

SEISMIC VELOCITY ESTIMATION BY BEAM STACK

A DISSERTATION
SUBMITTED TO THE DEPARTMENT OF GEOPHYSICS
AND THE COMMITTEE ON GRADUATE STUDIES
OF STANFORD UNIVERSITY
IN PARTIAL FULFILLMENT OF THE REQUIREMENTS
FOR THE DEGREE OF
DOCTOR OF PHILOSOPHY

By
Biondo Biondi
March 1990

© Copyright 1990
by
Biondo Biondi

printed as Stanford Exploration Project No. 64
by permission of the author

Copying for all internal purposes of the sponsors
of the Stanford Exploration Project is permitted

Seismic velocity estimation by beam stack

Biondo L. Biondi, Ph.D.

Stanford University, 1990

ABSTRACT

Imaging seismic data requires detailed knowledge of the propagation velocity of compressional waves in the subsurface. In conventional seismic processing, the interval velocity model is derived from stacking velocities. Stacking velocities are determined by measuring the coherency of the reflections along hyperbolic trajectories. This conventional method cannot be applied in geologically complex areas because the conversion of stacking velocities to interval velocities assumes a horizontally stratified medium and mild lateral velocity variations.

The tomographic velocity estimation proposed in this thesis can be applied when there are dipping reflectors and strong lateral variations. The method is based on the measurements of moveouts by beam stacks. A beam stack measures the local coherency of the reflections along curved trajectories (hyperbolic or parabolic). Being a local operator, the beam stack can provide information on non-hyperbolic moveouts in the data. This information is more reliable than the traveltimes of the reflections picked directly from the data because many seismic traces are used for computing beam stacks. The resolution of local coherency operators can be improved by substituting non-linear coherency criteria for conventional stack. At the end of this thesis, I present a new method for estimating coherency spectra based on the eigenstructure of the covariance matrix of the data.

I estimate seismic velocity by iteratively searching for the velocity model that best predicts the events in the beam-stacked data. The estimation method does not require a preliminary picking of the data because it directly maximizes the beam stacks energy at the traveltimes and surface locations predicted by ray tracing. The advantages of this formulation is the possibility of guiding the detection of the events in the beam-stacked data by imposing physical constraints on the velocity model. I solve the maximization problem using optimization algorithms based on the derivatives of the objective function with respect to the velocity model. To compute these derivatives I derived a linear operator

that relates perturbations in velocity to the observed changes in beam stacks kinematics.

The proposed tomographic method successfully estimated velocity anomalies from synthetic data and field data.

Acknowledgments

I am grateful to many people for their guidance and assistance. Jon Clærbout has not only taught me seismic processing but he has been a daily example of excellence and dedication in research. He created an outstanding research environment where academic freedom and efficient organization are admirably combined. Fabio Rocca advised me throughout my studies at Stanford with generous enthusiasm. His insights and wide knowledge are at the origin of many ideas that are presented in this dissertation. Francis Muir provided encouragements and original viewpoints.

All of my fellow students at the Stanford Exploration Project (SEP) have contributed to make my graduate studies a unique and gratifying experience. The ones that had the most direct influence on the development of the velocity estimation presented in this thesis are Chuck Sword and Clement Kostov. I also benefited from several discussions with John Etgen, Paul Fowler, Bill Harlan, Rick Otolini, John Toldi, Jos van Trier and Marta Woodward. Joe Dellinger often helped me solve graphics problems.

The financial support for my work came from the sponsors of the Stanford Exploration Project. I have also greatly benefited from many informal discussions with representatives of the sponsoring organizations during the annual SEP meetings.

AGIP - Hydrocarbon Exploration and Deutsche Shell provided the Adriatic Sea data through the kind efforts of Antonio Carlini. The offshore California data were donated to SEP by British Petroleum.

I would like to thank Fabio and Clement for useful suggestions on the presentation of this thesis. Fannie Toldi edited the text with care and expertise.

Last, but not least, I would like to thank Nazila, my parents and my sister. Their love, support and understanding have given me the strength for completing this work.

Table of Contents

Abstract	iii
Acknowledgments	v
1 Introduction	1
1.1 Velocity estimation from reflection seismic data	1
1.2 Conventional velocity analysis	2
1.3 Reflection tomography from beam-stacked data	3
1.3.1 Measuring reflections' moveouts by beam-stack	6
1.3.2 Model-driven detection of primary reflections	8
1.3.3 Velocity model and reflectors' geometry	9
1.4 Assumptions and limitations	10
2 Beam-stack and interval velocity	13
2.1 Overview	13
2.2 Data decomposition using beam stack	13
2.2.1 Local slant stack of common midpoint gathers	14
2.2.2 Beam stack of common midpoint gathers	15
2.2.3 Velocity resolution and beam stack parameters	20
2.2.4 Two-dimensional beam stack	21
2.3 Principles of velocity estimation	23
2.3.1 Using ray tracing to model beam-stacked data	24
2.3.2 Maximization of beam stacks' energy	27
2.3.3 Smooth parametrization of the velocity model	28
2.4 Effects of a velocity anomaly on beam-stacked data	29
2.5 Conclusions	36

3	Interval velocity estimation	39
3.1	Overview	39
3.2	The tomographic back-projection operator	39
3.2.1	The objective function and its gradient	40
3.2.2	Computation of the back-projection operator	44
3.3	Algorithms for solving the optimization problem	50
3.3.1	Global convergence–Conjugate gradient algorithm	50
3.3.2	Local convergence–Gauss-Newton algorithm	54
3.3.3	Synthetic example	56
3.4	Conclusions	57
4	Estimation of a velocity anomaly from field data	61
4.1	Analysis of the data set	61
4.1.1	Effects of the anomaly on prestack data	62
4.2	The estimation results	65
4.2.1	Using beam-stacked data to check the estimation results	73
4.3	Conclusions	73
5	High-resolution ray-parameter spectra using eigenstructure methods	77
5.1	Introduction and overview	77
5.2	The narrow-band method	80
5.2.1	Properties of the eigenstructure of the data covariance matrix	83
5.2.2	Estimation of the number of wavefronts	83
5.2.3	Estimation of the wavefront ray parameters	85
5.2.4	Correlated sources and spatial smoothing	86
5.3	Comparison with the stacking method	87
5.3.1	Geometric interpretation	88
5.4	The wide-band method	91
5.5	Application to local slant stacks	94
5.6	Conclusions	99
A	Resolution of local stacks	101
A.1	Ray-parameter resolution of local stacks	101
A.2	Spatial resolution of local stacks	103

A.3	The upper bound in the spatial resolution of local slant stacks	104
A.4	Conclusions	106
B	Relations among ray parameters in field coordinates and ray parameters in midpoint-offset coordinates	109
C	Ray tracing in a 2-D velocity model	111
C.1	Computing the raypath and traveltime	111
C.2	Computing the derivatives with respect to the slowness model	112
D	B-spline parametrization of the velocity model	117
E	Derivation of the back-projection operator	119
	Bibliography	123

List of Figures

1.1	Adriatic Sea stacked section	4
1.2	Adriatic Sea migrated section	5
1.3	CMP gather with non-hyperbolic moveouts from the Adriatic data set . . .	7
1.4	Beam stacks of the reflection with non-hyperbolic moveout shown at 3.12 s in Figure 1.3	9
2.1	CMP gather from the Adriatic data set and its slant stacks	16
2.2	Comparison of beam stacks with local slant stacks of the gather shown in Figure 2.1	19
2.3	Constant-offset section from the Adriatic data set and its slant stacks . . .	22
2.4	Modeling beam stacks by ray tracing	25
2.5	Synthetic CMP gather with corresponding beam stacks, and velocity func- tion	26
2.6	Velocity model with a velocity anomaly and a dipping reflector	31
2.7	Nearest-offset section from the synthetic data set modeled assuming the velocity function shown in Figure 2.6	31
2.8	Synthetic CMP gather recorded far from the anomaly and its beam stacks .	32
2.9	Synthetic CMP gather recorded on a side of the anomaly and its beam stacks	33
2.10	Raypath perturbations for a CMP gather recorded on a side of the anomaly	33
2.11	Synthetic CMP gather recorded above the anomaly and its beam stacks . .	34
2.12	Raypath perturbations for a CMP gather recorded above the anomaly . . .	34
2.13	Beam stacks' offsets picked from the synthetic data	35
2.14	Beam stacks' traveltimes picked from the synthetic data	35
2.15	Comparison of the picked and the ray traced beam stacks' offsets	37
2.16	Comparison of the picked and the ray traced beam stacks' traveltimes . . .	37
3.1	Beam stacks before and after the transformation of the traveltime axis . . .	43

3.2	Back-projection operator in constant velocity	48
3.3	Cross-section of the back-projection operator in constant velocity	48
3.4	Back-projection operator in laterally varying velocity	49
3.5	Cross-section of the back-projection operator in laterally varying velocity	49
3.6	Velocity model with a velocity anomaly and a dipping reflector	58
3.7	Estimation result from synthetic data	58
3.8	Final estimation result from synthetic data	59
3.9	Cross-section of the final estimation result	59
4.1	Adriatic Sea stacked section	63
4.2	Beam stacks' slice correspondent to the reflector at 2 s in Figure 4.1	64
4.3	Beam stacks' slice correspondent to the reflector at 3.1 s in Figure 4.1	64
4.4	CMP gather with non-hyperbolic moveouts and its beam stacks	66
4.5	CMP gather with non-hyperbolic moveouts and its beam stacks	66
4.6	Contour plot of the anomalous velocity model superimposed onto the migrated section	68
4.7	Section migrated with the background velocity	69
4.8	Section migrated with the estimated velocity	70
4.9	Windows of migrations with the background velocity (Figure 4.7) and the estimated velocity (Figure 4.8)	71
4.10	Results of migrating the the top of the anticline with the background velocity and the estimated velocity	72
4.11	Beam stacks' slice correspondent to the reflector at 2 s in Figure 4.1	74
4.12	Beam stacks' slice correspondent to the reflector at 3.1 s in Figure 4.1	74
4.13	Beam stacks of the non-hyperbolic reflections shown in Figures 4.4 and 4.5	75
5.1	CMP gather from offshore California containing water-bottom multiples interfering with primaries	79
5.2	Beam stacks of the CMP gather shown in Figure 5.1 for two different lengths of the stacking trajectories	80
5.3	Subdivision of the original array for application of spatial smoothing	87
5.4	Geometric interpretation of the stacking spectrum and the eigenstructure spectrum	89

5.5	Stacking and eigenstructure ray parameter spectra for two uncorrelated plane waves	91
5.6	Stacking and eigenstructure ray parameter spectra for two correlated plane waves	92
5.7	Stacking and eigenstructure ray parameter spectra with data frequency from 15 to 100 Hz	96
5.8	Stacking and eigenstructure ray parameter spectra with data frequency from 15 to 70 Hz	97
5.9	Stacking and eigenstructure ray parameter spectra with data frequency from 15 to 33 Hz	98
A.1	Stacking spectrum for a monochromatic plane wave	103
A.2	Beam stacks of a synthetic gather	105
A.3	Local slant stacks of a synthetic gather	107