

MIGRATION AS AN ADJOINT OF UP-WARD CONTINUATION MODELING IN SHOT-PROFILE DOMAIN

Upward-continuation modeling in the shot-profile domain

Starting from the cross-correlation imaging condition in the shot-profile migration

$$r(\mathbf{x}, \mathbf{h}) = \sum_{\mathbf{x}_s} \sum_{\omega} p^*(\mathbf{x} - \mathbf{h}, \mathbf{x}_s, \omega) u(\mathbf{x} + \mathbf{h}, \mathbf{x}_s, \omega), \quad (1)$$

where $p(\mathbf{x}, \mathbf{x}_s, \omega)$ is the source wavefield for a single frequency ω at image point $\mathbf{x} = (x, y, z)$ with the source located at $\mathbf{x}_s = (x_s, y_s, 0)$; $u(\mathbf{x}, \mathbf{x}_s, \omega)$ is the receiver wavefield and $\mathbf{h} = (h_x, h_y, h_z)$ is the subsurface half-offset, and * stands for the complex-conjugate. We can compute the adjoint of equation 1 as:

$$p(\mathbf{x}, \mathbf{x}_s, \omega) = \sum_{\mathbf{h}} u(\mathbf{x} + \mathbf{h}, \mathbf{x}_s, \omega) r(\mathbf{x}, \mathbf{h}) \quad (2a)$$

$$u(\mathbf{x}, \mathbf{x}_s, \omega) = \sum_{\mathbf{h}} p(\mathbf{x} - \mathbf{h}, \mathbf{x}_s, \omega) r(\mathbf{x}, \mathbf{h}). \quad (2b)$$

In a more compact notation, not explicitly writing the dependencies on x , y and \mathbf{h} , and for a given depth level, z , equation 2b can be written as:

$$u^z(\omega) = \mathbf{P}^z(\omega) r^z, \quad (3)$$

where \mathbf{P}^z is a convolutional matrix. If $r = r(\mathbf{x}, h_x)$, for the case of 5 x positions and 3 subsurface offsets and subsurface-offset interval equals to the CMP interval, equation 3 can be explicitly written as:

$$\begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \\ u_6 \\ u_7 \end{bmatrix} = \begin{bmatrix} 0 & p_1 & 0 & p_3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & p_2 & 0 & p_4 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & p_1 & 0 & p_3 & 0 & p_5 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & p_2 & 0 & p_4 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & p_3 & 0 & p_5 \end{bmatrix} \begin{bmatrix} r_{1,1} \\ r_{1,2} \\ r_{1,3} \\ r_{2,1} \\ r_{2,2} \\ r_{2,3} \\ r_{3,1} \\ r_{3,2} \\ r_{3,3} \\ r_{4,1} \\ r_{4,2} \\ r_{4,3} \\ r_{5,1} \\ r_{5,2} \\ r_{5,3} \end{bmatrix} \quad (4)$$

where the subscripts of u and p represent x positions. The first and second subscripts of r represent x positions and subsurface offset, respectively.

The recursive upward propagation of $u^z(\omega)$ and recording at the surface are given by the following equations

$$\begin{cases} u^{z-1}(\omega) = T_{\uparrow}^z(\omega, s)P^z(\omega)r^z \\ d(\omega) = u^1(\omega) \end{cases} \quad (5)$$

where T_{\uparrow}^z is the upward continuation operator, which is function of the slowness, s .

bla, bla ... The matrix representation of equation 5 is

$$\begin{aligned} \underline{\mathbf{u}} &= \mathbf{T}_{\uparrow} \mathbf{P} \mathbf{r} \\ \mathbf{d} &= \mathbf{E} \underline{\mathbf{u}} \end{aligned} \quad (6)$$

Weighted least-squares data fitting

The optimum reflectivity, \mathbf{r} , minimizes the objective function

$$J(\mathbf{r}, \underline{\mathbf{u}}) = h(\mathbf{r}, \underline{\mathbf{u}}) = \frac{1}{2} \|\mathbf{W}(\mathbf{d} - \mathbf{d}_{\text{obs}})\|^2. \quad (7)$$

$$(8)$$

The forward equation reads:

$$F(\mathbf{r}, \underline{\mathbf{u}}) = \underline{\mathbf{u}} - \mathbf{T}_{\uparrow} \mathbf{P} \mathbf{r} = 0. \quad (9)$$

- Build the augmented functional

$$\begin{aligned} \mathcal{L}(\underline{\lambda}, \underline{\mathbf{u}}, \mathbf{r}) &= h(\mathbf{r}, \underline{\mathbf{u}}) - \langle \underline{\lambda}, F(\mathbf{r}, \underline{\mathbf{u}}) \rangle \\ \mathcal{L}(\underline{\lambda}, \underline{\mathbf{u}}, \mathbf{r}) &= \frac{1}{2} \|\mathbf{W}(\mathbf{d} - \mathbf{d}_{\text{obs}})\|^2 - \langle \underline{\lambda}, \underline{\mathbf{u}} - \mathbf{T}_{\uparrow} \mathbf{P} \mathbf{r} \rangle. \end{aligned} \quad (10)$$

- Define the adjoint state equations

$$\frac{\partial \mathcal{L}(\underline{\lambda}, \underline{\mathbf{u}}, \mathbf{r})}{\partial \underline{\mathbf{u}}} = \mathbf{E}^T \mathbf{W}^2 (\mathbf{d} - \mathbf{d}_{\text{obs}}) - \lambda = 0, \quad (11)$$

which gives

$$\lambda = \mathbf{E}^T \mathbf{W}^2 (\mathbf{d} - \mathbf{d}_{\text{obs}}). \quad (12)$$

- Compute the gradient with respect to \mathbf{r}

$$\frac{\partial \mathcal{L}(\underline{\lambda}, \underline{\mathbf{u}}, \mathbf{r})}{\partial \mathbf{r}} = \frac{\partial J}{\partial \mathbf{r}} = \lambda^* \mathbf{T}_{\uparrow} \mathbf{P} \quad (13)$$

and

$$\nabla J = \mathbf{P}^* \mathbf{T}_{\downarrow} \lambda, \quad (14)$$

that corresponds to the downward propagation of the residuals and cross-correlation imaging condition of the downward propagated residuals with the source wavefield.