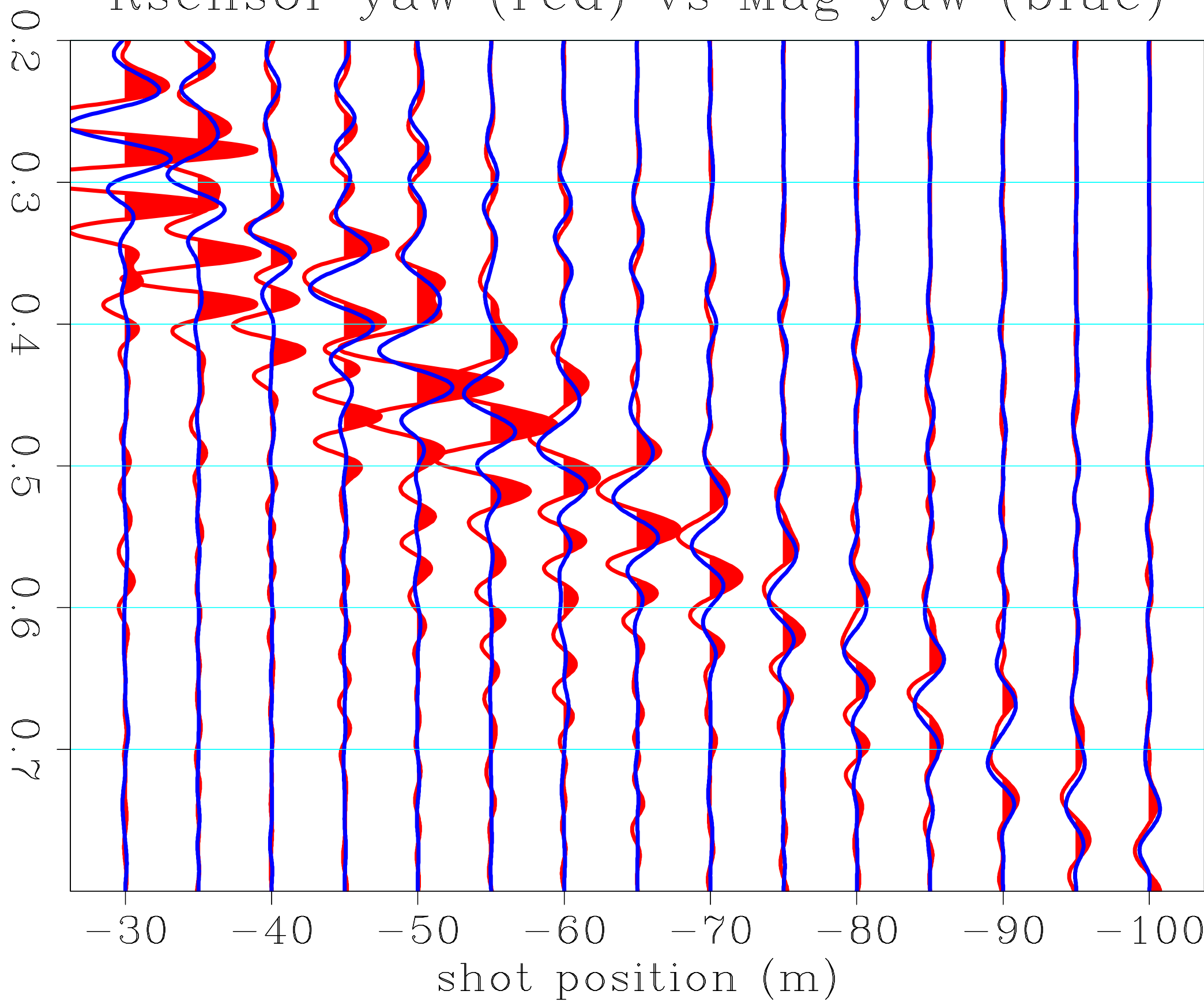


Rsensor yaw (red) vs Mag yaw (blue)

time(sec)



#