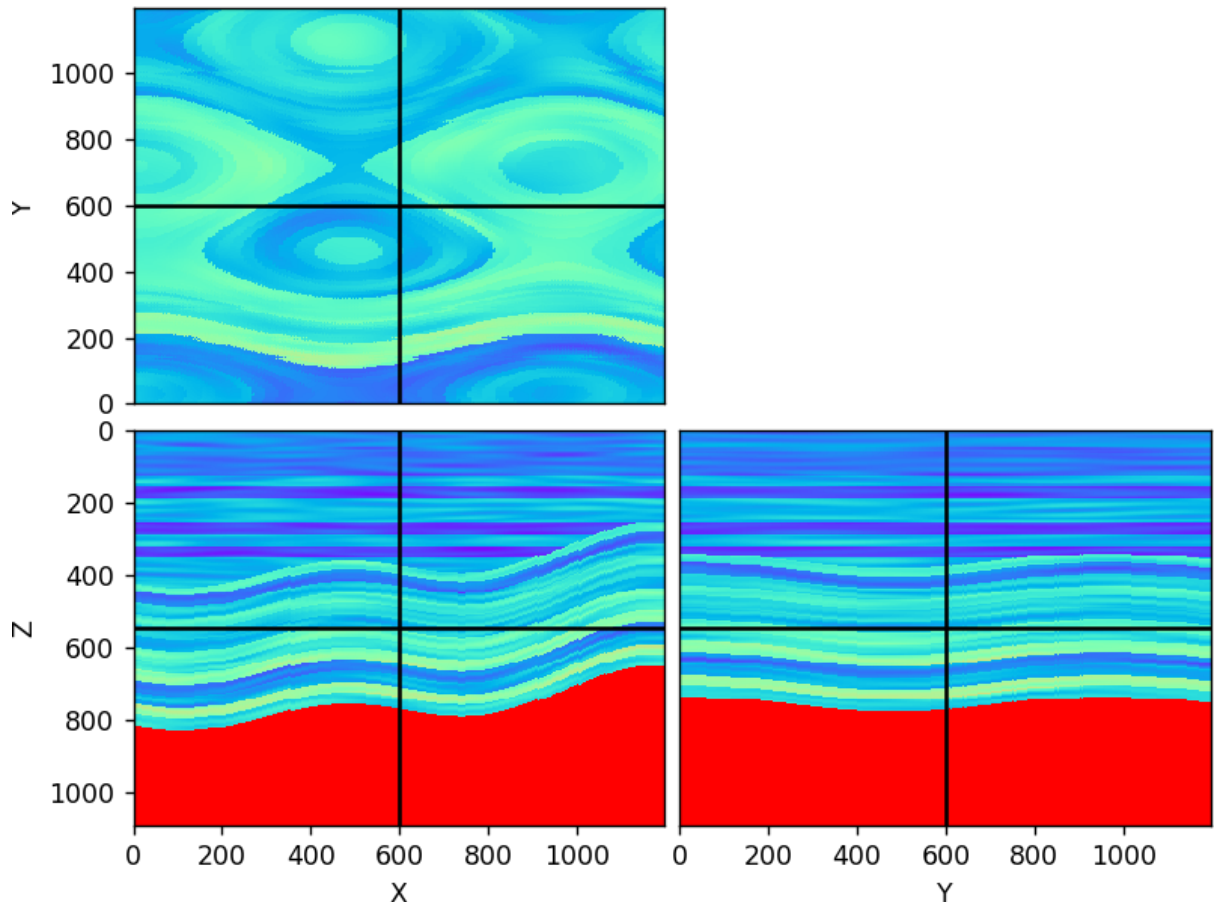
We can choose to introduce a compressional event. A compressional event produce an anticline-syncline pattern in the current model We can decide the angle of compression, the amount of uplift, and how much we want the pattern to vary spatially.

```
In [3]: %matplotlib notebook

mod=syntheticModel.geoModel(nx=300,ny=300)
mod.deposit(prop=2700,thick=100,var=.3,dev_pos=.1,layer=25,dev_layer=.3,
layer_rand=.3,band2=.01, band3=.01)
mod.squish(max=150,random_inline=2.,random_crossline=3.,aziumth=40.,wave
length=.2)
mod.deposit(prop=2400,thick=50,var=.3,dev_pos=.1,layer=25,dev_layer=.2,1
ayer_rand=.3)
figcaption("An example of using the compressional module.", label="fig:c
ompress")

c=Cubeplot.plot(mod.getProp("velocity"))
```

Caption: An example of using the compressional module.

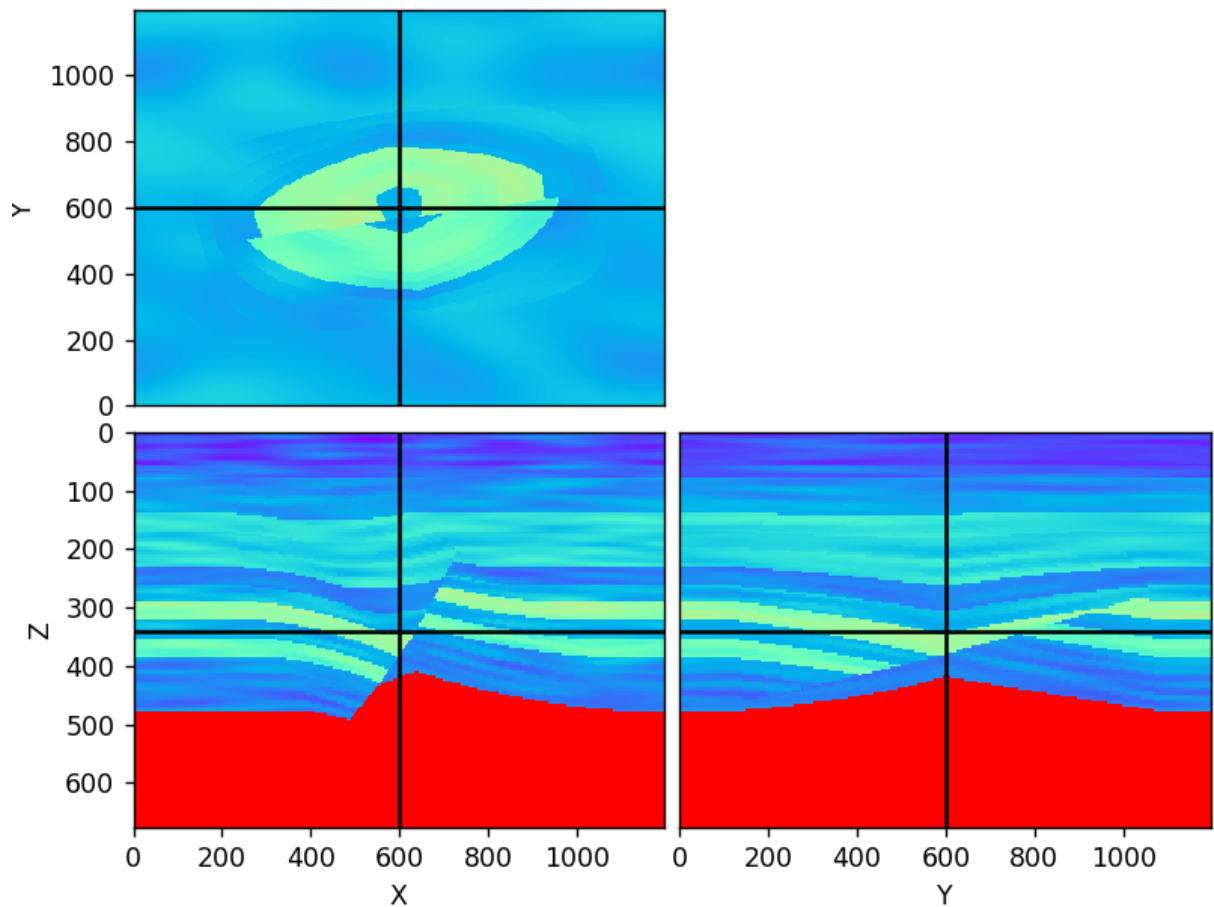


We can also add faults. Fault planes can be thought of as the surface of cylinder. Everything inside the cylinder rotates in one direction, everything outside the other direction. The further away the cylinder's focus, the more the fault looks like a plane. The bigger the angular rotation the more fault throw. The fault is centered at a given location, as we move away from that location along the cylinder the rotation lessens. We expect less rotation as we move away from the cylinder's edge.

```
In [4]: %matplotlib notebook
mod=syntheticModel.geoModel(nx=300,ny=300)
mod.deposit(prop=2700,thick=100,var=.3,dev_pos=.1,layer=25,dev_layer=.3,
layer_rand=.3,band2=.01, band3=.01)
mod.fault(begx=.5,begy=.5,begz=.5,daz=800,dz=700,azimuth=10,theta_die=12
, theta_shit=7,dist_die=.4,perp_die=.4)
mod.deposit(prop=2400,thick=20,var=.3,dev_pos=.1,layer=25,dev_layer=.2,l
ayer_rand=.3)
figcaption("An example of using the fault module.", label="fig:fault")

d=Cubeplot.plot(mod.getProp("velocity"))
```

Caption: An example of using the fault module.

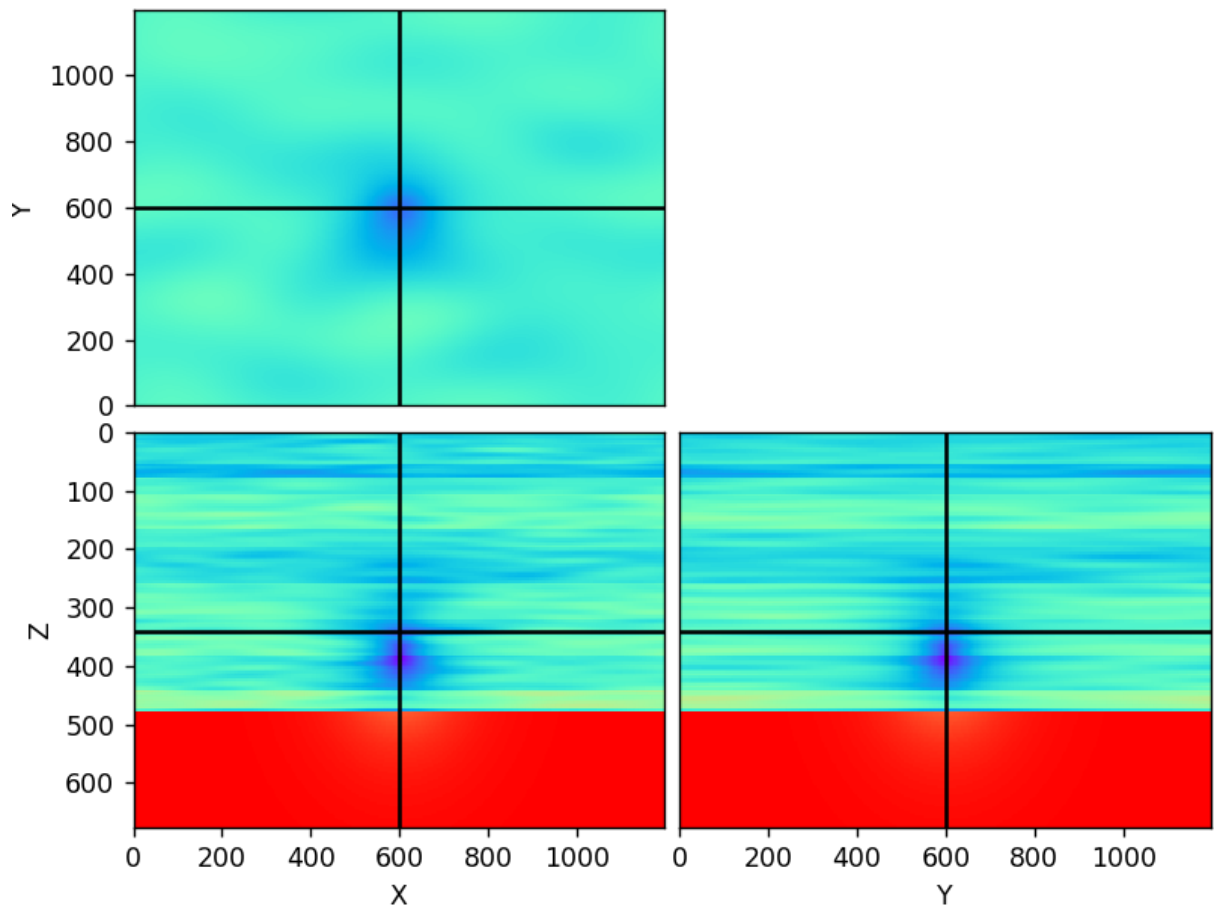


We can add Gaussian anomalies into our model by describing their location and amplitude.

```
In [5]: %matplotlib notebook
mod=syntheticModel.geoModel(nx=300,ny=300)
mod.deposit(prop=2700,thick=100,var=.3,dev_pos=.1,layer=25,dev_layer=.3,
layer_rand=.3,band2=.01, band3=.01)
mod.gaussian(vplus=-1000.,var=40.)
mod.deposit(prop=2400,thick=20,var=.1,dev_pos=.1,layer=25,dev_layer=.2,1
ayer_rand=.3)
figcaption("An example of using the Gaussian module.", label="fig:gauss
ian")

d=Cubeplot.plot(mod.getProp("velocity"))
```

Caption: An example of using the Gaussian module.

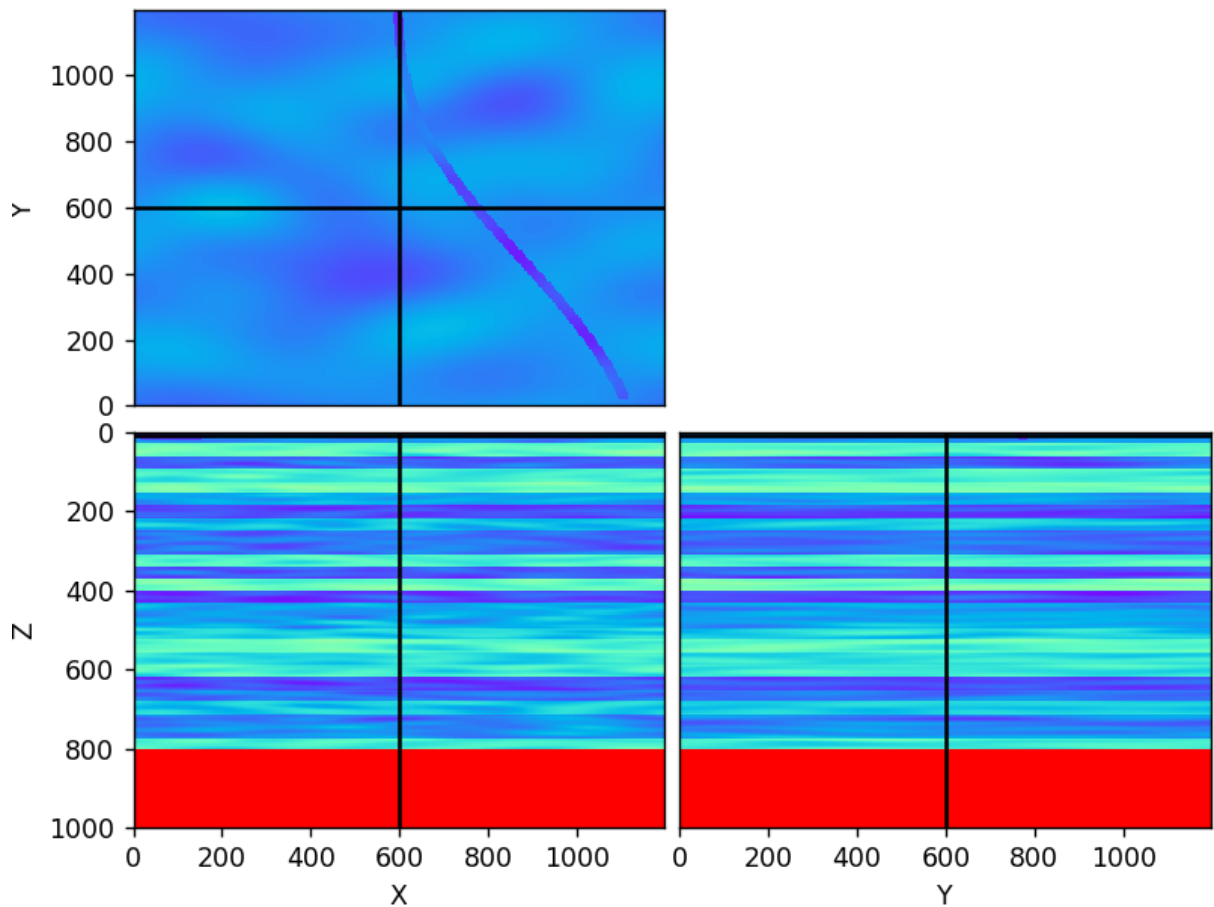


We can add river channels to our model by describing the beginning location and angle. We can add partial fill into the river channels and have their location move as a function of depth in a logical meandering stream pattern.

```
In [6]: %matplotlib notebook
mod=syntheticModel.geoModel(nx=300,ny=300)
mod.deposit(prop=2700,thick=200,var=.3,dev_pos=.1,layer=25,dev_layer=.3,
layer_rand=.3,band2=.01, band3=.01)
mod.erodeRiver()
mod.deposit(prop=2400,thick=1,var=.1,dev_pos=.1,layer=25,dev_layer=.2,la
yer_rand=.3)
figcaption("An example of using the erode river module.", label="fig:ri
ver")

d=Cubeplot.plot(mod.getProp("velocity"),slice1=2)
```

Caption: An example of using the erode river module.

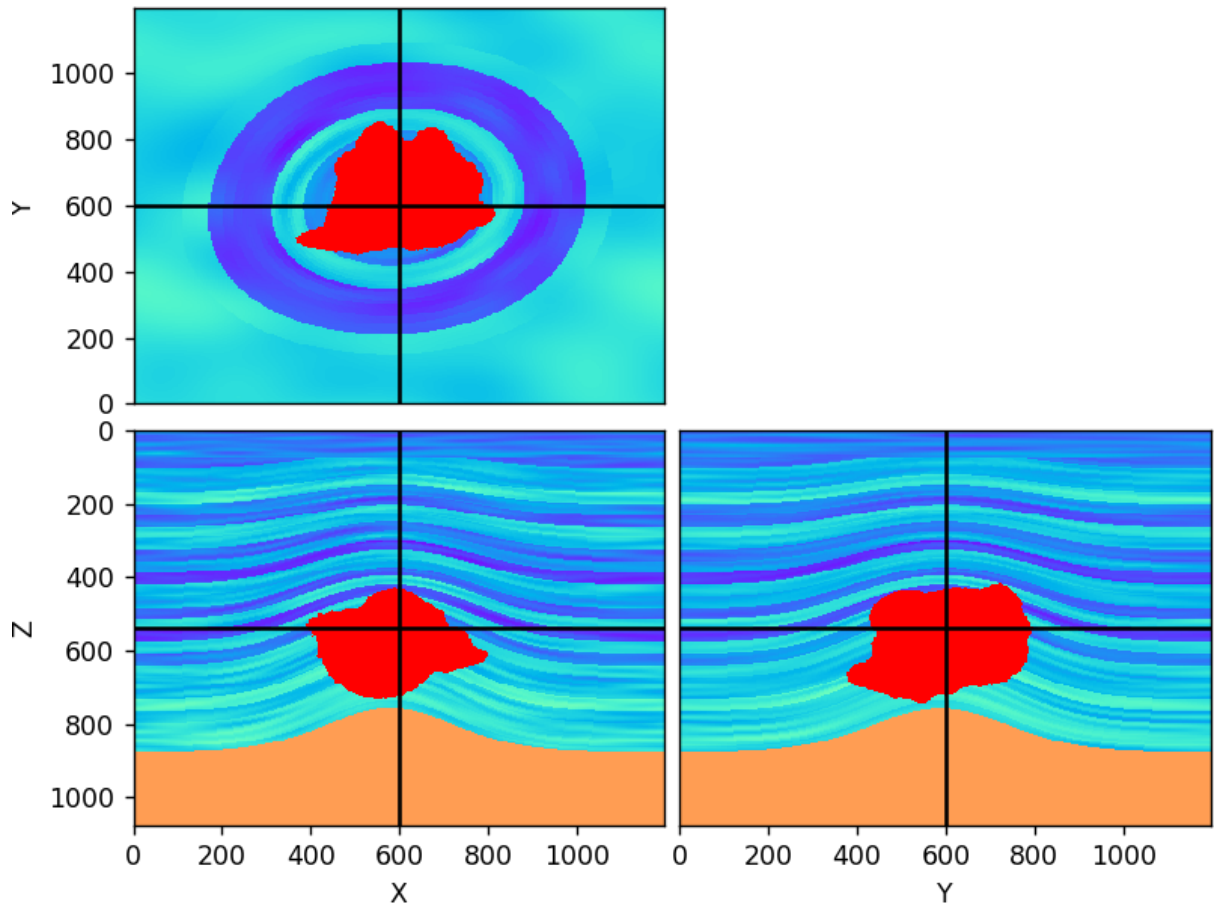


We can emplace salt. The salt is created by putting random sized perturbations within in a given area. Random, relatively low wavenumber, conductivity is then assigned. The heat equation is used to merge the perturbations.

```
In [7]: %matplotlib notebook
mod=syntheticModel.geoModel(nx=300,ny=300)
mod.deposit(prop=2700,thick=200,var=.3,dev_pos=.1,layer=25,dev_layer=.3,
layer_rand=.3,band2=.01, band3=.01)
mod.implace(ntSteps=50)
mod.deposit(prop=2400,thick=20,var=.1,dev_pos=.1,layer=25,dev_layer=.2,
layer_rand=.3)
figcaption("An example of using the implace module.", label="fig:implac
e")

d=Cubeplot.plot(mod.getProp("velocity"))
```

Caption: An example of using the implace module.



How good do the synthetics need to be?

Training a neural network at some level is just solving a non-linear inversion problem. The key to solving a non-linear problem is finding the neighborhood the solution lives in. One way to think about pre-training and transferring learning is that it is attempting to get the network into generally the correct neighborhood. This hypothesis can lead to several interesting questions.

- Can we build an initial network that generally understands seismic migrated volumes?
- Do we need to have different networks for different geologic basins?
- Can we slowly navigate into the correct neighborhood by training with a series of more realistic synthetic datasets?

This third question leads us to a potential solution for our lack of data problem. Creating geologic models is relatively cheap (minutes on a single machine). Finite difference modeling/migration is expensive hours/days on 10s of machines for a single dataset. A possible approach is to create hundreds of synthetic migrated volumes by calculating impedances and then convolving with a wavelet. A smaller set of modeled/migrated datasets can then be used to further improve the network. Such an approach would also help with the first two questions. For example, synthetics mimicking different basins can be generated to create basin specific networks.

Packaging

There are several ways to use the `syntheticGen` code. You can clone the code from Stanford's School of Earth and Environment's gitlab site . Building the code requires several other packages that also publicly available from that website. You can find all of the dependencies by looking in the `docker` sub-folder. You can download the latest version inside a docker from `rgc007/synthetic-gen`. This docker is accessible through a Jupyter notebook . Finally, there should be a link off the sep website where you found this paper to bring up an interactive document.

Future plans

There are several different modules that could be improved upon. The salt generation still does not consistently provide realistic salt geometries. The deposition model could benefit from using a similar heat equation approach to output different sediments rather than smoothing random numbers. Adding the abilities to do turbidites, emplacement, and other geologic features would also be useful improvements.

Finally, it might be useful to rewrite some of the code to run on GPUs. The sheer number of models that will be needed for some machine learning problems will make speed of model generation even more important.

Conclusion

Synthetic data can be used to help train neural networks. Simplified basin modeling is one approach to creating synthetics. To improve the codes ease of use the C++ base code is wrapped in python interfaces. A Jupyter notebook is used to further enhance the code's accessibility.

Bibliography

Clapp, Robert. 2018. Geologic Synthetic Model Generator. <http://zapad.stanford.edu/SEP-external/syntheticModel> (<http://zapad.stanford.edu/SEP-external/syntheticModel>).

Clapp, Robert G. 2014. Synthetic Model Building Using a Simplified Basin Modeling Approach. SEP. <http://sepwww.stanford.edu/public/docs/sep155> (<http://sepwww.stanford.edu/public/docs/sep155>).

Jakob, Wenzel, Jason Rhinelander, and Dean Moldovan. 2016. “pybind11 — Seamless Operability between C++11 and Python.” <https://github.com/pybind/pybind11> (<https://github.com/pybind/pybind11>).

Kluyver, Thomas, Benjamin Ragan-Kelley, Fernando Pérez, Brian E Granger, Matthias Bussonnier, Jonathan Frederic, Kyle Kelley, et al. 2016. “Jupyter Notebooks—a Publishing Format for Reproducible Computational Workflows.” In ELPUB, 87–90.

Le, Tuan Anh, Atilim Giineş Baydin, Robert Zinkov, and Frank Wood. 2017. “Using Synthetic Data to Train Neural Networks Is Model-Based Reasoning.” In Neural Networks (IJCNN), 2017 International Joint Conference on, 3514–21. IEEE.

Merkel, Dirk. 2014. “Docker: Lightweight Linux Containers for Consistent Development and Deployment.” Linux Journal 2014 (239): 2.

Reinders, James. 2007. Intel Threading Building Blocks: Outfitting C++ for Multi-Core Processor Parallelism. O’Reilly Media, Inc.

Van Baarsen, Jeroen. 2014. GitLab Cookbook. Packt Publishing Ltd.

Appendix

```
In [8]: help(syntheticModel.geoModel)
```

Help on class geoModel in module syntheticModel:

```

class geoModel(builtins.object)
  Methods defined here:

  __init__(self, **kw)
    Create a new geomodel
    nx - (100) Number of samples in x
    ox - (0.) First sample in x
    dx - (4.) Sampling in x
    ny - (100) Number of samples in y
    oy - (0.) First sample in y
    dy - (4.) Sampling in y
    dz - (4.) Sampling in z
    basement - (4000.) Basement property
    nbasement - (50) Initial number of samples in the basement
    properties - (['velocity']) Properties to model

  compact(self, **kw)
    Compact layers
    compact - [0.] Compact layers

  deposit(self, **kw)
    Deposit a layer
    base_param - ["velocity"] Base param to base all other properti
es
    band1 - [.60] Bandpass parameter axis 1 property dependent vs.
band1=
    band2 - [.05] Bandpass parameter axis 2 property dependent
    band3 - [.05] Bandpass parameter axis 3 property dependent
    ratio - [.4] Base ratio of property to main property
    var - [.0] Variance from main parameter
    layer_rand - [.5] Randomness variation within layer
    layer - [9999.] Layer Base value
    prop - [1.4]
    dev_layer - [0.]
    dev_pos - [0.]
    thick - [0.]

  erodeBowl(self, **kw)
    Erode a bowl shape
    center2 - [.5] Create a bowl fractional amount into model2
    center3 - [.5] Create a bowl fractional amount into model3
    width2 - [.01] Width of bowl fractional to length of axis 2
    width3 - [.01] Width of bowl fractional to length of axis 3
    depth - [.01] Depth of bowl fractional to length of axis 1
    fill_depth - [.01] Fill depth of bowl fractional to length of a
xis 1
    fill_prop - [.3] Fill value, dependent on model parameter

  erodeFlat(self, **kw)
    Erode a flat surface
    depth [.1] Fractional depth (axis 1) to slice off

  erodeRiver(self, **kw) SEP-172
    Erode a river shape
    start2 - [.5] Position (relative to axis length) to start river

```

```

start3 - [.0] Position (relative) to start river
dist    - [1.4] Length (relative) of river
azimuth - [0.] Angle for river
fill_prop - [0.] Fill value for deposition for river channel
fill_depth - [0.] Fill depth for river channel
nlevels - [1] Number of river channel bends to layout
wavelength - [.01] Wavelength multiplier for random river path
waveamp - [.01] Wave amplitude multiplier
thick   - [.3] Thickness of river channel

```

```

fault(self, **kw)

```

```

    Fault model
    azimuth - [0.] Azimuth of fault
    begx    - [.5] Relative location of the beginning of fault x
    begy    - [.5] Relative location of the beginning of fault y
    begz    - [.5] Relative location of the beginning of fault z
    dz      - [0.] Distance away for the center of a circle in z
    daz     - [.01] Distance away in azimuth
    perp_die- [0.1] Dieoff of fault in in perpdincular distance
    deltaTheta- [.1] Dieoff in theta away from the fault
    dist_die- [0.] Distance dieoff of fault
    theta_die- [0.01] Distance dieoff in thetat
    theta_shift- [.1] Shift in thetat for fault
    dir     - [.1] Direction of fault movement

```

```

gaussian(self, **kw)

```

```

    Add a gaussian anomaly
    center2 - [.5] Relative position of anomaly axis2
    center1 - [.5] Relative position of anomaly axis1
    center3 - [.5] Relative position of anomaly axis3
    vplus   - [1.] Value of anomaly to add
    var     - [.1] Relative variance of anomaly

```

```

getHyper(self)

```

```

getMinMax(self, prop)

```

```

getProp(self, prop)
    Get model property

```

```

implace(self, **kw)

```

```

    Add feature to model
    emplace - [True] Whether or not emplace a body into the model
    prop    - [4500.] Value to set body
    center1,center2,center3 [.5] Relative location of center of an

```

omaly

```

    axis1,axis2,axis3 - [.3] Relative axes for anomaly
    azimuth - [0.] Rotation azimuth for body
    pctRemove - [30.] Percentage of points to remove
    conform - [True] Conform model aroundn shape introduced
    down_decrease - [True] Decrease below anomaly
    down_dist - [0.] Distance down to change model
    ntSteps- [50] Number of time steps
    down_amount [0.] Down amount

```

```

parseParams(self, ks, typ, intM, floatM, stringM, boolM)
    Internal function to parse parameters

```

```
squish(self, **kw)
    Squish a model
    azimuth - [0.] Azimuth for squishing
    max - [50.] Maximum shift in z
    wavelength- - [1.] Wavelength scaling
    random_inline - [.5] Random inline
    random_crossline - [.5] random crossline
```

Data descriptors defined here:

```
__dict__
    dictionary for instance variables (if defined)

__weakref__
    list of weak references to the object (if defined)
```